# The Stability and Dynamics of a Spike in the One-Dimensional Keller-Segel model 

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#### Abstract

In the limit of a large mass $M \gg 1$, and on a finite interval of length $2 L$, an equilibrium spike solution to the classical Keller-Segel chemotaxis model with a linear chemotactic function is constructed asymptotically. By calculating an asymptotic formula for the translational eigenvalue for $M \gg 1$, it is shown that the equilibrium spike solution is unstable to translations of the spike profile. If in addition $L \gg 1$, the equilibrium spike is shown to be metastable as a result of an asymptotically exponentially small eigenvalue. For $M \gg 1$ and $L \gg 1$, an asymptotic ODE for the metastable spike motion is derived that shows that the spike drifts exponentially slowly towards one of the boundaries of the domain. For a certain reduced Keller-Segel model, corresponding to a domain of small length, a solution with a spike at each of the two boundaries is constructed. This solution is found to be metastable, and it is shown that there is an exponentially slow exchange of mass between the two spikes that occurs over very long time scales. For arbitrary initial conditions, energy methods are used to show the global existence of solutions. The relationship between this reduced Keller-Segel model and a Burgers-type equation modeling the upward propagation of a flame-front in a finite channel is emphasized. Full numerical computations are used to confirm the asymptotic results.


## 1 Introduction

The Keller-Segel model was first introduced in [8] to describe the process of cellular aggregation due to chemotaxis. This model is a PDE system of the

$$
\begin{equation*}
u_{t}=\nabla \cdot(D \nabla u-u \nabla \Phi(v)), \quad v_{t}=\kappa \Delta v-\gamma v+\alpha u, \tag{1.1}
\end{equation*}
$$

in a domain $\Omega$ with Neumann boundary conditions for $v$ and $u$ on the boundary $\partial \Omega$ of $\Omega$. The function $\Phi(v)$ is called the chemotactic function. We will assume a linear such function so that $\Phi(v)=\beta v$. Here $D, \beta, \kappa, \gamma$, and $\alpha$, are all positive constants. In this paper we will analyze a singularly perturbed limit of (1.1) in a one-dimensional spatial domain. In dimensionless variables the system (1.1) can be written as (see Appendix A)

$$
\begin{equation*}
u_{t}=u_{x x}-\left(u v_{x}\right)_{x}, \quad \tau v_{t}=v_{x x}-v+u, \quad-L<x<L, \quad t>0 \tag{1.2a}
\end{equation*}
$$

The three parameters are the domain half-length $L$, the time-constant $\tau$, and the total mass $M$ defined by

$$
\begin{equation*}
M=\int_{-L}^{L} u d x \tag{1.2b}
\end{equation*}
$$

which is preserved in time.
There is large body of literature dedicated to (1.2) and its variants in one, two, and higher dimensions. See [6] for an excellent overview. In particular, the two-dimensional version of (1.2) can exhibit a chemotactic collapse phenomenon whereby the solution develops a singularity corresponding to a single point blowup at certain points of the domain in finite time. This collapse process, together with either formal asymptotic or rigorous constructions of the local blowup profile, has been studied by many authors (see $[\mathbf{3}],[\mathbf{4}],[\mathbf{7}],[\mathbf{9}]$, and many references in $[\mathbf{6}]$ ). A certain regularization of the Keller-Segel model, which appears to prohibit blow-up and leads to localized islands of high concentration, was studied in [15] and [16].

In contrast, for the one-dimensional Keller-Segel model (1.2), it has been shown in $[\mathbf{9}],[\mathbf{1 1}]$ and $[\mathbf{5}]$ that the solution to (1.2) exists globally for all time. In [5] a steady-state solution that consists of a spike at the boundary was also constructed asymptotically. Moreover, numerical experiments in [5] indicate that if an initial condition consists of a spike at some point in the interior of the domain then it will drift towards the boundary.

The first goal of this paper is to study the stability and dynamics of an interior spike in the asymptotic limit of a large mass $M \gg 1$. In this limit, a spike with spatial support of $O(1 / M)$ can be constructed asymptotically, as was done in [5]. For the equilibrium problem, the location $x_{0}$ of the center of the spike is at the center of the domain so that $x_{0}=0$. We then study the translational stability of the equilibrium solution by deriving an asymptotic formula for the principal eigenvalue of the linearization. We show that this eigenvalue is positive, and consequently the equilibrium spike is unstable to translations. This result for the eigenvalue supports numerical observations, such as those made in $\S 5$ of [5], that a spike that is initially centered near the midpoint of a one-dimensional domain will drift towards the boundary of that domain.

Furthermore, in the dual asymptotic limit of a large mass $M \gg 1$ together with a large domain $L \gg 1$, we show that this translational eigenvalue is positive, but is asymptotically exponentially small. This suggests that a quasi-equilibrium spike solution exhibits metastable behaviour in this limit. We characterize this metastability for $M \gg 1$ and $L \gg 1$ by deriving the following asymptotic ODE for the spike location $x_{0}$ associated with a quasi-equilibrium solution of (1.2),

$$
\begin{equation*}
x_{0}^{\prime}(t) \sim \exp (-2 L)\left[\frac{\tau}{4}+\frac{1}{M}\right]^{-1} \sinh \left(2 x_{0}\right) \tag{1.3}
\end{equation*}
$$

This result shows that the spike drifts towards one of the boundaries of the domain with an asymptotically exponentially small speed. The analysis of metastability for (1.2) is in the same spirit as previous metastability analyzes for other problems (see [17] for a survey), but is rather more intricate owing to the different spatial scales of $v$ and $u$. More specifically, since $u$ decays rapidly away from a spike for $M \gg 1$, whereas $v$ has a global variation across the domain $[-L, L]$, a straightforward application of a limiting solvability condition, such as was used for related problems in $[\mathbf{1 7}]$, cannot be used here to derive the asymptotic speed of the spike.

The metastable behaviour of localized structures has recently been analyzed for several variants of the KellerSegel model (1.1). In [12], the effect of volume-filling was analyzed in one spatial dimension whereby the coefficient of the chemotaxis term vanishes at a sufficiently high population density for $u$. With this model, the chemotaxis
term $\left(u v_{x}\right)_{x}$ in (1.2) is replaced by $\left(u(1-u) v_{x}\right)_{x}$. In a certain asymptotic limit, this volume-filling Keller-Segel model, which has localized solutions for $u$ in the form of front-back plateau solutions, was shown formally in [12] to exhibit metastable behaviour. In [13] the Keller-Segel model (1.1), under a logarithmic sensitivity function $\Phi(v)=\log \left(v^{p}\right)$, was modified to include a finite rate of increase of $v$ for $u \gg 1$. In a certain asymptotic limit, the resulting model exhibits metastable spike behaviour in both one and two spatial dimensions.

The second goal of this paper is to study the stability of an equilibrium solution, having a boundary spike at each endpoint, of the Keller-Segel model (1.2) in the limit $L \ll 1$ and $M L \gg 1$. We find that this two boundary-spike solution is marginally unstable, and a certain exponentially small eigenvalue is shown to initiate a metastable competition instability whereby the mass in the two boundary spikes is exchanged exponentially slowly in time until only one of the boundary spikes remain. The study of this phenomena is based on the analysis of a certain reduced Keller-Segel model, which is obtained by taking the limit $L \ll 1$ with $M L \gg 1$ in (1.2). The resulting limiting model was first studied in [7] where a certain non-local transformation was used to prove the existence of blowup solutions in two spatial dimensions from a comparison principle. For the corresponding one-dimensional problem we use an analog of this non-local transformation to asymptotically reduce the model (1.2) for $\varepsilon \equiv 2 /(M L) \ll 1$ to

$$
\begin{equation*}
u_{t}=\varepsilon u_{x x}-\left(u_{x}+1\right) v_{x x}, \quad \tau v_{t}=v_{x x}+u, \quad 0<x<2, \quad t>0 ; \quad u=v=0, \quad \text { at } \quad x=0,2 . \tag{1.4}
\end{equation*}
$$

We remark that the variables $u, v$, and $\tau$, in (1.4) are not the same as in (1.2) (see $\S 3$ ). For the case $\tau=0$, (1.2) yields a single equation for $u$. The resulting equation is of Burgers' type and, rather curiously, also arises in the analysis of $[\mathbf{1}],[\mathbf{2}],[\mathbf{1 4}]$, and $[\mathbf{1 0}]$, for the upward propagation of a flame-front in a vertical channel. In our context, an asymptotic solution of (1.4) for $\varepsilon \ll 1$ with boundary layers at both endpoints corresponds to the two boundary-spike solution for the Keller-Segel model (1.2) when $L \ll 1$ and $M L \gg 1$. For this class of solutions, we extend the metastability analysis of [14] and [10] to the case of the system (1.4) where $\tau>0$. Our analysis shows that a two boundary-layer solution to (1.4) is unstable due to the presence of an exponentially small positive eigenvalue. This eigenvalue can be interpreted as the initial instability mechanism for the slow mass exchange between two boundary spikes of the Keller-Segel model (1.2) for $L \ll 1$ with $M L \gg 1$.

The final goal of this paper is to give a rigorous proof of the global existence of solutions to (1.4) using energy methods. This analysis complements the analysis of [5] and [9] for the global existence of solutions to the full Keller-Segel model (1.2) in one spatial dimension.

The outline of the paper is as follows. In $\S 2$ we construct an equilibrium and a quasi-equilibrium spike solution to (1.2) in limit $M \gg 1$ with $M L \gg 1$. The result is summarized in the (formal) Proposition 1 . In this limit, an asymptotic formula for the translational eigenvalue of the equilibrium solution is derived in $\S 2$ and summarized in Proposition 2. For $L \gg 1$, this eigenvalue is positive but exponentially small. In Proposition 3 of $\S 2.3$ we formally characterize the metastable dynamics of a quasi-equilibrium spike solution by deriving an asymptotic formula for the speed of the spike when $M \gg 1$ and $L \gg 1$. Numerical results are given to confirm both the eigenvalue estimates and the slow spike motion. In $\S 3$ we study the metastability of boundary-layer solutions for
the reduced Keller-Segel model (1.4). In $\S 4$ we prove the global existence of smooth solutions to (1.4). Finally, in $\S 5$ we conclude with a brief discussion, and we list a few open problems.

## 2 Analysis of the Motion of a Spike Solution

In this section we consider a single interior spike solution to (1.2). In $\S 2.1$ we begin by formally deriving the asymptotic representation of the spike profile for a quasi-equilibrium spike solution. We then determine the spike location for a true equilibrium solution. The asymptotic result for the quasi-equilibrium solution is given in Proposition 1. For the true equilibrium solution, in Proposition 2 we formally derive an asymptotic formula for the eigenvalue corresponding to an odd eigenfunction. For a large domain length $L$, this is the eigenvalue associated with a near translation invariance. Since this eigenvalue is positive, the interior equilibrium spike solution is unstable. Finally, in Proposition 3 of $\S 2.3$ we derive an equation of motion for the center of the spike in the special case where the domain length $L$ is asymptotically large.

