#### Ring patterns in patrticle aggregation models



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### Introduction

We consider a simple model of particle interaction in 2D

$$\frac{dx_j}{dt} = \frac{1}{N} \sum_{\substack{k=1...N\\k \neq j}} F\left(|x_k - x_j|\right) \frac{x_k - x_j}{|x_k - x_j|}, \ \ j = 1 \dots N$$
(1)

- Models insect aggregation [Edelstein-Keshet et al, 1998] such as locust swarms [Topaz et al, 2008]; robotic motion [Gazi, Passino, 2004].
- Interaction force F(r) is of attractive-repelling type: the insects repel each other if they are too close, but attract each-other at a distance.
- Mathematically F(r) is positive for small r, but negative for large r.



• Commonly, a *Morse interaction force* is used:

$$F(r) = \exp(-r) - F \exp(-r/L); \quad F < 1, L > 1$$
 (2)

## **Boundedness**, h-stability

- For a fixed N, any initial configuration converges to a bounded steady state [GP 2004]
- In the limit  $N \to \infty$ , two possibilities exist: either the particle cloud size grows with N [h-stable case] or its is bounded independent of N [catastrophic regime]. [Ruelle, 1969]
  - H-stable regime: the steady state resembles a hexagonal lattice [Topaz et al, 2006], its diameter is of  $O\left(\sqrt{N}\right)$
  - Catastrophic regime: doubling N doubles the density but size and shape is independent of  $N \to \infty.$
- Here, we want to take  $N \to \infty$ , so we are interested in a catastrophic case.
- For Morse interaction force  $F(r) = \exp(-r) F \exp(-r/L)$  :
  - In 1D, catastrophic regime if  $FL^2 > 1$ , else h-stable.
  - In 2D, catastrophic regime if  $FL^3 > 1$ , else h-stable.

### **Example of h-stable vs. catastrophic**



Tanh-type force:  $F(r) = \tanh((1-r)a) + b$ 



### **Ring-type steady state**

- Seek steady state of the form  $x_j = r \left( \cos \left( 2\pi j/N \right), \sin \left( 2\pi j/N \right) \right), \ j = 1 \dots N.$
- $\bullet$  In the limit  $N \to \infty$  the radius of the ring must be the root of

$$I(r) := \int_0^{\frac{\pi}{2}} F(2r\sin\theta)\sin\theta d\theta = 0.$$
 (3)

- For Morse force  $F(r) = \exp(-r) F \exp(-r/L)$ , such root exists whenever  $FL^2 > 1$  [coincides with 1D catastrophic regime]
- For general repulsive-attractive force F(r), a ring steady state exists if  $F(r) \le C < 0$  for all large r.
- Even if the ring steady-state exists, the time-dependent problem can be ill-posed!

## **Continuum limit for curve solutions**

 $\bullet$  If particles concentrate on a curve, in the limit  $N \to \infty$  we obtain

$$\rho_t = \rho \frac{\langle z_\alpha, z_{\alpha t} \rangle}{|z_\alpha|^2}; \quad z_t = K * \rho$$
(4)

where  $z\left( lpha;t
ight)$  is a parametrization of the solution curve;  $ho\left( lpha;t
ight)$  is its density and

$$K * \rho = \int F\left(|z(\alpha') - z(\alpha)|\right) \frac{z(\alpha') - z(\alpha)}{|z(\alpha') - z(\alpha)|} \rho(\alpha', t) dS(\alpha').$$
(5)

- Depending on F(r) and initial conditions, the curve evolution may be *ill-defined!* 
  - For example a circle can degenerate into an annulus, gaining a dimension.
- We used a Lagrange particle-based numerical method to resolve (4).
  - Agrees with direct simulation of the ODE system (1):



