# Instability thresholds in the microwave heating model with exponential nonlinearity. 

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#### Abstract

When ceramics are heated inside a microwave cavity, a well known phenomenon is the occurrence of hot spots - localized regions of high temperature. This phenomenon was modelled by Kriegsmann [IMA J. App. Math. 59(2), (1997) pp. 123-146], [IMA J. App. Math. 66(1), (2001) pp. 1-32] using a non-local evolution PDE. We investigate profile and the stability of hot spots in one and two dimensions using Kriegsmann's model with exponential nonlinearity. The linearized problem assciated with hot spot type solutions posesses two classes of eigenvalues. The first type are the large eigenvalues are assocaited with the stabititly of the hot spot profile and in this paticular model there can not be instablitly associated with these eigenvalues. The second type are the small eigenvalues associated with translation invarience. We show that the hot spots can become unstable due to the presence of small eigenvalues, and we characterize the instability thresholds. In particular, we show that for the material with low heat conductivity (such as ceramics), and in the presence of a variable electric field, the hot spots are typically stable inside a plate (in 2D) but can become unstable for a slab (in 1D) provided that the microwave power is sufficiently large. On the other hand for materials with high heat conductivity, the interior hot spots are unstable and move to the boundary of the domain in either one or two dimensions. For materials with moderate heat conductivity, the stability of hot spots is determined by both the geometry and the electric field inside the microwave cavity.


## 1 Introduction

The usage of microwave heating to join ceramic materials can result in the formation of stable highly localized hot spots [16]. The formation of a localized hot spot cannot be explained using a simple linear theory. Several nonlinear models of hot spot formation have been proposed to explain this phenomenon, see for example review [5] and the references therein. In [1] a model for the temperature of a sample placed in a resonant chamber is derived. A wave guide keeps the amplitude of the microwaves constant along one axis. The formation of a stable hot-spot is the result of considering a temperature dependent electrical conductivity in conjunction with a local detuning in the resonant chamber containing the sample. The electrical conductivity changes occurring in the sample interfere with the formation of a standing wave in the resonant chamber. These considerations result in the
following non-local reaction-diffusion equation:

$$
\begin{align*}
U_{\tau} & =D \Delta U-2\left(U+b\left[(U+1)^{4}-1\right]\right)+\frac{P f(x) G(U)}{\left(1+\chi \int_{\Omega} f(x) G(U) d x\right)^{2}}, \quad x \in \Omega  \tag{1}\\
\partial_{n} U & =0, \quad x \in \partial \Omega \tag{2}
\end{align*}
$$

Here $f(x)$ is proportional to the square of the magnitude of the electric field along the sample, $G(u)$ is the scaled temperature-depedent electrical conductivity, $D$ is the constant thermal diffusivity, $\chi>0$ is a parameter based on the geometry of the sample and the Q-factor of the cavity (see [1]), $b \ll 1$ is the ratio of radiative to convective heat loss along the axis of the sample at the ambient temperature, and $P>0$ is the nondimensional power of the resonant cavity mode. The form of $f(x)$ is determined by the wave guide used as well as the geometry of the chamber and placement of the sample within the chamber. In [12], the sample is placed across the chamber and the wave guide keeps the electric field constant along the axis of a thin cylindrical sample. In this instance, the hot spot is actually unstable and propagates exponentially slowly along the sample until reaching the boundary of the domain [9]. In [13] a thin cylindrical sample is placed along the wave guide and the electric field may then vary along the length of the sample. Under certain additional assumptions on the parameters, it was shown in [9] that the hot spot will travel along the length of the sample until reaching a local maximum of $f$. The function $G(u)$ is the dimensionless electrical conductivity of the sample. We will consider a realistic exponential model $G(U)=e^{c U}$. We will also consider the small Biot number (b). For ceramics, the thermal diffusivity $D$ is typically small. We make a further simplicfication by assuming that $\chi \int_{\Omega} f(x) e^{c U} d x \gg 1$. This assumption is consistent with most applications where the hot spot is observed [9]. In the non-dimensional form, we obtain

$$
\begin{equation*}
u_{t}=d^{2} \Delta u-u+\frac{p f(x) e^{u}}{\left(\int_{\Omega} f(x) e^{u}\right)^{2}}, x \in \Omega ; \quad \partial_{n} u=0, x \in \partial \Omega \tag{3}
\end{equation*}
$$

where $p=\frac{c P}{2 \chi^{2}}$ and $d=\sqrt{\frac{c}{2} D}$. While the diffusivity coefficient $d^{2}$ is typically small for ceramic materials, we will also consider the more general mathematical problem where $d$ may be of $O(1)$. For example, in two dimensions and with $d=1$, this model is related to the Liouville equation [15]. We will also consider the general form of $f(x)$, not restricted to the standard geometries and wave guides. Equation (3) is the starting point of our analysis.