### 2.1 The Quasi-Equilibrium Spike Solution

We now summarize the main result of this section in the following formal statement:

Proposition 1 Consider a one-spike quasi-equilibrium solution of (1.2) with spike location at $x_{0} \in(-L, L)$. The spike location corresponds to the maximum value of $u$ in $(-L, L)$. Then, for $M \gg 1$ and $M L \gg 1$, the profile for $u$ has the asymptotic form

$$
\begin{equation*}
u \sim \frac{M^{2}}{8} \operatorname{sech}^{2}\left(\frac{M\left(x-x_{0}\right)}{4}\right)+M U_{1}+\cdots \tag{2.1}
\end{equation*}
$$

For $x-x_{0} \leq O\left(\frac{1}{M}\right)$, the corresponding inner solution for $v$ is

$$
\begin{equation*}
v \sim M G\left(x_{0}, x_{0}\right)-\ln \left[4 \cosh ^{2}\left(\frac{M\left(x-x_{0}\right)}{4}\right)\right]+\frac{V_{1}}{M}+\cdots \tag{2.2}
\end{equation*}
$$

Alternatively, the outer approximation for $v$, valid for $x-x_{0} \gg O(1 / M)$, is

$$
\begin{equation*}
v \sim M G\left(x, x_{0}\right) \tag{2.3}
\end{equation*}
$$

Here $G\left(x, x_{0}\right)$ is the Green's function satisfying $G_{x x}-G=-\delta\left(x-x_{0}\right)$ with $G_{x}\left( \pm L, x_{0}\right)=0$, given explicitly by

$$
G\left(x, x_{0}\right)=\frac{1}{\sinh (2 L)} \begin{cases}\cosh \left(x_{0}+L\right) \cosh (x-L), & x_{0}<x<L  \tag{2.4}\\ \cosh (x+L) \cosh \left(x_{0}-L\right), & -L<x<x_{0}\end{cases}
$$

A leading-order composite expansion $v_{c}$ for $v$, which is uniformly valid on $-L \leq x \leq L$, is

$$
\begin{equation*}
v_{c} \sim-\ln \left[4 \cosh ^{2}\left(\frac{M\left(x-x_{0}\right)}{4}\right)\right]+M G\left(x, x_{0}\right)+\frac{M}{2}\left|x-x_{0}\right| \tag{2.5}
\end{equation*}
$$

Finally, the true equilibrium solution is obtained when the spike is centered at $x_{0}=0$.

We now derive this result. We assume that $u$ has a spike located at some point $x_{0} \in(-L, L)$. In the inner region, where $x-x_{0}=O(1 / M)$, we introduce the change of variables

$$
\begin{equation*}
y=M\left(x-x_{0}\right) \quad u=M^{2} U, \quad v=V \tag{2.6}
\end{equation*}
$$

Substituting (2.6) into the steady-state problem for (1.2) we obtain

$$
\begin{equation*}
U^{\prime \prime}-\left(U V^{\prime}\right)^{\prime}=0, \quad V^{\prime \prime}-\frac{V}{M^{2}}+U=0 \tag{2.7}
\end{equation*}
$$

Here the primes indicate derivatives with respect to $y$. We then expand

$$
\begin{equation*}
U=U_{0}+\frac{1}{M} U_{1}+\cdots, \quad V=M V_{c}+V_{0}+\frac{1}{M} V_{1}+\cdots \tag{2.8}
\end{equation*}
$$

where $V_{c}$ is a constant independent of $y$ to be found. Substituting (2.8) into (2.7), we obtain

$$
\begin{align*}
U_{0}^{\prime \prime}-\left(U_{0} V_{0}^{\prime}\right)^{\prime}=0, & V_{0}^{\prime \prime}+U_{0}=0  \tag{2.9a}\\
U_{1}^{\prime \prime}-\left(U_{0} V_{1}^{\prime}+V_{0}^{\prime} U_{1}\right)^{\prime}=0, & V_{1}^{\prime \prime}+U_{1}=V_{c} \tag{2.9b}
\end{align*}
$$

We assume that all of the mass is concentrated in the inner region and so $M=\int_{-L}^{L} u d x$ is transformed to $\int_{-\infty}^{\infty} U d y=1$. Therefore, we have $\int_{-\infty}^{\infty} U_{0} d y=1$ and $\int_{-\infty}^{\infty} U_{j} d y=0$ for $j \geq 1$.

We integrate the leading-order equation for $U_{0}$ in (2.9a) and we impose $U_{0} \rightarrow 0$ as $|y| \rightarrow \infty$. This yields

$$
\begin{equation*}
U_{0}^{\prime}=U_{0} V_{0}^{\prime} \tag{2.10}
\end{equation*}
$$

Therefore, since $\int_{-\infty}^{\infty} U_{0} d y=1$, we get

$$
\begin{equation*}
U_{0}=\frac{1}{I_{0}} e^{V_{0}}, \quad I_{0}=\int_{-\infty}^{\infty} e^{V_{0}} d y \tag{2.11}
\end{equation*}
$$

Then, from the equation (2.9 a) for $V_{0}$, we get

$$
\begin{equation*}
V_{0}^{\prime \prime}+\frac{1}{I_{0}} e^{V_{0}}=0, \quad V_{0}^{\prime}(0)=0 \tag{2.12}
\end{equation*}
$$

In terms of an undetermined constant $A$, the solution to (2.12) is

$$
\begin{equation*}
V_{0}(y)=-\ln \left[A \cosh ^{2}(B y)\right], \quad B=\left(2 A I_{0}\right)^{-1 / 2} \tag{2.13}
\end{equation*}
$$

Then, by using $I_{0}=\int_{-\infty}^{\infty} e^{V_{0}} d y$, we readily derive that $I_{0}=\frac{2}{A B}$. By combining this relation with (2.13), we get

$$
\begin{equation*}
B=\frac{1}{4}, \quad I_{0}=\frac{8}{A} . \tag{2.14}
\end{equation*}
$$

Therefore, at this stage of the analysis we have

$$
\begin{equation*}
V_{0}(y)=-\ln \left[A \cosh ^{2}\left(\frac{y}{4}\right)\right], \quad U_{0}(y)=\frac{1}{8} \operatorname{sech}^{2}\left(\frac{y}{4}\right) . \tag{2.15}
\end{equation*}
$$

The constants $A$, and $V_{c}$ in (2.8), will be found by matching $V_{0}$ to the outer solution for $v$.
Higher-order correction terms in the inner region can also be calculated. The solution to (2.9b) with $U_{1} \rightarrow 0$ as $|y| \rightarrow \infty$ and $\int_{-\infty}^{\infty} U_{1} d y=0$ is simply $U_{1}=U_{0} V_{1}-U_{0} \int_{-\infty}^{\infty} U_{0} V_{1} d y$. Therefore, we get

$$
\begin{equation*}
U_{1}=\frac{1}{8} \operatorname{sech}^{2}\left(\frac{y}{4}\right) V_{1}-\frac{1}{64} \operatorname{sech}^{2}\left(\frac{y}{4}\right) \int_{-\infty}^{\infty} \operatorname{sech}^{2}\left(\frac{\eta}{4}\right) V_{1} d \eta \tag{2.16}
\end{equation*}
$$

where $V_{1}$ is the solution to

$$
\begin{equation*}
V_{1}^{\prime \prime}+\frac{1}{8} \operatorname{sech}^{2}\left(\frac{y}{4}\right) V_{1}-\frac{1}{64} \operatorname{sech}^{2}\left(\frac{y}{4}\right) \int_{-\infty}^{\infty} \operatorname{sech}^{2}\left(\frac{\eta}{4}\right) V_{1} d \eta=V_{c} \tag{2.17}
\end{equation*}
$$

From our analysis of the inner solution, it is clear that $U_{0}$ decays exponentially to zero as $|y| \rightarrow \infty$ whereas $V_{0}$ is linear as $|y| \rightarrow \infty$. Hence, $U$ and $V$ are the fast and slow variables, respectively. Therefore, in the sense of distributions, we can replace the effect of $u$ in the outer region, where $x-x_{0} \gg O(1 / M)$, by

$$
\begin{equation*}
u \rightarrow\left(\int_{-1}^{1} u d x\right) \delta\left(x-x_{0}\right)=\frac{1}{M}\left(\int_{-\infty}^{\infty} M^{2}\left(U_{0}+\frac{1}{M} U_{1}+\cdots\right) d y\right) \delta\left(x-x_{0}\right)=M \delta\left(x-x_{0}\right) . \tag{2.18}
\end{equation*}
$$

In this way, we find that the outer solution for $v$ satisfies

$$
\begin{equation*}
v_{x x}-v=-M \delta\left(x-x_{0}\right), \quad v_{x}( \pm L)=0 \tag{2.19}
\end{equation*}
$$

In terms of the Green's function $G\left(x, x_{0}\right)$, given explicitly in (2.4), the solution to (2.19) is

$$
\begin{equation*}
v=M G\left(x, x_{0}\right) \tag{2.20}
\end{equation*}
$$

The matching condition for the inner and outer approximations for $v$ is that the far-field behaviour of $V$ as $y \rightarrow \pm \infty$ agrees asymptotically with the behaviour of $G\left(x, x_{0}\right)$ as $x \rightarrow x_{0}^{ \pm}$. Therefore, we must have

$$
\begin{equation*}
M V_{c}+V_{0}+\frac{1}{M} V_{1}+\cdots \sim M G\left(x_{0}, x_{0}\right)+G_{x}\left(x_{0}^{ \pm}, x_{0}\right) y+G_{x x}\left(x_{0}, x_{0}\right) \frac{y^{2}}{2 M}+\cdots \tag{2.21}
\end{equation*}
$$

Since $V_{0} \sim-\ln (A / 4) \mp y / 2$ as $y \rightarrow \pm \infty$, as obtained from (2.15), the matching condition (2.21) determines $V_{c}$ and $A$ as $V_{c}=G\left(x_{0}, x_{0}\right)$ and $A=4$. In addition, from this matching condition, we also obtain that the equilibrium location of the spike is the root of $G_{x}\left(x_{0}^{+}, x_{0}\right)=-G_{x}\left(x_{0}^{-}, x_{0}\right)$. A simple calculation using (2.4) shows that

$$
\begin{equation*}
G_{x}\left(x_{0}^{+}, x_{0}\right)=\frac{\cosh \left(x_{0}+L\right) \sinh \left(x_{0}-L\right)}{\sinh (2 L)} \quad G_{x}\left(x_{0}^{-}, x_{0}\right)=\frac{\cosh \left(x_{0}-L\right) \sinh \left(x_{0}+L\right)}{\sinh (2 L)} \tag{2.22}
\end{equation*}
$$

Therefore, for the true equilibrium solution we must have $x_{0}=0$.
As a remark, we notice that for $L \gg 1$, we have $G_{x}\left(x_{0}^{ \pm}, x_{0}\right)=\mp \frac{1}{2}+O\left(e^{-\gamma L}\right)$ for some $\gamma$ that depends on $x_{0}$. Therefore, for $L \gg 1$, it is the exponentially small terms in the equilibrium condition $G_{x}\left(x_{0}^{+}, x_{0}\right)=-G_{x}\left(x_{0}^{-}, x_{0}\right)$ that enforce $x_{0}=0$. This exponential ill-conditioning of the equilibrium problem for $L \gg 1$ suggests that the linearization of the true equilibrium solution will have an exponentially small eigenvalue in this limit. Finally, setting $x_{0}=0$ for the true equilibrium solution we calculate that

$$
\begin{equation*}
V_{c}=G(0,0)=\frac{1}{2} \operatorname{coth}(L), \quad G_{x x}(0,0)=\frac{1}{2} \operatorname{coth}(L) \tag{2.23}
\end{equation*}
$$

Therefore, for the true equilibrium solution, the matching condition (2.21) shows that the solution $V_{1}$ to (2.17) has the far-field behaviour $V_{1} \sim \operatorname{coth}(L) y^{2} / 4$ as $|y| \rightarrow \infty$. The solution to (2.17) can then be reduced to quadrature. This completes the formal derivation of Proposition 1.