# Local stability of a ring

- Linearize:  $z(\alpha, t) = r \exp(i\alpha) + \exp(\lambda t) \phi(\alpha), \ \phi \ll 1.$
- Ring is stable of  $\operatorname{Re}(\lambda) \leq 0$  for all pair  $(\lambda, \phi)$ . There are three zero eigenvalues corresponding to rotation and translation invariance; all other eigenvalues come in pairs due to rotational invariance.
- $\lambda$  is the eigenvalue of

$$M(m) := \begin{bmatrix} I_1(m) & I_2(m) \\ I_2(m) & I_1(-m) \end{bmatrix}; \quad m = 2, 3, \dots$$
(6)

$$I_1(m) = \frac{2}{\pi} \int_0^{\frac{\pi}{2}} \left[ \frac{F(2r\sin\theta)}{2r\sin\theta} + F'(2r\sin\theta) \right] \sin^2\left((m+1)\theta\right) d\theta;$$
(7a)

$$I_2(m) = \frac{2}{\pi} \int_0^{\frac{\pi}{2}} \left[ \frac{F(2r\sin\theta)}{2r\sin\theta} - F'(2r\sin\theta) \right] \left[ \sin^2\left(m\theta\right) - \sin^2(\theta) \right] d\theta.$$
 (7b)

• Eigenfunction is a pure fourier mode when projected to the curvilinear coordinates of the circle.



### Quadratic force $F(r) = r - r^2$

• Computing explicitly,

$$\operatorname{tr} M(m) = -\frac{\left(4m^4 - m^2 - 9\right)}{\left(4m^2 - 1\right)\left(4m^2 - 9\right)} < 0, \quad m = 2, 3, \dots$$
$$\det M(m) = \frac{3m^2(2m^2 + 1)}{\left(4m^2 - 9\right)\left(4m^2 - 1\right)^2} > 0, \quad m = 2, 3, \dots$$

- Conclusion: ring pattern corresponding to  $F(r) = r r^2$  is locally stable
- For large m, the two eigenvalues are  $\lambda \sim -\frac{1}{4}$  and  $\lambda \sim -\frac{3}{8m^2} \to 0$  as  $m \to \infty$ . The presence of arbitrary small eigenvalues implies the existence of very slow dynamics near the ring equilibrium.



### **General power force**

 $F(r) = r^p - r^q, \ 0$ 

- The mode  $m = \infty$  is stable if and only if pq > 1 and p < 1.
- Stability of other modes can be expressed in terms of Gamma functions.
- The dominant unstable mode corresponds to m = 3; the boundary is given by  $0 = 723 - 594(p+q) - 27(p^2 + q^2) - 431pq + 106(pq^2 + p^2q) + 19(p^3q + pq^3) + 10(p^3q^2 + p^2q^3) + 6(p^3 + q^3) + p^3q^3;$
- Boundaries for  $m = 4, 5, \ldots$  are similarly expressed in terms of higher order polynomials in p, q.



## (In)stability of $m \gg 1$ modes

- If  $\lambda(m) > 0$  for all sufficiently large m, then we call the ring solution **ill-posed**. Otherwise we call it **well-posed**.
- For ill-posed problems, the ring can degenerate into either an annulus (eg.  $F(x) = 0.5 + x x^2$ ) or discrete set of points (eg  $F(x) = x^{1.3} x^2$ )
- , if F(r) is  $C^4$  on [0, 2r], then the necessary and sufficient conditions for well-posedness of a ring are:

$$F(0) = 0, \quad F''(0) < 0 \text{ and}$$
 (8)

$$\int_0^{\pi/2} \left( \frac{F(2r\sin\theta)}{2r\sin\theta} - F'(2r\sin\theta) \right) d\theta < 0.$$
(9)

• Ring solution for the morse force  $F(r) = \exp(-r) - F \exp(-r/L)$  is always ill-posed.

### **Under construction...**

- "Sphere patterns" in 3D and their stability
- What about global stability of rings?
- Forces with sharp transition can produce exotic patterns; examples:
  - Flower:  $F(x) = \max(\min(1.6,(1-x)*4),-0.1)$
  - Exotic fish:  $F(x) = \max(\min(1.6,(1-x)*6),-0.3)$
  - Fuzzball:  $F(x) = \max(\min(1.6,(1-x)*10),-0.05)$