Let us summarize the main results of this paper. We consider the equilibium hot spot solutions on a one-dimensional interval, a bounded two dimensional domain and a two-dimensional disk. The hot spot location and its stability is determined by the geometry of the problem as well as the electric field strength $f(x)$. The detailed results for one and two dimensions are given in $\S 2$ and $\S 3$, respectively (Principal Results 2.1 and 2.2 for one dimension, Principal Results 3.1 and 3.2 for two dimensions). In particular, the hot spots are found to exist provided that the power $p$ is sufficiently large, even for relatively large value of the thermal diffusivity $d$. An important case is the radially symmetric domain and $f(x)=f(|x|)$, which we now describe. In this case, by symmetry, the hot spot is located at the center of the domain. For a disk domain $\Omega=B_{L}(0)=\{x:|x| \leq L\} \subset \mathbb{R}^{2}$ and a radially symmetric electric field strength $f(x)=f(|x|)$, we find that the hot spot is stable with respect to both the large and small eigenvalues provided that

$$
\begin{equation*}
-\frac{f^{\prime \prime}(0)}{f(0)} \geq \frac{2}{d^{2}}\left(\frac{K_{0}^{\prime \prime}(L / d)}{I_{0}^{\prime \prime}(L / d)}-\frac{K_{0}^{\prime}(L / d)}{I_{0}^{\prime}(L / d)}\right) \tag{4}
\end{equation*}
$$

where $I_{0}$ and $K_{0}$ are Bessel functions; it is unstable with respect to the small eigenvalues if the inequality in (4) is reversed. For typical ceramics with $d \ll 1$, the stability condition (4) reduces to

$$
\begin{equation*}
-\frac{f^{\prime \prime}(0)}{f(0)} \geq \frac{4 \pi}{d^{2}} e^{-2 L / d} \tag{5}
\end{equation*}
$$

Since the right hand side of (5) is exponentially small, the two-dimensional hot spot for a ceramic material will be stable at the center provided that $f$ has a maximum there.

For a one-dimensional situation with $f(x)=f(-x)$ and $\Omega=[-L, L]$, we show in Principal Result 2.2 that the hot spot is stable provided that

$$
\begin{equation*}
L / d \gg 1 \quad \text { and } \quad-\frac{f^{\prime \prime}(0)}{f(0)} \geq \frac{4}{d^{2}} \ln \left(\frac{p}{2 d^{2} f(0)}\right) \exp \left(\frac{-2 L}{d}\right) ; \quad \Omega=[-L, L] \in \mathbb{R} \tag{6}
\end{equation*}
$$

Both of these requirements are necessary; if one of them does not hold, then the hot spot was found to be unstable. In particular, this shows that in one dimension, the heat diffisivity $d$ must be small. In addition, the hot spot can be distabilized if the power $p$ is sufficiently large. This is unlike the two-dimensional case, where the stability result is independent of the power $p$. Equations (4) and (6) also show that in either one or two dimensions, the hot spot cannot be stable if $f(x)$ is constant; a necessary condition for the radially symmetric case is that $f(x)$ must have a maximum at the origin.

In $\S 5$ we study numerically and analytically how the formation of the hot spots depends on the power $p$. For the case of small diffusion $d \ll 1$, we show that the necessary condition for hot spot formation is that $p>p_{c}$ where $p_{c}$ is the critical power given by

$$
\begin{equation*}
p_{c}=M e\left(\int_{\Omega} W\left(-\frac{f(x)}{M e}\right) d x\right)^{2} \tag{7}
\end{equation*}
$$

where $M=\max _{x \in \Omega}|f(x)|$ and $W(x)$ is the principle branch of the Lambert W function (which satisfies $x=W(x) e^{W(x)}$ with $\left.-1<W(x)\right)$. Finally, we study the possibility of a pattern with two spots. We show in $\S 5$ that two hot spots cannot be stable. Moreover the unstable mode corresponds to a competition instability, whereby one of the two spots is rapidly absorbed by the other. This is analogous to the so-called shadow limit of reaction-diffusion equations, see for example [8], where a similar phenomenon is observed for the Geirer-Meinhardt model. We conclude with some discussion of open problems in $\S 6$.

We note that the results in this paper rely on the use of careful but formal asymptotics. No attempt has been made to provide a rigorous justification. However careful numerics were used to verify all of the results.

## 2 One dimension

In this section we study hot spots on a one-dimensional domain $\Omega=[-L, L]$. We first construct a stationary hot-spot solution using matched asymptotics. An example of such a hot spot is shown in Figure 1(a).