For $M=100$ and $L=1$, in Fig. 1(a) and Fig. 1(b) we use the asymptotic result in Proposition 1 to plot $u$ and $v$, respectively, for $x_{0}=0$ and $x_{0}=1 / 2$. In plotting $v$ in Fig. 1(b) we used the composite expansion $v_{c}$ given in (2.5). The dashed curves in Fig. 1(b) correspond to the outer solution $v \sim M G\left(x, x_{0}\right)$. Notice that since the inner


Figure 1. The equilibrium and the quasi-equilibrium solution for $M=100$ and $L=1$. Left figure: $u$ versus $x$ for $x_{0}=0$ (heavy solid curve) and for $x_{0}=1 / 2$ (solid curve). Right figure: the composite approximation $v_{c}$ versus $x$ for $x_{0}=0$ (heavy solid curve) and for $x_{0}=1 / 2$ (solid curve). The dashed curves in this figure are the outer solutions $v \sim M G\left(x, x_{0}\right)$.
approximation for $v$ serves only to round a corner layer in the derivative of $G\left(x, x_{0}\right)$ at $x=x_{0}$, the pointwise values for the outer solution for $v$ and the composite expansion agree rather well over the entire interval.

Finally, we make three remarks. Firstly, since the width of the domain is $O(L)$ while the width of the spike region is $O(1 / M)$, the formal analysis above is valid provided that $M L \gg 1$. Secondly, we note that it is possible to change the equilibrium spike location from $x_{0}=0$ to another value by adding a spatially variable term of the form $v_{x x}-a(x) v+u$, for some $a(x)>0$, in (1.2). For this modification, the leading-order inner solution for $u$ and $v$ are the same as when $a(x) \equiv 1$, except that now the equilibrium spike location would satisfy $G_{x}\left(x_{0}^{+}, x_{0}\right)=-G_{x}\left(x_{0}^{-}, x_{0}\right)$, where $G\left(x, x_{0}\right)$ is the Green's function for $G_{x x}-a(x) G=-\delta\left(x-x_{0}\right)$ with $G_{x}\left( \pm L, x_{0}\right)=0$. For this problem $x_{0} \neq 0$ in general. Finally, we remark that in $\S 5.1$ of [5] a spike profile is constructed asymptotically in a different asymptotic limit of the classical Keller-Segel model (1.2). However, formal asymptotic matching was not used in [5] to uniquely determine certain constants in the inner solution.

### 2.2 Eigenvalue problem

We now study the eigenvalue problem determining the stability of the equilibrium spike solution centered at $x_{0}=0$ constructed in $\S 2.1$. The equilibrium solution $u_{e}, v_{e}$ satisfies

$$
\begin{equation*}
u_{x x}-\left(u v_{x}\right)_{x}=0, \quad v_{x x}-v+u=0, \quad|x|<L ; \quad u_{x}( \pm L)=v_{x}( \pm L)=0 \tag{2.24}
\end{equation*}
$$

From (2.24), a key relation between $u$ and $v$ is that

$$
\begin{equation*}
u_{x}=u v_{x} \tag{2.25}
\end{equation*}
$$

We analyze the stability of this solution by setting

$$
\begin{equation*}
u=u_{e}+e^{\lambda t} \phi(x), \quad v=v_{e}+e^{\lambda t} \psi(x) \tag{2.26}
\end{equation*}
$$

By substituting (2.26) into (1.2a) we obtain the eigenvalue problem

$$
\begin{align*}
& \phi_{x x}-\left(\phi v_{x}+u \psi_{x}\right)_{x}=\lambda \phi ; \quad|x|<L ; \quad \phi_{x}( \pm L)=0,  \tag{2.27a}\\
& \psi_{x x}-(1+\tau \lambda) \psi=-\phi, \quad|x|<L ; \quad \psi_{x}( \pm L)=0 . \tag{2.27b}
\end{align*}
$$

In this section we formally derive an asymptotic formula for the eigenvalue $\lambda$ of translation in the limit $M \gg 1$ with $M L \gg 1$ and $\lambda \ll M^{2}$. This eigenvalue is found to be positive, and leads to the translational instability of the spike profile. Our main result is summarized as follows:

Proposition 2 Consider the one-spike equilibrium solution, centered at $x_{0}=0$, constructed in Proposition 1 in the limit $M \gg 1$ with $M L \gg 1$. In this limit, and assuming that $\lambda \ll M^{2}$, the translational eigenvalue $\lambda$ satisfies the transcendental relation

$$
\begin{equation*}
\lambda \sim \frac{M}{2} \operatorname{coth} L-\frac{M \mu}{2} \tanh (\mu L), \quad \mu \equiv \sqrt{1+\tau \lambda} \tag{2.28}
\end{equation*}
$$

For $\tau=0$, (2.28) reduces to

$$
\begin{equation*}
\lambda \sim \frac{M}{\sinh (2 L)} . \tag{2.29}
\end{equation*}
$$

In the limit $L \gg 1$, the solution to (2.28) satisfies

$$
\begin{equation*}
\lambda \sim \frac{2 M}{(M \tau / 4)+1} \exp (-2 L), \quad L \gg 1 \tag{2.30}
\end{equation*}
$$

Alternatively, in the limit $L \ll 1$, with $M L \gg 1$ and $\tau M L \ll 1$, we have that

$$
\begin{equation*}
\lambda \sim \frac{M}{2 L}\left[1+\frac{M L \tau}{2}\right]^{-1}, \quad L \ll 1, \quad M L \gg 1, \quad \tau M L \ll 1 \tag{2.31}
\end{equation*}
$$

We now derive (2.28). The limiting results (2.30) and (2.31) follow readily from (2.28). We begin by conveniently re-writing (2.27b) in operator form as

$$
\begin{equation*}
L \psi \equiv \psi_{x x}-\psi+u \psi=\tau \lambda \psi-\phi+u \psi \tag{2.32}
\end{equation*}
$$

By using $u_{x}=u v_{x}$ from (2.25), we obtain upon differentiating the equation for $v$ in (2.24) that $L v_{x}=0$. Then, by using Green's identity on (2.32), together with $v_{x}=0$ on $x= \pm L$, we get

$$
\begin{equation*}
\tau \lambda \int_{-L}^{L} v_{x} \psi d x=-\int_{-L}^{L}\left(u_{x} \psi-\phi v_{x}\right) d x-\left.\psi v_{x x}\right|_{-L} ^{L} . \tag{2.33}
\end{equation*}
$$

We now calculate each of the terms in (2.33). The analysis below shows that $\phi$ is localized near the spike, whereas $\psi$ has a significant variation in both the inner region near the spike and in the outer region away from the spike. Therefore, since $u$ is localized near the spike, the dominant contribution to the integral on the righthand side of (2.33) arises from the spike region where $x=O\left(M^{-1}\right)$. In contrast, the dominant contribution to the integral on the left-hand side of (2.33) arises from the outer region away from the spike core.

In the inner region where $x=O\left(M^{-1}\right)$, we introduce the inner variables $y, U, V, \Phi$, and $\Psi$, defined by

$$
\begin{equation*}
y=M x, \quad u(x)=M^{2} U(M x), \quad v(x)=V(M x), \quad \phi(x)=M^{2} \Phi(M x), \quad \psi(x)=\Psi(M x) . \tag{2.34}
\end{equation*}
$$

By substituting (2.34) into (2.27), we obtain that $\Phi(y)$ and $\Psi(y)$ satisfy

$$
\begin{equation*}
\Phi^{\prime \prime}-\left(\Phi V^{\prime}+U \Psi^{\prime}\right)^{\prime}=\frac{\lambda}{M^{2}} \Phi, \quad \Psi^{\prime \prime}-\frac{\Psi}{M^{2}}+\Phi=\frac{\tau \lambda}{M^{2}} \Psi . \tag{2.35}
\end{equation*}
$$

Here the primes indicate derivatives with respect to $y$. We assume that $\lambda / M^{2} \ll 1$, and we expand

$$
\begin{equation*}
\Phi=\Phi_{0}+\frac{\lambda}{M^{2}} \Phi_{1}+\cdots, \quad \Psi=\Psi_{0}+\frac{\lambda}{M^{2}} \Psi_{1}+\cdots \tag{2.36}
\end{equation*}
$$

By substituting (2.36) into (2.35), we obtain

$$
\begin{gather*}
\Phi_{0}^{\prime \prime}-\left(\Phi_{0} V^{\prime}+U \Psi_{0}^{\prime}\right)^{\prime}=0, \quad \Psi_{0}^{\prime \prime}-\frac{\Psi_{0}}{M^{2}}+\Phi_{0}=0,  \tag{2.37a}\\
\Phi_{1}^{\prime \prime}-\left(\Phi_{1} V^{\prime}+U \Psi_{1}^{\prime}\right)^{\prime}=\Phi_{0}, \quad \Psi_{1}^{\prime \prime}-\frac{\Psi_{1}}{M^{2}}+\Phi_{1}=\tau \Psi_{0} \tag{2.37b}
\end{gather*}
$$

Here $U(y)$ and $V(y)$ satisfy (2.7).
We integrate $(2.37 a)$ for $\Phi_{0}$ and impose $\Phi_{0}^{\prime}( \pm \infty)=\Phi_{0}( \pm \infty)=0$. Then, upon using $V^{\prime}=U^{\prime} / U$, we get

$$
\begin{equation*}
\Phi_{0}^{\prime}-\frac{U^{\prime}}{U} \Phi_{0}=U \Psi_{0}^{\prime} \tag{2.38}
\end{equation*}
$$

The solution to (2.38) is

$$
\begin{equation*}
\Phi_{0}=U \Psi_{0} \tag{2.39}
\end{equation*}
$$

Therefore, from (2.37a), $\Psi_{0}$ satisfies

$$
\begin{equation*}
\Psi_{0}^{\prime \prime}-\frac{\Psi_{0}}{M^{2}}+U \Psi_{0}=0 \tag{2.40}
\end{equation*}
$$

Since $U^{\prime}=U V^{\prime}$, we obtain from differentiating (2.7) for $V$ that $\Psi_{0}=V^{\prime}$. Hence, from (2.39), we get

$$
\begin{equation*}
\Phi_{0}=U V^{\prime}=U^{\prime}, \quad \Psi_{0}=V^{\prime} \tag{2.41}
\end{equation*}
$$

Next, we integrate $(2.37 b)$ for $\Phi_{1}$ and impose $\Phi_{1}^{\prime}( \pm \infty)=\Phi_{1}( \pm \infty)=0$. By using $V^{\prime}=U^{\prime} / U$, we get $\left(\Phi_{1} / U\right)^{\prime}=$ $\Psi_{1}^{\prime}+1$. Upon integrating this expression and substituting the result into $(2.37 b)$ for $\Psi_{1}$, we get

$$
\begin{equation*}
\Phi_{1}=U\left(\Psi_{1}+y\right) \tag{2.42}
\end{equation*}
$$

where $\Psi_{1}$ satisfies

$$
\begin{equation*}
\Psi_{1}^{\prime \prime}-\frac{\Psi_{1}}{M^{2}}+U \Psi_{1}=\tau V^{\prime}-U y \tag{2.43}
\end{equation*}
$$

Then, we substitute (2.41) and (2.42) into (2.36), to conclude that

$$
\begin{equation*}
\phi=M^{2} \Phi, \quad \Phi=U \Psi+\frac{\lambda}{M^{2}} U y+\cdots=U^{\prime}+\frac{\lambda}{M^{2}} U\left(\Psi_{1}+y\right)+\cdots . \tag{2.44}
\end{equation*}
$$

Next, we substitute the inner variables (2.34) into the integral on the right-hand side of (2.33). Then, using
(2.44), $U^{\prime}=U V^{\prime}$, and upon integrating by parts, we obtain

$$
\begin{align*}
J \equiv \int_{-L}^{L}\left(u_{x} \psi-\phi v_{x}\right) d x & =M^{2} \int_{-M L}^{M L}\left(U^{\prime} \Psi-\Phi V^{\prime}\right) d y \\
& \sim M^{2} \int_{-M L}^{M L}\left(U^{\prime} \Psi-U V^{\prime} \Psi-\frac{\lambda}{M^{2}} U V^{\prime} y\right) d y \\
& \sim-\lambda \int_{-M L}^{M L} y U^{\prime} d y=-\lambda\left[\left.y U\right|_{-M L} ^{M L}-\int_{-M L}^{M L} U d y\right] . \tag{2.45}
\end{align*}
$$

Since $M L \gg 1$, and $U( \pm \infty)=0$ with $\int_{-\infty}^{\infty} U d y=1$ from $\S 2.1$, we obtain from (2.45) that

$$
\begin{equation*}
J \sim \lambda . \tag{2.46}
\end{equation*}
$$

By substituting (2.46) into (2.33), we get

$$
\begin{equation*}
\lambda(\tau I+1) \sim-\left.\psi v_{x x}\right|_{-L} ^{L}, \quad I \equiv \int_{-L}^{L} v_{x} \psi d x . \tag{2.47}
\end{equation*}
$$

In (2.47) we use the outer approximation for $v$, which satisfies (2.19) with $x_{0}=0$. Therefore, from (2.20) and (2.4), we obtain that $v_{x x}=v$ at $x= \pm L$ and

$$
v( \pm L) \sim \frac{M}{2 \sinh L}, \quad v_{x} \sim \frac{M}{2 \sinh L}\left\{\begin{array}{cc}
\sinh (x-L), \quad 0<x<L  \tag{2.48}\\
\sinh (x+L), \quad & -L<x<0
\end{array}\right.
$$

To calculate the outer solution for $\psi$, we must first represent $\phi$ in (2.32) in the sense of distributions. A simple calculation shows that for $M \rightarrow \infty$, a localized and odd function of the form $g(M x)$ can be represented as the dipole distribution $g(M x) \rightarrow-M^{-2}\left(\int_{-\infty}^{\infty} y g(y) d y\right) \delta^{\prime}(x)$. Therefore, from (2.44), we have

$$
\begin{equation*}
\phi(x)=M^{2} \Phi(M x) \quad \rightarrow \quad\left(-\int_{-\infty}^{\infty} y U^{\prime} d y-\frac{\lambda}{M^{2}} \int_{-\infty}^{\infty} y U\left(\Psi_{1}+y\right) d y\right) \delta^{\prime}(x) . \tag{2.49}
\end{equation*}
$$

Since $\lambda / M^{2} \ll 1$, we can neglect the second term in (2.49). Then, upon integrating the first term in (2.49) by parts, and using $\int_{-\infty}^{\infty} U d y=1$, we obtain that $\phi \rightarrow \delta^{\prime}(x)$. Therefore, from (2.32), the leading-order outer approximation for $\psi$ satisfies

$$
\begin{equation*}
\psi_{x x}-\mu^{2} \psi=-\delta^{\prime}(x), \quad|x|<L ; \quad \psi_{x}( \pm L)=0 ; \quad \mu \equiv \sqrt{1+\tau \lambda} \tag{2.50}
\end{equation*}
$$

The solution to (2.50) is readily calculated as

$$
\psi( \pm L) \sim \mp \frac{1}{2 \cosh (\mu L)}, \quad \psi(x) \sim-\frac{1}{2 \cosh (\mu L)}\left\{\begin{align*}
\cosh (\mu(x-L)), & 0<x<L  \tag{2.51}\\
-\cosh (\mu(x+L)), & -L<x<0
\end{align*}\right.
$$

Finally, we substitute (2.48) and (2.51) into (2.47). This yields that

$$
\begin{equation*}
\lambda(1+\tau I) \sim \frac{M}{2 \cosh (\mu L) \sinh (L)}, \tag{2.52}
\end{equation*}
$$

where the integral $I$ in (2.47) is given by

$$
\begin{equation*}
I=\frac{M}{2 \sinh L \cosh (\mu L)} \int_{0}^{L} \sinh z \cosh (\mu z) d z=\frac{M[\mu \sinh (\mu L) \sinh L-\cosh (\mu L) \cosh L+1]}{2\left(\mu^{2}-1\right) \sinh L \cosh (\mu L)}, \tag{2.53}
\end{equation*}
$$

Substituting (2.53), (2.48), and (2.51) into (2.47), and using $\mu^{2}-1=\tau \lambda$, we obtain (2.28). This completes the derivation of the formal Proposition 2.

We now show that $\lambda>0$ from (2.28). To do so, we write (2.28) in the form $F(\lambda)=0$, where $F(\lambda)$ is defined by

$$
\begin{equation*}
F(\lambda) \equiv \lambda+\frac{M \mu}{2} \tanh (\mu L)-\frac{M}{2} \operatorname{coth} L, \quad \mu \equiv \sqrt{1+\tau \lambda} \tag{2.54}
\end{equation*}
$$

For any $L>0$ and $M>0$, a simple calculation shows that $F(0)<0, F(\lambda) \rightarrow+\infty$ as $\lambda \rightarrow \infty$, and $F^{\prime}(\lambda)>0$. Therefore, for any $L>0$ and $M>0$, the eigenvalue of translation is unstable. For $M=100$, and for three values of $\tau$, In Fig. 2(a) we plot the numerical solution to (2.28) as a function of $L$. For $\tau=1$, in Fig. 2(b) we plot $\lambda$ versus $L$ for two values of $M$. It is easy to show from (2.28) that $\lambda$ is a decreasing function of $\tau$, a decreasing function of $L$, and an increasing function of $M$. In Table 1 we show a largely favorable comparison between the asymptotic result (2.28) for $\lambda$ and the corresponding full numerical result computed from (2.24) and (2.27). The rather poor agreement for the case $\tau \geq 1, L=0.5$, and $M=50$, is improved by increasing $M$ to concentrate the spike near $x=0$.

From (2.30) we note that the classical Keller-Segel model is exponentially ill-conditioned in the limit $L \gg 1$ and $M \gg 1$. Hence, we expect that the corresponding time-dependent problem will exhibit the phenomena of dynamic metastability in this limit. This is studied in $\S 2.3$. Although the eigenvalue estimate (2.28) was done only for the equilibrium solution where $x_{0}=0$, a similar analysis shows that the quasi-equilibrium solution with $x_{0} \neq 0$ is also exponentially ill-conditioned when $L \gg 1$ and $M \gg 1$.


Figure 2. Left figure: $\lambda$ versus $L$ computed numerically with $M=100$ from (2.28) (solid curves) for $\tau=0.5, \tau=1.0$, $\tau=3.0$, and $\tau=5.0$. At each fixed $L, \lambda$ increases as $\tau$ decreases, and hence the top curve is for $\tau=0.5$. Right figure: $\lambda$ versus $L$ computed with $\tau=1.0$ from (2.28) for $M=50$ (lower solid curve) and $M=400$ (upper solid curve). In these figures the dotted curves are the approximations to $\lambda$ given in (2.30), which are valid for $L \gg 1$.


Table 1. Comparison of the asymptotic solution for the translation eigenvalue $\lambda$ given in (2.28) with the corresponding full numerical result computed from (2.24) and (2.27).

### 2.3 Dynamics

In this section we derive an equation of motion for the center $x_{0}$ of the spike that is valid for $M \gg 1$ and for long domains where $L \gg 1$. In this limit, where the eigenvalue was found in $\S 2.2$ to be exponentially small, the spike motion is metastable and the spike is found to drift exponentially slowly towards one of the boundaries of the domain.

Proposition 3 Consider the one-spike quasi-equilibrium solution of Proposition 1 and suppose that $M \gg 1$ and $L \gg 1$. Let $x_{0}(t)$ be the location of the maximum height of the spike for $u$ at a given time $t$ with $\left|x_{0}\right|<L$. Then, $x_{0}$ satisfies the asymptotic ODE

$$
\begin{equation*}
x_{0}^{\prime}(t) \sim \exp (-2 L)\left[\frac{\tau}{4}+\frac{1}{M}\right]^{-1} \sinh \left(2 x_{0}\right) \tag{2.55}
\end{equation*}
$$

We now derive this result. As in the derivation of the quasi-equilibrium solution of $\S 2.1$, we introduce the following scalings

$$
\begin{equation*}
y=M\left(x-x_{0}(t)\right), \quad u=M^{2} U, \quad v=V \tag{2.56}
\end{equation*}
$$

where $U=U(y)$ and $V=V(y)$. We then define $\sigma$ by

$$
\begin{equation*}
\sigma \equiv x_{0}^{\prime}(t) \tag{2.57}
\end{equation*}
$$

Substituting (2.56) and (2.57) into (1.2), we readily derive that

$$
\begin{equation*}
U^{\prime \prime}-\left(U V^{\prime}\right)^{\prime}=-\frac{\sigma}{M} U^{\prime}, \quad V^{\prime \prime}-\frac{V}{M^{2}}+U=-\frac{\tau \sigma}{M} V^{\prime} \tag{2.58}
\end{equation*}
$$

Recall from the construction of the equilibrium solution in $\S 2.1$ that $U$ is localized near the spike, but that the solution to the leading order approximation for $V$, given by $V^{\prime \prime}+U=0$, does not decay as $y \rightarrow \pm \infty$. Therefore, we shall retain the term $\frac{1}{M^{2}} V$ in (2.58) to ensure that $V$ decays as $|y| \rightarrow \infty$ when $L \gg 1$. This allows us to impose a limiting solvability condition to determine the ODE for $x_{0}(t)$.

Since there is an asymptotically small eigenvalue when $L \ll 1$, we expect that the speed $\sigma$ of the spike is slow so that $\sigma \ll 1$. Therefore, we expand $U$ and $V$ in terms of $\sigma \ll 1$ as

$$
\begin{equation*}
U=U_{0}+\sigma U_{1}+\cdots, \quad V=V_{0}+\sigma V_{1}+\cdots \tag{2.59}
\end{equation*}
$$

Substituting (2.59) into (2.58) we obtain the following leading-order problem for $U_{0}$ and $V_{0}$

$$
\begin{equation*}
U_{0}^{\prime \prime}-\left(U_{0} V_{0}^{\prime}\right)^{\prime}=0, \quad V_{0}^{\prime \prime}-\frac{V_{0}}{M^{2}}+U_{0}=0 \tag{2.60}
\end{equation*}
$$

The system for $U_{1}$ and $V_{1}$ is

$$
\begin{align*}
U_{1}^{\prime \prime}-\left(U_{0} V_{1}^{\prime}+U_{1} V_{0}^{\prime}\right)^{\prime} & =-\frac{U_{0}^{\prime}}{M}  \tag{2.61a}\\
V_{1}^{\prime \prime}-\frac{V_{1}}{M^{2}}+U_{1} & =-\frac{\tau V_{0}^{\prime}}{M} \tag{2.61b}
\end{align*}
$$

By integrating the equation for $U_{0}$ we obtain $U_{0}^{\prime}=U_{0} V_{0}^{\prime}$. Then, we can integrate the equation for $U_{1}$ once to get

$$
\begin{equation*}
U_{1}^{\prime}-V_{0}^{\prime} U_{1}=U_{0}\left(V_{1}^{\prime}-\frac{1}{M}\right) \tag{2.62}
\end{equation*}
$$

By using $U_{0}^{\prime}=U_{0} V_{0}^{\prime}$, the solution to (2.62) is readily found to be

$$
\begin{equation*}
U_{1}=U_{0}\left(V_{1}-\frac{y}{M}\right) \tag{2.63}
\end{equation*}
$$

By substituting (2.63) into (2.61 b), the equation for $V_{1}$ becomes

$$
\begin{equation*}
L V_{1} \equiv V_{1}^{\prime \prime}+U_{0} V_{1}-\frac{V_{1}}{M^{2}}=\left(\frac{U_{0} y}{M}-\frac{\tau V_{0}^{\prime}}{M}\right) \tag{2.64}
\end{equation*}
$$

We shall consider (2.64) on the interval $y_{-}<y<y_{+}$, where $y_{-} \equiv-M\left(L+x_{0}\right)$ and $y_{+} \equiv M\left(L-x_{0}\right)$. This range corresponds to the entire domain $-L<x<L$.