The steady state problem is

$$
\begin{gather*}
u_{x x}-\frac{1}{d^{2}} u+\alpha f(x) e^{u}=0, \quad u_{x}( \pm L)=0 \text { where }  \tag{8}\\
\alpha:=\frac{p}{\left(d \int_{-L}^{L} f(x) e^{u} d x\right)^{2}} \tag{9}
\end{gather*}
$$

Roughly speaking, the hot-spot solution consists of an inner region of hot temperature where the exponential term in (8) is dominant, and of an outer layer of colder temperature, where the background effects dominate. The location $x_{0}$ of the stationary hot spot is determined by both the electric field strength $f(x)$ and the boundary effects. We summarize the construction as follows.


Figure 1: (a) Stationary hot spot solution to (8) in one dimension. The parameters are $f(x)=1$, $L=2, d=1$ with $p=1.144 \times 10^{9}$ chosen so that (9) yields $\alpha=0.0001$. Solid curve represents the numerical solution to the boundary value problem (8). Dashed curve is the uniform asymptotic approximation (15). (b) Hot spot solution to (51) in two dimensions on a disk of radius $L=1.5$. Other parameters are $f(x)=1, d=1$ with $p=1.7217 \times 10^{5}$ chosen so that (52) yields $\alpha=0.004$. Solid curve represents the numerical solution to the boundary value problem (51). Dashed curve is the uniform asymptotic approximation (101).

Principal Result 2.1. Suppose that either $p \gg 1$ or $d \ll 1$, with all other parameters of $O(1)$. Then (8,9) admits a hot-spot solution concentrated at the location $x_{0}$, given asymptotically by

$$
\begin{equation*}
\frac{\sinh \left(\frac{2 x_{0}}{d}\right)}{\sinh \left(\frac{2 L}{d}\right)}+\mu \frac{f^{\prime}\left(x_{0}\right)}{f\left(x_{0}\right)} \sim 0 \tag{10}
\end{equation*}
$$

where $\mu \ll 1$ is the spatial extent of the hot spot centered at $x_{0}$, asymptotically given by

$$
\begin{equation*}
\mu \sim \frac{d}{\ln \left(\frac{p}{2 d^{2} f\left(x_{0}\right)}\right)}\left(\frac{\cosh \left(\frac{2 x_{0}}{d}\right)}{\sinh \left(\frac{2 L}{d}\right)}+\operatorname{coth} \frac{2 L}{d}\right) \tag{11}
\end{equation*}
$$

Inside the hot spot, the temperature profile has the shape

$$
\begin{equation*}
u(x) \sim \ln \left\{\frac{p}{2 \alpha \mu^{2} f\left(x_{0}\right)} \operatorname{sech}^{2}\left(\frac{x}{2 \mu}\right)\right\}, \quad\left|x-x_{0}\right| \ll \mu \tag{12}
\end{equation*}
$$

where $\alpha$ as defined in (9), is asymptotically given by

$$
\begin{equation*}
\alpha \sim \frac{d^{2} 4}{p \mu^{2}} . \tag{13}
\end{equation*}
$$

Away from the hot spot, the temperature profile is

$$
\begin{equation*}
u(x) \sim \frac{2}{\mu} G\left(x, x_{0}\right), \quad\left|x-x_{0}\right| \gg \mu \tag{14}
\end{equation*}
$$

where $G\left(x, x_{0}\right)$ is the Green's function defined in (25).


Figure 2: (a) The plot of hot spot center $x_{0}$ vs. $m$, with $f(x)=1+m x, L=2.7, d=1, \alpha=3.16 \times 10^{-5}$. Crosses denote the numerical solution of (8). Solid line denotes the asymptotic prediction given by (10) with $\mu$ given by (30). (b) The plot of $x_{0}$ vs. $\lambda$ where $\lambda$ is the eigenvalue with largest real part, in this case the small eigenvalues. Crosses denote the values of $\lambda$ as numerically computed from (16). Solid line denotes the asymptotic prediction given by (49).

By combining (12) and (14), for the case of a symmetric hot spot ( $x_{0}=0, f(x)$ is even), a composite solution that is uniformly valid on $[-L, L]$ is given by

$$
\begin{equation*}
u(x) \sim \ln \left\{\frac{1}{4} \operatorname{sech}^{2}\left(\frac{x}{2 \mu}\right)\right\}+|x| / \mu+\frac{\ln \left(\frac{2}{\mu^{2} f\left(x_{0}\right) \alpha}\right)}{\cosh (L / d)} \cos \left(\frac{|x|-L}{d}\right) \tag{15}
\end{equation*}
$$

Figure 1(a) shows a favorable comparison between the composite asymptotic solution and the numerical solution to the full problem (8). In Figure 2(a), the effect of variation of the magnitude of the electric field strength, $f(x)$ along the length of the sample, on the hot spot location is shown. Again, a favorable comparsion between full numerics and the asymptotic formula for $x_{0}(10)$ is observed.