Although the solution $V_{0}$ to (2.60) is exponentially small near $y=y_{ \pm}$when $L \gg 1$, we must include this exponentially small effect in order to derive an accurate ODE for the metastable dynamics. Similar weak boundary effects are essential for a metastability analysis of other problems (cf. [13], [14], [10], and [17]). Therefore, in terms of $V_{0}$ and $V_{1}$, the Neumann boundary condition $v_{x}( \pm L)=0$ is transformed to the following boundary
condition for (2.64):

$$
\begin{equation*}
V_{1}^{\prime}\left(y_{ \pm}\right)=-\frac{1}{\sigma} V_{0}^{\prime}\left(y_{ \pm}\right) \tag{2.65}
\end{equation*}
$$

Now as was shown in $\S 2.2$, the eigenvalue problem $L \Psi=\lambda \Psi$ with $\Psi^{\prime}=0$ at $y=y_{ \pm}$has an exponentially small eigenvalue when $L \gg 1$ and $x_{0}=0$. As remarked in $\S 2.2$ this is also true when $x_{0} \neq 0$. We then use Green's identity with $\Psi$ and $V_{1}$ on (2.64) and (2.65) to obtain that

$$
\begin{equation*}
\lambda \int_{y_{-}}^{y_{+}} \Psi v_{1} d y-\int_{y_{-}}^{y_{+}} \Psi\left(\frac{U_{0} y}{M}-\frac{\tau V_{0}^{\prime}}{M}\right) d y=\left.\frac{1}{\sigma} \Psi V_{0}^{\prime}\right|_{y_{-}} ^{y_{+}} \tag{2.66}
\end{equation*}
$$

From (2.60) it follows that $U_{0} \sim c e^{-|y| / 2}$ as $y \rightarrow \infty$. Therefore, in the outer region where $y \gg 1, V_{0}$ satisfies $V_{0}^{\prime \prime}-M^{-2} V_{0} \sim 0$, which yields $V_{0} \sim k e^{-|y| / M}$. To obtain the constant $k$ in this outer region, we must calculate the effect of $U_{0}$ in the equation for $V_{0}$ in (2.60) in the sense of distributions. We recall from $\S 2.1$ that $u \rightarrow M \delta(x)$ in the outer region. Therefore, $M^{2} U_{0} \rightarrow M \delta(x)=M \delta(y / M)=M^{2} \delta(y)$, which yields $U_{0} \rightarrow \delta(y)$. Thus, in the outer region, the equation for $V_{0}$ becomes $V_{0}^{\prime \prime}-\frac{V_{0}}{M^{2}} \sim-\delta(y)$. The solution is readily found to be

$$
\begin{equation*}
V_{0} \sim \frac{M}{2} e^{-|y| / M} \tag{2.67}
\end{equation*}
$$

As a remark, near $y=y_{ \pm}=O(M L)$, we have that $V_{0}$ is exponentially small when $L \gg 1$. Therefore, a boundary layer of exponentially small height is required in order for $V_{0}$ to satisfy the boundary conditions $V_{0}^{\prime}\left(y_{ \pm}\right)=0$ exactly. However, this calculation is not needed in our metastability analysis.

Next, we differentiate (2.60) for $V_{0}$ with respect to $y$, and use $U_{0}^{\prime}=U_{0} V_{0}^{\prime}$. By comparing the resulting equation with (2.64) we conclude that $L V_{0}^{\prime}=0$. Therefore, except in a thin boundary layer near the endpoints $y_{ \pm}$, we have $\Psi \sim V_{0}^{\prime}$. We use this result together with (2.67) to calculate the second term on the left-hand side of (2.66) as

$$
\begin{align*}
& \frac{1}{M} \int_{y_{-}}^{y_{+}} \tau \Psi V_{0}^{\prime} d y \sim \frac{\tau}{M} \int_{y_{-}}^{y_{+}}\left(V_{0}^{\prime}\right)^{2} d y \sim \frac{\tau}{4 M} \int_{-\infty}^{\infty} e^{-2|y| / M} d y=\frac{\tau}{4}  \tag{2.68a}\\
& \frac{1}{M} \int_{y_{-}}^{y_{+}} \Psi y U_{0} d y \sim \frac{1}{M} \int_{y_{-}}^{y_{+}} y V_{0}^{\prime} U_{0} d y \sim \frac{1}{M} \int_{-\infty}^{\infty} y U_{0}^{\prime} d y=-\frac{1}{M} \tag{2.68b}
\end{align*}
$$

In obtaining the last expression in $(2.68 b)$ we used $\int_{-\infty}^{\infty} U_{0} d y=1$ after integrating by parts. Upon substituting (2.68) into (2.66), we obtain

$$
\begin{equation*}
\lambda \sigma \int_{y_{-}}^{y_{+}} \Psi v_{1} d y+\left.\sigma\left(\frac{1}{M}+\frac{\tau}{4}\right) \sim \Psi V_{0}^{\prime}\right|_{y_{-}} ^{y_{+}} . \tag{2.69}
\end{equation*}
$$

Finally, we must calculate $\Psi\left(y_{ \pm}\right)$. Since $\Psi \sim V_{0}^{\prime}$ fails to satisfy the boundary condition $\Psi^{\prime}\left(y_{ \pm}\right)=0$ by exponentially small terms, we must add a boundary layer of exponentially small height year $y=y_{ \pm}$in order to ensure that $\Psi^{\prime}\left(y_{ \pm}\right)=0$. Near $y=y_{-}$, we have $\Psi^{\prime \prime}-\frac{1}{M^{2}} \Psi \sim 0$. The solution of this equation that satisfies the Neumann condition is

$$
\begin{equation*}
\Psi \sim B\left(e^{-\left(y-y_{-}\right) / M}+e^{\left(y-y_{-}\right) / M}\right) \tag{2.70}
\end{equation*}
$$

for some constant $B$. To determine $B$ we must have that the growing exponential term in (2.70) agree with $\Psi \sim V_{0}^{\prime} \sim \frac{1}{2} e^{y / M}$. This determines $B$ as $B=\frac{1}{2} e^{y_{-} / M}$. Therefore, we have $\Psi\left(y_{-}\right) \sim 2 B$. A similar boundary layer


Figure 3. Motion of the center of the spike with $M=100, L=3, \tau=1$. The dotted curve shows the position of the spike as obtained from the full numerical simulation of (1.2). The solid curve is the result obtained from the asymptotic ODE (2.72).
analysis determines $\Psi\left(y_{+}\right)$. In this way, we obtain for $L \gg 1$ that

$$
\begin{equation*}
\Psi\left(y_{-}\right) \sim e^{y_{-} / M} \ll 1, \quad y_{-} \equiv-M\left(L+x_{0}\right) ; \quad \Psi\left(y_{+}\right) \sim-e^{-y_{+} / M} \ll 1, \quad y_{+} \equiv M\left(L-x_{0}\right) . \tag{2.71}
\end{equation*}
$$

Finally, we use (2.71) and (2.67) to calculate the boundary contribution term in (2.69). Since $\lambda_{1}$ is exponentially small, the integral on the left-hand side of (2.69) is asymptotically smaller than the second term on the left-hand side of (2.69). In this way, we obtain that $\sigma=x_{0}^{\prime}$ satisfies the asymptotic ODE

$$
\begin{equation*}
\frac{d x_{0}}{d t} \sim F\left(x_{0}\right) \equiv e^{-2 L}\left[\frac{\tau}{4}+\frac{1}{M}\right]^{-1} \sinh \left(2 x_{0}\right) \tag{2.72}
\end{equation*}
$$

This completes the derivation of the formal Proposition 3.
From (2.72) we notice that the equilibrium $x_{0}=0$ is unstable but with an asymptotically exponentially small growth rate $F^{\prime}(0)$ given by

$$
\begin{equation*}
F^{\prime}(0)=2 e^{-2 L}\left[\frac{\tau}{4}+\frac{1}{M}\right]^{-1} \tag{2.73}
\end{equation*}
$$

This value is precisely the formula for the exponentially small eigenvalue of Proposition 2 when $L \gg 1$.
Finally, in Figure 3 we compare results from the ODE (2.72) with full numerical results for the spike motion computed from (1.2). The initial condition was a one-spike solution with the spike slightly offset from $x_{0}=0$. In the simulation we took $M=100, L=3$, and $\tau=1$. While the asymptotic ODE is theoretically valid only when $L \gg 1$, this figure shows that it gives a decent approximation to the full numerical result even for the moderate value of $L=3$.

## 3 Reduced Keller-Segel model

In this section we consider a reduced Keller-Segel model, which can be obtained by taking the limit $L \ll 1$, but with $M L \gg 1$, in (1.2). This regime was first considered in $[\mathbf{7}]$ in the context of the analysis of blowup solutions in two spatial dimensions. We now give the derivation of this reduced Keller-Segel model starting from (1.2). We first let $y=x / L$ to obtain

$$
\begin{equation*}
L^{2} u_{t}=u_{y y}-\left(u v_{y}\right)_{y}, \quad \tau v_{t}=\frac{1}{L^{2}} v_{y y}+u-v, \quad 0<y<2 ; \quad \frac{1}{2} \int_{0}^{2} u d y=\frac{M}{2 L} \tag{3.1}
\end{equation*}
$$

with $v_{y}=u_{y}=0$ at $y=0,2$. Let $v_{a}$ denote the average $v_{a}=\frac{1}{2} \int_{0}^{2} v d y$. Then, for $L \ll 1$, it follows from (3.1) that $\tau v_{a}^{\prime}=M /(2 L)-v_{a}$. Therefore, for $t \gg 1$, we have $v_{a} \rightarrow M /(2 L)$ as $t \rightarrow \infty$. This suggests that we make the change of variables

$$
\begin{equation*}
v=\frac{M}{2 L}\left(1+L^{2} \mathcal{V}\right), \quad u=\frac{M}{2 L} \mathcal{U}, \quad \tilde{t}=\frac{M}{2 L} t \tag{3.2}
\end{equation*}
$$

By substituting (3.2) into (3.1), we obtain that $\mathcal{U}$ and $\mathcal{V}$ satisfy

$$
\begin{equation*}
\mathcal{U}_{\tilde{t}}=\varepsilon \mathcal{U}_{y y}-\left(\mathcal{U} \mathcal{V}_{y}\right)_{y}, \quad \tilde{\tau} \mathcal{V}_{\tilde{t}}=\mathcal{V}_{y y}+\mathcal{U}-1+L^{2} \mathcal{V}, \quad 0<y<2 ; \quad \frac{1}{2} \int_{0}^{2} \mathcal{U} d y=1 \tag{3.3}
\end{equation*}
$$

with $\mathcal{U}_{y}=\mathcal{V}_{y}=0$ at $y=0,2$. Here $\varepsilon$ and $\tilde{\tau}$ are defined by

$$
\begin{equation*}
\varepsilon \equiv \frac{2}{M L} \ll 1, \quad \tilde{\tau}=\frac{\tau}{\varepsilon} . \tag{3.4}
\end{equation*}
$$

Since $L \ll 1$, we can neglect the term $L^{2} \mathcal{V}$ in (3.3). Finally, we introduce the new variables $\tilde{u}$ and $\tilde{v}$ by

$$
\begin{equation*}
\tilde{u}=\int_{0}^{y}(\mathcal{U}-1) d s, \quad \tilde{v}=\int_{0}^{y} \mathcal{V} d s \tag{3.5}
\end{equation*}
$$

In terms of these new variables in (3.5), and upon replacing $y$ by $x$ and dropping the tilde notation, we obtain that (3.3) transforms to (1.4).

### 3.1 Equilibrium Boundary-Layer Solutions of the Reduced Model

We now construct certain equilibrium boundary-layer solutions to the reduced Keller-Segel model (1.4),

$$
\begin{equation*}
\varepsilon u_{x x}-\left(u_{x}+1\right) v_{x x}=0, \quad v_{x x}+u=0 . \tag{3.6}
\end{equation*}
$$

For $\varepsilon \ll 1$, we first construct a solution to (3.6) on $[0,1]$ with $u=v=0$ at $x=0,1$ that has a boundary layer at $x=0$. More general solutions follow by using reflection symmetry. By combining (3.6) we obtain a single equation

$$
\begin{equation*}
\varepsilon u_{x x}+\left(u_{x}+1\right) u=0, \quad u(0)=u(1)=0 . \tag{3.7}
\end{equation*}
$$

In the outer region, away from the boundary layer at $x=0$, the following outer solution is an exact solution to (3.7):

$$
\begin{equation*}
u \sim 1-x, \quad x \gg O(\varepsilon) . \tag{3.8}
\end{equation*}
$$



Figure 4. The equilibrium solution to (3.7) on $[0,1]$ with a boundary layer at $x=0$. The values of $\varepsilon$ are as indicated. The solid and dashed curves are the full numerical and the asymptotic solution (3.14), respectively.

In the boundary layer near $x=0$, we re-scale $u$ and $x$ as

$$
\begin{equation*}
U(y)=u(\varepsilon y), \quad y=\varepsilon^{-1} x \tag{3.9}
\end{equation*}
$$

so that (3.7) becomes

$$
\begin{equation*}
U^{\prime \prime}+U^{\prime} U+\varepsilon U=0 \tag{3.10}
\end{equation*}
$$

Here the primes indicate derivatives with respect to $y$. We then expand $U$ as

$$
\begin{equation*}
U(y)=U_{0}(y)+\varepsilon U_{1}(y)+\ldots . \tag{3.11}
\end{equation*}
$$

Substituting (3.11) into (3.10), we obtain on $0<y<\infty$ that

$$
\begin{equation*}
U_{0}^{\prime \prime}+U_{0}^{\prime} U_{0}=0, \quad U_{0}(0)=0 ; \quad U_{1}^{\prime \prime}+U_{0}+\left(U_{1} U_{0}\right)^{\prime}=0, \quad U_{1}(0)=0 \tag{3.12}
\end{equation*}
$$

The solution $U_{0}$ to (3.12) is $U_{0}(y)=c \tanh (c y / 2)$, where the constant $c$ is determined by an asymptotic matching to the outer solution. This matching condition is that the outer solution $u \sim 1-x=1-\varepsilon y$ must agree with the far-field behaviour of $U_{0}+\varepsilon U_{1}+\cdots$ as $y \rightarrow \infty$. This yields $U_{0}(\infty)=1$, so that $c=1$ and

$$
\begin{equation*}
U_{0}(y)=\tanh \left(\frac{y}{2}\right) \tag{3.13}
\end{equation*}
$$

In addition, the asymptotic boundary condition for $U_{1}$ in (3.12) is $U_{1}^{\prime} \rightarrow-1$ as $y \rightarrow \infty$. In summary, a leadingorder composite solution for $u$ over $[0,1]$ is simply

$$
\begin{equation*}
u \sim \tanh \left(\frac{x}{2 \varepsilon}\right)-x \tag{3.14}
\end{equation*}
$$

For several values of $\varepsilon$, in Fig. 4 we show that the composite expansion (3.14) compares rather favorably with
the full numerical solution to (3.7). By making an odd reflection of the single boundary-layer solution (3.14) around $x=1$, we obtain a boundary-layer solution on the domain $[0,2]$ with boundary layers at each endpoint. Similarly, we can make an odd reflection of (3.14) around $x=0$ to obtain an internal layer solution for (3.7) on $[-1,1]$. The formal result is summarized as follows:

Proposition 4 With homogeneous Dirichlet boundary conditions, consider the BVP

$$
\begin{equation*}
\varepsilon u_{x x}+\left(u_{x}+1\right) u=0 . \tag{3.15}
\end{equation*}
$$

For $\varepsilon \rightarrow 0$, the following asymptotic equilibrium states are admissible:

$$
\begin{align*}
& u_{b 1} \sim \tanh \left(\frac{x}{2 \varepsilon}\right)-x, \quad x \in[0,1], \quad \text { Single boundary-layer solution on }[0,1],  \tag{3.16}\\
& u_{i 1} \sim \tanh \left(\frac{x}{2 \varepsilon}\right)-x, \quad x \in[-1,1], \quad \text { Single interior layer solution on }[-1,1]  \tag{3.17}\\
& u_{b 2} \sim \tanh \left(\frac{x}{2 \varepsilon}\right)+\tanh \left(\frac{x-2}{2 \varepsilon}\right)-x+1, \quad x \in[0,2], \quad \text { Double boundary-layer solution on }[0,2] . \tag{3.18}
\end{align*}
$$

The expressions above are uniformly valid in the regions indicated.


Figure 5. Left figure: The equilibrium double boundary-spike solution $\mathcal{U}=u_{x}+1$ for $\varepsilon=0.04$, where $u=u_{b 2}$ is the double boundary-layer solution given in (3.18). Right figure: the eigenfunction $\phi$ given in (3.28) on $[0,1]$ and extended to $[0,2]$ to be symmetric about $x=1$.

In Fig. 5 (a) we plot the double boundary-spike solution for $\mathcal{U}$ satisfying (3.3), given by $\mathcal{U}=1+u_{x}$, where $u$ is the double boundary-layer solution $u_{b 2}$ for (3.7) given in (3.18).

### 3.2 Metastability analysis

We now study the stability of the double boundary-layer solution $u_{b 2}$ of Proposition 4. We linearize around the equilibrium solution by letting

$$
u=u_{e}(x)+e^{\lambda t} \phi(x), \quad v=v_{e}(x)+e^{\lambda t} \psi(x)
$$

By substituting this into (1.4), and dropping the subscript, we obtain

$$
\begin{equation*}
\lambda \phi=\varepsilon \phi_{x x}+u \phi_{x}-\left(u_{x}+1\right) \psi_{x x}, \quad \tau \lambda \psi=\psi_{x x}+\phi \tag{3.19}
\end{equation*}
$$

We then combine the two equations in (3.19) to get

$$
\begin{equation*}
\lambda\left(\phi+\left(u_{x}+1\right) \tau \psi\right)=L \phi \equiv \varepsilon \phi_{x x}+(u \phi)_{x}+\phi \tag{3.20}
\end{equation*}
$$

Next, we note that for any smooth function $w$, and with $u(0)=u(1)=0$, we have Green's identity

$$
\begin{equation*}
\int_{0}^{1} w L \phi d x=\varepsilon\left(w_{x} \phi-w \phi_{x}\right)_{0}^{1}+\int_{0}^{1} \phi L^{*} w d x \tag{3.21}
\end{equation*}
$$

where the adjoint operator $L^{*}$ is defined by

$$
\begin{equation*}
L^{*} w \equiv \varepsilon w_{x x}-u w_{x}+w . \tag{3.22}
\end{equation*}
$$

Here we have formed the inner product over $[0,1]$ rather than $[0,2]$, since we can exploit the symmetry of the double boundary-layer solution. More specifically, we will look for an even eigenfunction $\phi$ on the interval [0, 2], which satisfies $\phi_{x}(1)=0$. Therefore, we will consider the following boundary conditions on $[0,1]$ :

$$
\begin{equation*}
\phi(0)=0=\psi(0), \quad \phi_{x}(1)=0=\psi_{x}(1) . \tag{3.23}
\end{equation*}
$$

Let $w$ be a solution to $\varepsilon w_{x}=u w$ on $[0,1]$. By using $u_{b 1}$ in (3.16) we obtain

$$
\begin{equation*}
w \sim \exp \left(-\frac{x^{2}}{2 \varepsilon}\right) \cosh ^{2}\left(\frac{x}{2 \varepsilon}\right) \tag{3.24}
\end{equation*}
$$

We then calculate

$$
\begin{equation*}
L^{*} w=\left(u_{x}+1\right) w \sim \frac{1}{2 \varepsilon} \exp \left(-\frac{x^{2}}{2 \varepsilon}\right) \tag{3.25}
\end{equation*}
$$

We note that $w_{x}(0)=0=w_{x}(1)$. With then substitute (3.20), (3.24), (3.25), and (3.23), into (3.21), to obtain

$$
\begin{equation*}
\lambda \int_{0}^{1}\left[\phi+\left(u_{x}+1\right) \tau \psi\right] w d x=-\varepsilon w(0) \phi_{x}(0)+\int_{0}^{1} \phi\left(u_{x}+1\right) w d x \tag{3.26}
\end{equation*}
$$

We now estimate the various terms in (3.26). From (3.20), and assuming that $\lambda \ll 1$, it follows that in the outer region we have $u \phi_{x}+\left(u_{x}+1\right) \phi=0$, which reduces to $(1-x) \phi_{x}=0$. Therefore, for $\varepsilon \ll 1, \phi$ is asymptotically a constant in this region. Without loss of generality, we can impose the normalization condition $\phi(1)=1$ for $\phi$. Hence, $\phi(x) \sim 1$ in the outer region. In the inner region, by rescale $y=\varepsilon^{-1} x$ and $\phi(x)=\Phi(x / \varepsilon)$. Substituting this together with $u \sim U_{0}(y)$ into (3.20), we obtain the following leading-order equation

$$
\begin{equation*}
\Phi^{\prime \prime}+\left(\Phi U_{0}\right)^{\prime}=0 \tag{3.27}
\end{equation*}
$$

Here the primes indicate derivatives with respect to $y$. To match to the outer approximation for $\phi$, we require that $\Phi(0)=0$ and $\Phi(\infty)=1$. The solution to (3.27) with these boundary conditions is $\Phi(y)=\left(y U_{0}\right)^{\prime}$. Therefore, we have the following leading-order uniformly valid estimate of $\phi$ :

$$
\begin{equation*}
\phi \sim \frac{d}{d x}\left[x \tanh \left(\frac{x}{2 \varepsilon}\right)\right] . \tag{3.28}
\end{equation*}
$$

By using (3.28) together with (3.24) we obtain that

$$
\begin{equation*}
\varepsilon w(0) \phi_{x}(0) \sim 1 \tag{3.29}
\end{equation*}
$$

In Fig. 5(b) we plot (3.28) when it is extended to the interval $[0,2]$ as a symmetric function about $x=1$.
Next, we decompose (3.26) in terms of three integrals as

$$
\begin{equation*}
\lambda\left(I_{1}+\tau I_{2}\right)=-1+I_{3} . \tag{3.30}
\end{equation*}
$$

Here we have defined

$$
\begin{equation*}
I_{1} \equiv \int_{0}^{1} \phi w d x, \quad I_{2} \equiv \int_{0}^{1}\left(u_{x}+1\right) \psi w d x, \quad I_{3} \equiv \int_{0}^{1} \phi\left(u_{x}+1\right) w d x \tag{3.31}
\end{equation*}
$$