Next we address the stability of the hot spot with respect to time. By linearizing near the steady state:

$$
u(x, t)=u(x)+e^{\lambda t} \phi(x), \quad \phi \ll 1
$$

we are led to the study of the following eigenvalue problem

$$
\begin{equation*}
\frac{\lambda}{d^{2}} \phi=\phi_{x x}-\frac{1}{d^{2}} \phi+\alpha f(x) e^{u} \phi-2 \alpha^{3 / 2} p^{-1 / 2} d^{-1} f(x) e^{u} \int_{-L}^{L} f(x) e^{u} \phi d x \tag{16}
\end{equation*}
$$

Note that (16) is self-adjoint; as a consequence all of its eigenvalues are purely real. The problem (16) admits large eigenvalues of $O\left(\frac{1}{\mu^{2}}\right)$ as well as eigenvalues of that arise due to the translation invariance of the inner solution, which we will call small eigenvalues. The large eigenvalues are studied in §4, where it is shown that they are all negative. Thus the stability is controlled by the sign of the small eigenvalues. We summarize our findings below.

Principal Result 2.2. Consider a hot-spot solution as constructed in Principal result 2.1. In the limit $\mu \rightarrow 0$, there are two cases.

1. $d / L=O(1):$ The hot spot is unstable.
2. $d / L \ll 1$ : The the hot spot is stable if and only if $\lambda<0$ where $\lambda$ is given by

$$
\begin{equation*}
\lambda \sim 2 \mu d\left(\frac{f^{\prime \prime}\left(x_{0}\right)}{f\left(x_{0}\right)}-\left(\frac{f^{\prime}\left(x_{0}\right)}{f\left(x_{0}\right)}\right)^{2}\right)+8 \exp \left(\frac{-2 L}{d}\right) \cosh \left(\frac{x_{0}}{d}\right), \quad d / L \ll 1 \tag{17}
\end{equation*}
$$

In the first case, the unstable eigenvalue $\lambda$ is given implicitly by (49).
Formula (17) is an asymptotic estimate to the small eigenvalue of (16). Figure 2(b) shows that the asymptotic formula (17) is in good agreement with the numerically computed solution to the eigenvalue problem (16). For a radially symmetric case where $f(x)=f(|x|)$ and $x_{0}=0$, the stability criterion of Principal Result 2.2 in conjuction with (9) yields the formula (6).

Derivation of Principal Result 2.1. The derivation consists of two steps. We first determine the leading order profile and the spatial extent $\mu$ of the hot spot. In the second step, the location $x_{0}$ of the hot spot is determined at the next order of the expansion.

Step 1: Hot spot profile. To determine the temperature profile and the spatial extent of the hot spot, we expand near its center $x=x_{0}$ as

$$
\begin{align*}
x & =x_{0}+\mu y  \tag{18a}\\
f(x) & =f_{0}+\mu y f_{0}^{\prime}+\cdots \quad \text { where } f_{0} \equiv f\left(x_{0}\right), f_{0}^{\prime} \equiv f^{\prime}\left(x_{0}\right)  \tag{18b}\\
u(x) & =U(y)=U_{0}(y)+\mu U_{1}(y)+\cdots \tag{18c}
\end{align*}
$$

where $\mu \ll 1$ is the spatial extent of the hot spot, to be determined later. Equation (8) then becomes

$$
U_{y y}+\frac{\mu^{2}}{d^{2}} U+\mu^{2} \alpha f\left(x_{0}+\mu y\right) e^{U}=0
$$

Next we change variables

$$
\begin{equation*}
U(y)=\ln \left\{\frac{V(y)}{\alpha \mu^{2} f\left(x_{0}+\mu y\right)}\right\} \tag{19}
\end{equation*}
$$

and expand

$$
\begin{aligned}
& V=V_{0}+\mu V_{1}+\cdots \\
& U=U_{0}+\mu U_{1}+\cdots
\end{aligned}
$$

The equation for $V_{0}$ is then

$$
\begin{equation*}
V_{0 y y}-\frac{V_{0 y}^{2}}{V_{0}}+V_{0}^{2}=0 \tag{20}
\end{equation*}
$$

An explicit solution is given by

$$
\begin{equation*}
V_{0}=\frac{1}{2} \operatorname{sech}^{2}\left(\frac{y}{2}\right) \tag{21}
\end{equation*}
$$

Note that (20) admits a scaling invariance $V_{0}=a^{-2} \hat{V}_{0} ; \quad y=a \hat{y}$. However we can set $a=1$ by an appropriate relabelling of $\mu$.