To evaluate these integrals, we first establish an identity for $\left(u_{x}+1\right) w$. We multiply (3.7) by $w$, and then use the equation $\varepsilon w_{x}=u w$ for $w$ to readily obtain that $\left[\left(u_{x}+1\right) w\right]_{x}=0$. Hence, $\left(u_{x}+1\right) w=\left(u_{x}(0)+1\right) w(0)$. We then use (3.16) for $u$, together with $w(0)=1$, to establish the identity

$$
\begin{equation*}
\left(u_{x}+1\right) w=\frac{1}{2 \varepsilon}, \quad x \in[0,1] . \tag{3.32}
\end{equation*}
$$

We first evaluate $I_{3}$. By using (3.31), (3.28), and (3.32), we readily calculate that

$$
\begin{equation*}
I_{3}=\frac{1}{2 \varepsilon} \int_{0}^{1} \frac{d}{d x}\left[x \tanh \left(\frac{x}{2 \varepsilon}\right)\right] d x=\frac{1}{2 \varepsilon} . \tag{3.33}
\end{equation*}
$$

Next, we calculate $I_{1}$. Since $w$ is exponentially large in the outer region, we estimate

$$
\begin{equation*}
I_{1} \equiv \int_{0}^{1} \phi w \sim \int_{0}^{1} w d x \tag{3.34}
\end{equation*}
$$

By using (3.24), we calculate in the outer region that

$$
\begin{equation*}
w \sim \frac{1}{4} \exp \left(\frac{1}{2 \varepsilon}\left(x^{2}-2 x\right)\right)=\frac{e^{1 /(2 \varepsilon)}}{4} \exp \left(-\frac{(x-1)^{2}}{2 \varepsilon}\right) . \tag{3.35}
\end{equation*}
$$

By substituting (3.35) into (3.34), we calculate that

$$
\begin{equation*}
I_{1} \sim \frac{e^{1 /(2 \varepsilon)}}{4} \int_{0}^{1} \exp \left(-\frac{(x-1)^{2}}{2 \varepsilon}\right) d x \sim \frac{\sqrt{\varepsilon}}{4} e^{1 /(2 \varepsilon)} \int_{0}^{\infty} \exp \left(-\frac{z^{2}}{2}\right) d z=\frac{e^{1 /(2 \varepsilon)}}{4} \sqrt{\frac{\varepsilon \pi}{2}} \tag{3.36}
\end{equation*}
$$

Finally, we calculate $I_{2}$. In the outer region we have $\phi \sim 1$. Therefore, assuming that $\lambda \tau \ll 1$, we obtain from (3.19) that $\psi_{x x} \sim-1$, with $\psi(0)=0$ and $\psi_{x}(1)=0$. The solution is $\psi \sim x-x^{2} / 2$. Therefore, we have that

$$
\begin{equation*}
I_{2} \sim \int_{0}^{1} \frac{1}{2 \varepsilon}\left(x-\frac{x^{2}}{2}\right) d x=\frac{1}{6 \varepsilon} . \tag{3.37}
\end{equation*}
$$

Upon substituting (3.33), (3.36), and (3.37), into (3.30), we obtain that

$$
\begin{equation*}
\lambda\left(\frac{e^{1 /(2 \varepsilon)}}{4} \sqrt{\frac{\varepsilon \pi}{2}}+\frac{\tau}{6 \varepsilon}\right) \sim \frac{1}{2 \varepsilon}-1 \tag{3.38}
\end{equation*}
$$

Upon assuming that $\tau \ll O\left(\sqrt{\varepsilon} e^{1 /(2 \varepsilon)}\right)$, we can extract the dominant terms in (3.38) for $\varepsilon \ll 1$ to obtain the following main result:

Proposition 5 Suppose that $\tau \ll O\left(e^{\frac{1}{2 \varepsilon}} \sqrt{\varepsilon}\right)$. Then the double boundary-layer solution of Proposition 4 is unstable with respect to an even perturbation. The corresponding eigenvalue is exponentially small and is given asymptotically for $\varepsilon \ll 1$ by

$$
\begin{equation*}
\lambda \sim 2 \exp \left(-\frac{1}{2 \varepsilon}\right) \sqrt{\frac{2}{\pi \varepsilon^{3}}}\left(1-\frac{2 \tau}{3} \exp \left(-\frac{1}{2 \varepsilon}\right) \sqrt{\frac{2}{\pi \varepsilon^{3}}}+O(\varepsilon)\right) \tag{3.39}
\end{equation*}
$$



Figure 6. Left figure: the slow dynamics of the quasi-equilibrium double boundary-spike solution $\mathcal{U}=u_{x}+1$ in (3.41) showing the slow exchange of mass between the two boundary spikes for $\varepsilon=0.04$. Since $x_{0}(0)=1.01>1$, the left spike has an initial mass slightly larger than the right spike. Right figure: the double boundary-layer solution $u$ in (3.40). In these figures, the heavy solid curves are for $t=0$, the solid curves are for $t=3.2845 \times 10^{4}$ and $x_{0}=1.2$, and the dashed curve is for $t=3.3541 \times 10^{4}$ and $x_{0}=1.4$. Eventually the right spike loses all its mass to the left one.

Note that the relative error term in this expansion is $O(\varepsilon)$ and it swamps the exponentially small correction due to $\tau$. The $O(\varepsilon)$ error comes from a poor estimate of $\int_{0}^{1} w d x$. To obtain a better estimate, it is necessary to compute $w$ to a higher order, which would involve the computation of $U_{1}$ from (3.12). Nevertheless, Proposition 5 shows the instability of a double boundary-layer solution. As a numerical example, with $\varepsilon=0.05$ we obtain from a full numerical computation that $\lambda=0.007223381$ when $\tau=0$. This compares well with the asymptotic prediction of $\lambda \sim 0.006479929$. Next, for $\tau=1$ we obtain $\lambda=0.00720314197261$ so that $\frac{\left.\lambda\right|_{\tau=0}-\left.\lambda\right|_{\tau=1}}{\left.\lambda\right|_{\tau=0}}=0.0028$. This compares favorably with the theoretical prediction of $\frac{2}{3} \exp \left(-\frac{1}{2 \varepsilon}\right) \sqrt{\frac{2}{\pi \varepsilon^{3}}}=0.0021$.

Remark 6 The equilibrium problem (3.7) for the reduced Keller-Segel model (1.4) also arises in the analysis of $[\mathbf{1}],[\mathbf{2}],[\mathbf{1 4}]$, and $[\mathbf{1 0}]$, for the upward propagation of a metastable flame-front in a vertical channel. The timedependent flame-front problem is equivalent to (1.4) for the case $\tau=0$. The eigenvalue estimate in (3.39) for $\tau=0$ agrees with the asymptotic estimate given in equation (3.29) of $[\mathbf{1 0}]$, which was derived by first transforming (1.4) with $\tau=0$ to a quasi-linear problem (see §1 of [10]). The analysis here leading to an estimate of $\lambda$, corrects an error made in the eigenvalue calculation of equation (3.27) of [14], resulting from an incorrect evaluation of one integral.

Finally, we discuss quasi-equilibrium double boundary-layer solutions $u$ to (3.7) given by

$$
\begin{equation*}
u=x_{0} \tanh \left(\frac{x_{0} x}{2 \varepsilon}\right)-\left(2-x_{0}\right) \tanh \left(\frac{\left(2-x_{0}\right)(2-x)}{2 \varepsilon}\right)+\left(2-x_{0}\right)-x \tag{3.40}
\end{equation*}
$$

In the outer region, $u \sim x_{0}-x$. The double boundary-spike solution $\mathcal{U}$ to (3.3), given by $\mathcal{U}=u_{x}+1$, is

$$
\begin{equation*}
\mathcal{U}=\frac{x_{0}^{2}}{2 \varepsilon} \operatorname{sech}^{2}\left(\frac{x_{0} x}{2 \varepsilon}\right)+\frac{\left(2-x_{0}\right)^{2}}{2 \varepsilon} \operatorname{sech}^{2}\left(\frac{\left(2-x_{0}\right)(2-x)}{2 \varepsilon}\right) \tag{3.41}
\end{equation*}
$$

From (3.41), the left boundary spike has more mass than the right one when $x_{0}>1$. Then, the slow dynamics of $x_{0}$ characterizes the slow mass exchange between the two spikes. For $\tau \ll 1$, we obtain from $\S 3.2$ of $[\mathbf{1 0}]$ (see also Corollary 2 of [14]) that $x_{0}(t)$ satisfies the asymptotic ODE

$$
\begin{equation*}
x_{0}^{\prime} \sim \sqrt{\frac{2}{\pi \varepsilon}}\left[\left(2-x_{0}\right)^{2} e^{-\left(2-x_{0}\right)^{2} / 2 \varepsilon}-x_{0}^{2} e^{-x_{0}^{2} / 2 \varepsilon}\right] \tag{3.42}
\end{equation*}
$$

In Fig. 6 we illustrate this slow mass exchange mechanism for the case where $x_{0}(0)=1.01$, for which $x_{0}^{\prime}>0$. In this case, the right spike in $\mathcal{U}$ will disappear at some finite time.

## 4 Global Solution to a Reduced Model

In this section we consider the reduced Keller-Segel model (1.4) and we prove that solutions exist globally in time. We first re-write this reduced model as follows:

$$
\begin{equation*}
u_{t}=\varepsilon u^{\prime \prime}-\left(1+u^{\prime}\right) v^{\prime \prime}, \quad \tau v_{t}=v^{\prime \prime}+u, \quad \text { in } \Omega \times I=[-1,1] \times[0, T) \tag{4.1}
\end{equation*}
$$

Here the primes indicate partial derivatives with respect to $x$. For (4.1), the following initial conditions and Dirichlet boundary conditions are assumed

$$
\begin{equation*}
u(\cdot, 0)=u_{0}(x), \quad v(\cdot, 0)=v_{0}(x) ; \quad u(\cdot, t)=v(\cdot, t)=0 \quad \text { at } x= \pm 1 \tag{4.2}
\end{equation*}
$$

We summarize our main result as follows:

Proposition 7 Let $u$ and $v$ be solutions to the reduced Keller-Segel model (4.1) and (4.2). If $u_{0}(x)$ and $v_{0}(x)$ are smooth, then $u$ and $v$ are smooth for all time.