Next we consider the outer region of (8). We estimate

$$
\begin{equation*}
u_{x x}-\frac{1}{d^{2}} u=-C_{0} \delta\left(x-x_{0}\right) \tag{22}
\end{equation*}
$$

where $\delta\left(x-x_{0}\right)$ is is the Dirac delta function with support at $x_{0}$ and the constant $C_{0}$ is given by

$$
\begin{equation*}
C_{0}=\int_{-L}^{L} \alpha f(x) e^{u} d x \sim \frac{1}{\mu} \int_{-\infty}^{\infty} V_{0}(y) d y \sim \frac{2}{\mu} \tag{23}
\end{equation*}
$$

The solution to (22) is therefore

$$
\begin{equation*}
u \sim \frac{2}{\mu} G\left(x, x_{0}\right) \tag{24}
\end{equation*}
$$

where $G$ is the Green's function satisfying

$$
G_{x x}-\frac{1}{d^{2}} G=-\delta\left(x-x_{0}\right) ; \quad G_{x}\left( \pm L, x_{0}\right)=0
$$

and is explicitly given by

$$
G\left(x, x_{0}\right)=\frac{d}{\sinh \left(\frac{2 L}{d}\right)} \begin{cases}\cosh \left(\frac{x-L}{d}\right) \cosh \left(\frac{x_{0}+L}{d}\right), & x>x_{0}  \tag{25}\\ \cosh \left(\frac{x_{0}-L}{d}\right) \cosh \left(\frac{x+L}{d}\right), & x<x_{0}\end{cases}
$$

The spatial extent of the hot spot $\mu$ is now determined by matching the inner and outer solution. To do so, we write the inner solution in the outer variables as $|y| \rightarrow \infty$. Note that

$$
V_{0} \sim 2 \exp (-|y|), \quad|y| \rightarrow \infty
$$

so that from (19) we get

$$
\begin{align*}
U_{0} & \sim \ln \left(\frac{2}{\alpha \mu^{2} f_{0}}\right)-|y| ; \quad|y| \rightarrow \infty  \tag{26}\\
\mu U_{0} & \sim \mu \ln \left(\frac{2}{\alpha \mu^{2} f_{0}}\right), \quad \mu \ll\left|x-x_{0}\right| \ll 1 \tag{27}
\end{align*}
$$

On the other hand, we expand $G$ in Taylor series around $x=x_{0}$. We write

$$
\begin{array}{ll}
G\left(x, x_{0}\right) \sim G_{0}+\left(x-x_{0}\right) G_{0^{+}}^{\prime}, & 0<x-x_{0} \ll 1 \\
G\left(x, x_{0}\right) \sim G_{0}+\left(x-x_{0}\right) G_{0^{-}}^{\prime}, & 0<x_{0}-x \ll 1
\end{array}
$$

where

$$
\begin{align*}
G_{0} & =G\left(x_{0}, x_{0}\right)=\frac{d}{2}\left(\frac{\cosh \left(\frac{2 x_{0}}{d}\right)}{\sinh \left(\frac{2 L}{d}\right)}+\operatorname{coth} \frac{2 L}{d}\right)  \tag{28}\\
G_{0^{ \pm}}^{\prime} & =\left.\frac{\partial}{\partial x} G\left(x, x_{0}\right)\right|_{x=x_{0}^{ \pm}}=\frac{1}{2}\left(\frac{\sinh \left(\frac{2 x_{0}}{d}\right)}{\sinh \left(\frac{2 L}{d}\right)} \pm 1\right) \tag{29}
\end{align*}
$$

Substituting (28) and (27) into (24) we obtain an equation for $\mu$,

$$
\begin{equation*}
\mu \ln \left(\frac{2}{\alpha \mu^{2} f_{0}}\right)=d\left(\frac{\cosh \left(\frac{2 x_{0}}{d}\right)}{\sinh \left(\frac{2 L}{d}\right)}+\operatorname{coth} \frac{2 L}{d}\right) \tag{30}
\end{equation*}
$$

It remains to verify the consistency condition $\mu \ll 1$. We evaluate

$$
\int_{-L}^{L} f e^{u} d x \sim \int_{-\infty}^{\infty} \frac{V}{\alpha \mu^{2}} d y \sim \frac{2}{\alpha \mu}
$$

so that

$$
\begin{gather*}
\frac{1}{\alpha \mu^{2}} \sim \frac{p}{d^{2} 4}  \tag{31}\\
\mu \sim \frac{d}{\ln \left(\frac{p}{2 d^{2} f_{0}}\right)}\left(\frac{\cosh \left(\frac{2 x_{0}}{d}\right)}{\sinh \left(\frac{2 L}{d}\right)}+\operatorname{coth} \frac{2 L}{d}\right) \sim O\left(\frac{d}{\ln \left(p / d^{2}\right)}\right)
\end{gather*}
$$

In particular this equation is consistent provided that either $p \gg 1$ or $d \ll 1$ (with other parameters being $O(1)$.).