Proof Without loss of generality we can assume for simplicity that $\varepsilon=1$ and $\tau=1$, since different values of these parameters do not affect our analysis regarding global existence. We first note that $u$ and $v$ are uniformly bounded from the formulation of the solutions in (3.5). We also note that we can use a standard estimate for a linear parabolic equation to derive that $v$ in (4.1) satisfies

$$
\begin{equation*}
\left\|v_{t}\right\|_{L_{x}^{p}, L_{t}^{q}(\Omega \times I)}+\|v\|_{W_{x}^{2, p}, L_{t}^{q}(\Omega \times I)} \leq C\|u\|_{L_{x}^{p}, L_{t}^{q}(\Omega \times I)}, \tag{4.3}
\end{equation*}
$$

for any $1<p, q<\infty$. Here $\|f\|_{L_{x}^{p}, L_{t}^{q}}$ indicates the mixed norm of $L^{p}$ and $L^{q}$ in space and time variables for a measurable function $f$, namely $\|f\|_{L_{x}^{p}, L_{t}^{q}(\Omega \times I)}^{q}=\int_{I}\|f(\cdot, t)\|_{L^{p}(\Omega)}^{q} d t$. In (4.3) we have denoted by $W^{k, p}$ the usual Sobolev space for the case where all derivatives up to the $k^{\text {th }}$ order are in $L^{p}$. We remark that since $u$ is uniformly bounded and $\Omega$ is a bounded domain, the right-hand side of (4.3) is bounded by a fixed constant depending on $p, q$ and $T$. Next, we obtain $u_{t}^{\prime}=u^{\prime \prime \prime}-\left[\left(u^{\prime}+1\right) v^{\prime \prime}\right]^{\prime}$, upon differentiating the first equation in (4.1) with respect to $x$. Multiplying this equation by $u^{\prime}$, and integrating the resulting equation by parts, we readily obtain

$$
\begin{equation*}
\frac{1}{2} \frac{d}{d t} \int_{\Omega}\left|u^{\prime}\right|^{2} d x+\int_{\Omega}\left|u^{\prime \prime}\right|^{2} d x=\int_{\Omega}\left(u^{\prime}+1\right) v^{\prime \prime} u^{\prime \prime} d x \tag{4.4}
\end{equation*}
$$

Here we have used that $u^{\prime \prime}=0$ and $v^{\prime \prime}=0$ at the boundaries $x= \pm 1$.
We need to estimate the right-hand side in (4.4). To do so, we re-write it as follows:

$$
\begin{equation*}
\int_{\Omega}\left(u^{\prime}+1\right) v^{\prime \prime} u^{\prime \prime} d x=\int_{\Omega} u^{\prime} v^{\prime \prime} u^{\prime \prime} d x+\int_{\Omega} v^{\prime \prime} u^{\prime \prime} d x: \equiv I+I I \tag{4.5}
\end{equation*}
$$

Due to standard interpolations of Sobolev norms, we have the following estimates:

$$
\begin{gathered}
\left\|u^{\prime}\right\|_{L^{2}(\Omega)} \leq C\|u\|_{L^{2}(\Omega)}^{\frac{1}{2}}\left\|u^{\prime \prime}\right\|_{L^{2}(\Omega)}^{\frac{1}{2}} \\
\|u\|_{L^{4}(\Omega)} \leq C\|u\|_{L^{2}(\Omega)}^{\frac{3}{4}}\left\|u^{\prime}\right\|_{L^{2}(\Omega)}^{\frac{1}{4}} \\
\left\|u^{\prime}\right\|_{L^{4}(\Omega)} \leq C\left\|u^{\prime}\right\|_{L^{2}(\Omega)}^{\frac{3}{4}}\left\|u^{\prime \prime}\right\|_{L^{2}(\Omega)}^{\frac{1}{4}}
\end{gathered}
$$

Here we have used the facts that $u=0$ on the boundary and that the average of $u^{\prime}$ is zero. By using these estimates, together with the Hölder inequality, we obtain for the first term $I$ in (4.5) that

$$
I=\int_{\Omega} u^{\prime} v^{\prime \prime} u^{\prime \prime} d x \leq\left\|u^{\prime}\right\|_{L^{4}(\Omega)}\left\|v^{\prime \prime}\right\|_{L^{4}(\Omega)}\left\|u^{\prime \prime}\right\|_{L^{2}(\Omega)} \leq C\|u\|_{L^{2}(\Omega)}^{\frac{3}{8}}\left\|v^{\prime \prime}\right\|_{L^{4}(\Omega)}\left\|u^{\prime \prime}\right\|_{L^{2}(\Omega)}^{\frac{13}{8}}
$$

Then, since $u$ is bounded and $\Omega$ is a bounded domain, we obtain

$$
I \leq C\left\|v^{\prime \prime}\right\|_{L^{4}(\Omega)}\left\|u^{\prime \prime}\right\|_{L^{2}(\Omega)}^{\frac{13}{8}} \leq C\left\|v^{\prime \prime}\right\|_{L^{4}(\Omega)}^{\frac{16}{3}}+\frac{1}{4}\left\|u^{\prime \prime}\right\|_{L^{2}(\Omega)}^{2}
$$

Here we have used Young's inequality in the last inequality above. For the second term $I I$ in (4.5), we estimate

$$
I I \leq\left\|v^{\prime \prime}\right\|_{L^{2}(\Omega)}\left\|u^{\prime \prime}\right\|_{L^{2}(\Omega)} \leq C\left\|v^{\prime \prime}\right\|_{L^{2}(\Omega)}^{2}+\frac{1}{4}\left\|u^{\prime \prime}\right\|_{L^{2}(\Omega)}^{2}
$$

In summary, by using the estimate (4.3) together with the other estimates above, we conclude that

$$
\int_{\Omega}\left|u^{\prime}(\cdot, T)\right|^{2} d x+\int_{0}^{T} \int_{\Omega}\left|u^{\prime \prime}\right|^{2} d x d t \leq \int_{\Omega}\left|u^{\prime}(\cdot, 0)\right|^{2} d x+C \int_{0}^{T} \int_{\Omega}\left|v^{\prime \prime}\right|^{2} d x d t+C \int_{0}^{T}\left(\int_{\Omega}\left|v^{\prime \prime}\right|^{4} d x\right)^{\frac{4}{3}} d t
$$

$$
\leq \int_{\Omega}\left|u^{\prime}(\cdot, 0)\right|^{2} d x+C \int_{0}^{T} \int_{\Omega}|u|^{2} d x d t+C \int_{0}^{T}\left(\int_{\Omega}|u|^{4} d x\right)^{\frac{4}{3}} d t \leq \int_{\Omega}\left|u^{\prime}(\cdot, 0)\right|^{2} d x+C T
$$

Here we have used that $u$ is bounded. From this final estimate we conclude that $u$ is continuous by the Sobolev embedding argument. Therefore, by a standard bootstrap procedure, it follows that $u$ and $v$ are smooth. This completes the proof.

Remark 8 For the case $\tau=0$, where the chemotactic equation is of elliptic type, we can also show that solutions to (4.1) are smooth. This case, in fact, is much simpler to treat than the case where $\tau>0$, and so we leave the details to the reader. Indeed, if $\tau=0$, then the system (4.1) can be reduced to $u_{t}=u^{\prime \prime}+\left(1+u^{\prime}\right) u$. By following a similar procedure as for case where $\tau>0$, we can again show that $u$, and consequently $v$, are both smooth.

## 5 Conclusion

In a one-dimensional domain, and in the asymptotic limit of a large mass $M>1$, a quasi-equilibrium spike solution for the classical Keller-Segel model with a linear chemotactic function was constructed. In this limit, the equilibrium spike solution was found to be translationally unstable, and is metastable for asymptotically large domain lengths $L$. For $M \gg 1$ and $L \gg 1$, an asymptotic ODE for the metastable spike motion was derived that showed that the spike drifts exponentially slowly towards one of the boundaries of the domain. For $L \gg 1$ and $M \gg 1$, the existence of an exponentially small eigenvalue indicates that the solution to the classical Keller-Segel model can be highly sensitive to small perturbations. This sensitivity for $M \gg 1$ and $L \gg 1$ suggests a strong lack of robustness in biological modeling based on the classical Keller-Segel model, and it also suggests that severe difficulties will be encountered in trying to numerically compute solutions. In contrast, for $M \gg 1$ and $L=O(1)$, the translation eigenvalue is unstable, but not exponentially small. In this parameter range, it would be interesting to construct a traveling-wave spike solution to characterize the motion of the spike.

For a reduced Keller-Segel model (1.4) we have studied the stability of an equilibrium solution that consists of two boundary spikes centered at the endpoints of the domain. Rather curiously, the equilibria of this reduced Keller-Segel model are very similar to those of the model of $[\mathbf{1}],[\mathbf{2}],[\mathbf{1 4}]$, and $[\mathbf{1 0}]$, for the upward propagation of a flame-front in a vertical channel. We showed that this double boundary-spike solution to the reduced KellerSegel model is unstable due to an asymptotically exponentially small positive eigenvalue in the spectrum of the linearized problem. This eigenvalue is estimated precisely. The shape of the corresponding eigenfunction is shown to initiate an exchange of mass between the two boundary spikes in such a way that after a very long time one of the two boundary spikes fully absorbs the mass of the other. Finally, we have shown that solutions to the reduced Keller-Segel model with arbitrary initial conditions exist globally in time.

There are several open problems related to this study. The first open problem is to extend the derivation of the equations of motion of the center of the spike (2.55) to the case when the domain length $L$ is not large. The second issue concerns the stability of a homoclinic stripe solution of zero curvature to the Keller-Segel model in a square domain under a linear chemotactic function. For this two-dimensional problem, it would be interesting
to determine if spot-generating breakup instabilities of the stripe can occur, and if so, whether they are the precursor to a finite-time blow-up of solutions to the Keller-Segel model. A third open problem is to analyze the existence and stability of spike solutions to a modified Keller-Segel model in two space dimensions, where the rate of increase of $v$ with respect to $u$ saturates as $u \rightarrow \infty$. In a certain asymptotic limit, this saturation effect was shown to lead to metastable spikes for the two-dimensional Keller-Segel model under a logarithmic chemotactic function $\Phi(v)=\ln v^{p}$ in (1.1). It would be interesting to extend that analysis to the case of a linear chemotactic function.

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## Appendix A Nondimensionalization of the Keller-Segel Model

We consider (1.1) for $U, V$, with $\Phi(V)=\beta V$, in the one-dimensional domain $-\mathcal{L}<X<\mathcal{L}$ given by

$$
\begin{equation*}
U_{T}=D U_{X X}-\beta\left(U V_{X}\right)_{X}, \quad V_{T}=\kappa V_{X X}-\gamma V+\alpha U . \tag{A.1}
\end{equation*}
$$

The total mass is given by $\int_{-\mathcal{L}}^{\mathcal{L}} U d X=\mathcal{M}$. We introduce the non-dimensional variables $u, v, x$, and $t$, by

$$
\begin{equation*}
T=\omega t, \quad U=U_{0} u, \quad V=V_{0} v, \quad X=L_{d} x . \tag{A.2}
\end{equation*}
$$

In terms of these variables, (A.1) becomes

$$
\begin{equation*}
\frac{L_{d}^{2}}{D \omega} u_{t}=u_{x x}-\frac{\beta V_{0}}{D}\left(u v_{x}\right)_{x}, \quad \frac{1}{\gamma \omega} v_{t}=\frac{\kappa}{L_{d}^{2} \gamma} v_{x x}-v+\frac{\alpha U_{0}}{\gamma V_{0}} u \tag{A.3}
\end{equation*}
$$

on the domain $|x|<L \equiv \mathcal{L} / L_{d}$. This form suggests the choices

$$
\begin{equation*}
\omega=\frac{\kappa}{D \gamma}, \quad L_{d}=\sqrt{\frac{\kappa}{\gamma}}, \quad V_{0}=\frac{D}{\beta}, \quad U_{0}=\frac{D \gamma}{\alpha \beta} . \tag{A.4}
\end{equation*}
$$

In addition, the mass condition $\int_{-\mathcal{L}}^{\mathcal{L}} U d X=\mathcal{M}$ transforms to $\int_{-L}^{L} u d x=\mathcal{M} /\left(U_{0} L_{d}\right)$. In this way, we obtain (1.2) with the three nondimensional parameters $\tau, L$, and $M$, defined by

$$
\begin{equation*}
\tau \equiv \frac{D}{\kappa}, \quad L \equiv \mathcal{L} \sqrt{\frac{\gamma}{\kappa}}, \quad M \equiv \frac{\mathcal{M} \alpha \beta}{D \sqrt{\gamma \kappa}} \tag{A.5}
\end{equation*}
$$

Therefore, the limit $L=O(1)$ and $M \gg 1$ can be interpreted as $D$ small with $\kappa$ fixed, or equivalently $\beta$ is large relative to the other parameters. The limit $L \gg 1$ and $M \gg 1$, where metastability occurs, is when both $D$ and $\kappa$ are small relative to the other parameters.

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