Step 2: Hot spot location. The equation for the location $x_{0}$ is determined at a higher order. We have

$$
\begin{equation*}
U_{0}+\mu U_{1}=\ln \left\{\frac{V_{0}}{\alpha \mu^{2} f_{0}} \frac{1+\mu \frac{V_{1}}{V_{0}}}{1+\mu \frac{y f_{0}^{\prime}}{f_{0}}}\right\}=\ln \frac{V_{0}}{\alpha \mu^{2} f_{0}}+\mu\left(\frac{V_{1}}{V_{0}}-y \frac{f_{0}^{\prime}}{f_{0}}\right) \tag{32}
\end{equation*}
$$

so that

$$
\begin{equation*}
V_{0}=\left.\mu^{2} \alpha f_{0} e^{U_{0}}\right|_{-\infty} ^{\infty} ; \quad V_{1}=\left(U_{1}+y \frac{f_{0}^{\prime}}{f_{0}}\right) V_{0} \tag{33}
\end{equation*}
$$

and the first two orders in the inner variables are

$$
\begin{array}{r}
U_{0 y y}+V_{0}=0 \\
U_{1 y y}+V_{0} U_{1}+V_{0} y \frac{f_{0}^{\prime}}{f_{0}}=0 \tag{35}
\end{array}
$$

Multiply (35) by $U_{0 y}$ and integrate from $-\infty$ to $+\infty$. Integrating by parts we obtain

$$
\begin{equation*}
\int_{-\infty}^{\infty} U_{1}\left(U_{0 y y y}+V_{0} U_{0 y}\right) d y+\frac{f_{0}^{\prime}}{f_{0}} \int_{-\infty}^{\infty} y V_{0} U_{0 y} d y+\left.\left(U_{1 y} U_{0 y}-U_{1} U_{0 y y}\right)\right|_{-\infty} ^{\infty}=0 \tag{36}
\end{equation*}
$$

Note that

$$
V_{0 y}=V_{0} U_{0 y} ; \quad U_{0 y y}+V_{0 y}=0
$$

so that

$$
\begin{equation*}
\int_{-\infty}^{\infty} U_{1}\left(U_{0 y y y}+V_{0} U_{0 y}\right) d y=0 ; \quad \text { and } \quad \int_{-\infty}^{\infty} y V_{0} U_{0 y} d y=-\int_{-\infty}^{\infty} V_{0}=-2 \tag{37}
\end{equation*}
$$

To evaluate the boundary term, first note that for large $y$ we have

$$
U_{0 y} \rightarrow \mp 1, U_{0 y y} \rightarrow 0 \text { as } y \rightarrow \pm \infty
$$

The behaviour of $U_{1}$ for large $y$ is determined by matching to the outer solution. Recall that

$$
U_{0}(y)+\mu U_{1}(y) \sim \frac{2}{\mu} G\left(x, x_{0}\right), \quad x \rightarrow x_{0},|y| \rightarrow \infty
$$

Writing the right hand side in terms of inner variables we have

$$
G\left(x, x_{0}\right)=G\left(x_{0}+\varepsilon y, x_{0}\right) \sim G_{0}+y \mu G_{0^{ \pm}}^{\prime}, \quad y \gtrless 0
$$

where $G_{0}$ and $G_{0^{ \pm}}^{\prime}$ are given by $(28,29)$. For large $|y|$ we then obtain

$$
\begin{aligned}
\mu U_{1}+y \sim 2 y G_{0^{+}}^{\prime}, & y \gg 1 \\
\mu U_{1}-y \sim 2 y G_{0^{-}}^{\prime}, & y \ll 1
\end{aligned}
$$

so that

$$
\begin{equation*}
\left.U_{1 y}\right|_{y= \pm \infty}=\frac{1}{\mu}\left(2 G_{0^{ \pm}}^{\prime} \mp 1\right) \tag{38}
\end{equation*}
$$

and finally,

$$
\begin{align*}
\left(U_{1 y} U_{0 y}-U_{1} U_{0 y y}\right)_{-\infty}^{\infty} & =-\frac{2}{\mu}\left(G_{0^{+}}^{\prime}+G_{0^{-}}^{\prime}\right) \\
& =-\frac{2}{\mu} \frac{\sinh \left(\frac{2 x_{0}}{d}\right)}{\sinh \left(\frac{2 L}{d}\right)} \tag{39}
\end{align*}
$$

Substituting (37) and (38) into (36) yields the equation for spike location,

$$
\begin{equation*}
\frac{\sinh \left(\frac{2 x_{0}}{d}\right)}{\sinh \left(\frac{2 L}{d}\right)}=-\mu \frac{f_{0}^{\prime}}{f_{0}} . \tag{40}
\end{equation*}
$$

This conlcudes the derivation of Principal Result 2.1.
Derivation of Principal Result 2.2. We now turn to the stability of the hot spot. In the inner region $y=\left(x-x_{0}\right) / \mu$ we expand the eigenfunction as

$$
\begin{equation*}
\phi(x)=\Phi_{0}(y)+\mu \Phi_{1}(y)+\cdots . \tag{41}
\end{equation*}
$$

Substituting (41), (18) and (20) into (16) we get at the leading order,

$$
\begin{equation*}
\Lambda \Phi_{0}=\Phi_{0 y y}+V_{0} \Phi_{0}-V_{0} \int_{-\infty}^{\infty} V_{0} \Phi_{0} d y \tag{42}
\end{equation*}
$$

where $\Lambda=\mu^{2} / d^{2} \lambda$; and $V_{0}$ is given in (20). Note that the spectrum of (42) admits a zero eigenvalue $\Lambda=0, \Phi_{0}=V_{0 y} / V_{0}$, which corresponds to translation invariance. It will be shown in Principal Result 4.1 that all non-zero eigenvalues of (42) are negative. In view of this, we need to only be concerned with the zero translational eigenvalue. Since it is zero at leading order, its stability is determined by considering the correction terms that arise due to the the outer region of (16) and the spatially inhomogeneous term $f(x)$. In the inner region, we estmate the eigenfunction by

$$
\begin{equation*}
\phi \sim u_{x} \sim \frac{V_{x}}{V} . \tag{43}
\end{equation*}
$$

The integral term then becomes

$$
\int_{-L}^{L} f e^{u} \phi d x \sim \int_{-\infty}^{\infty} \frac{V}{\alpha \mu^{2}}\left(\frac{V_{y}}{V}\right) d y=0
$$

To obtain a solvability condition, multiply (16) by $u_{x}$ and integrate. Upon integrating by parts we obtain

$$
\frac{\lambda}{d^{2}} \int_{-L}^{L} \phi u_{x} d x=-\left.u_{x x} \phi\right|_{-L} ^{L}-\int_{-L}^{L} \alpha f^{\prime} e^{u} \phi d x
$$

In the outer region for $u$ and $\phi$ we have

$$
\begin{aligned}
\frac{\lambda}{d^{2}} \phi & \sim \phi_{x x}-\frac{1}{d^{2}} \phi, \quad x \neq x_{0} ; \\
0 & \sim u_{x x x}-\frac{1}{d^{2}} u_{x}, \quad x \neq x_{0} .
\end{aligned}
$$

Let $D=[-L, L] \backslash\left\{x_{0}\right\}$. We have:

$$
\begin{aligned}
\int_{D}\left(\phi_{x x}-\frac{1}{d^{2}} \phi-\frac{\lambda}{d^{2}} \phi\right) u_{x} d x & \left.\sim\left(u_{x} \phi_{x}-u_{x x} \phi\right)\right|_{-L} ^{x_{0}^{-}}+\left.\left(u_{x} \phi_{x}-u_{x x} \phi\right)\right|_{x_{0}^{+}} ^{L}-\int_{-L}^{L} \frac{\lambda}{d^{2}} \phi u_{x} d x \\
& \sim-\left.u_{x x} \phi\right|_{-L} ^{L}-\int_{-L}^{L} \frac{\lambda}{d^{2}} \phi u_{x} d x-\left.\left(u_{x} \phi_{x}-u_{x x} \phi\right)\right|_{x_{0}^{+}} ^{x_{0}^{-}}=0
\end{aligned}
$$

Therefore we obtain

$$
\begin{equation*}
-\left.\left(u_{x} \phi_{x}-u_{x x} \phi\right)\right|_{x_{0}^{-}} ^{x_{0}^{+}} \sim-\int_{-L}^{L} \alpha f^{\prime} e^{u} \phi d x \tag{44}
\end{equation*}
$$

Now in the outer region we have $u \sim C_{0} G\left(x, x_{0}\right)$. Let $G^{\lambda}$, $N^{\lambda}$ be the Green's functions satisfying

$$
\begin{array}{ll}
G_{x x}^{\lambda}-\frac{(1+\lambda)}{d^{2}} G^{\lambda}=-\delta\left(x-x_{0}\right) ; & G_{x}^{\lambda}( \pm L)=0 \\
N_{x x}^{\lambda}-\frac{(1+\lambda)}{d^{2}} N^{\lambda}=-\delta^{\prime}\left(x-x_{0}\right) ; & N_{x}^{\lambda}( \pm L)=0 \tag{46}
\end{array}
$$

By differentating (45) with respect to $x_{0}$, we obtain

$$
\begin{equation*}
N^{\lambda}=-\frac{\partial G^{\lambda}}{\partial x_{0}} \tag{47}
\end{equation*}
$$

Explicitly, we have

$$
\begin{aligned}
& G^{\lambda}\left(x, x_{0}\right)=\frac{1}{\omega \sinh (2 L \omega)}\left\{\begin{array}{cc}
\cosh ((x-L) \omega) \cosh \left(\left(x_{0}+L\right) \omega\right), & x>x_{0} \\
\cosh \left(\left(x_{0}-L\right) \omega\right) \cosh ((x+L) \omega), & x<x_{0}
\end{array}\right. \\
& N^{\lambda}\left(x, x_{0}\right)=\frac{-1}{\sinh (2 L \omega)} \begin{cases}\cosh ((x-L) \omega) \sinh \left(\left(x_{0}+L\right) \omega\right), & x>x_{0} \\
\sinh \left(\left(x_{0}-L\right) \omega\right) \cosh ((x+L) \omega), & x<x_{0}\end{cases} \\
& \text { where } \omega=\frac{\sqrt{1+\lambda}}{d}
\end{aligned}
$$

Matching the inner and outer region, we have $\phi \sim u_{x} \sim C_{0} G_{x}$ where $C_{0}$ is given by (23). Thus $\phi$ has a jump discontinuity $\left.\phi\right|_{x=x_{0}^{-}} ^{x=x_{0}^{+}} \sim-C_{0}$. On the other hand, $N^{\lambda}$ has a jump discontinuity of -1 at $x_{0},\left.\quad N^{\lambda}\right|_{x=x_{0}^{-}} ^{x=x_{0}^{+}}=-1$. Therefore in the outer region we get $\phi \sim C_{0} N^{\lambda}\left(x, x_{0}\right)$. We then obtain

$$
\begin{equation*}
\left(u_{x} \phi_{x}-u_{x x} \phi\right)_{x_{0}^{-}}^{x_{0}^{+}} \sim-C_{0}^{2}\left(\left.G_{x} N_{x}^{\lambda}\right|_{x^{-}} ^{x^{+}}-\left.\frac{1}{d^{2}} G N^{\lambda}\right|_{x^{-}} ^{x^{+}}\right) \tag{48}
\end{equation*}
$$

Now $N_{x}^{\lambda}$ is continuous at $x_{0}$ whereas $G_{x}$ has a jump discontinuity of -1 . Using (47) we then simplify

$$
\left.G_{x} N_{x}^{\lambda}\right|_{x^{-}} ^{x^{+}}=-\left.N_{x}^{\lambda}\right|_{x=x_{0}}=\left.G_{x_{0} x}^{\lambda}\right|_{x=x_{0}}
$$

and similarly

$$
\left.G N^{\lambda}\right|_{x^{-}} ^{x^{+}}=-\left.G\right|_{x=x_{0}}
$$

Therefore

$$
\begin{aligned}
&\left(u_{x} \phi_{x}-u_{x x} \phi\right)_{x_{0}^{-}}^{x_{0}^{+}} \sim-C_{0}^{2}\left(\left.G_{x_{0} x}^{\lambda}\right|_{x=x_{0}}+\left.\frac{1}{d^{2}} G\right|_{x=x_{0}}\right) . \\
&\left.G_{x_{0} x}^{\lambda}\right|_{x=x_{0}}=\frac{\omega \sinh \left(\left(x_{0}-L\right) \omega\right) \sinh \left(\left(x_{0}+L\right) \omega\right)}{\sinh (2 L \omega)} \\
&=\frac{\omega\left(\cosh \left(2 x_{0} \omega\right)-\cosh (2 L \omega)\right)}{2 \sinh (2 L \omega)} ; \quad \omega=\frac{\sqrt{1+\lambda}}{d} ; \\
&\left.G\right|_{x=x_{0}}=\frac{\left(\cosh \left(2 x_{0} \omega_{0}\right)+\cosh \left(2 L \omega_{0}\right)\right)}{2 \omega_{0} \sinh \left(2 L \omega_{0}\right)} ; \quad \omega_{0}=\frac{1}{d}
\end{aligned}
$$

so that

$$
\left(u_{x} \phi_{x}-u_{x x} \phi\right)_{x_{0}^{-}}^{x_{0}^{+}}=\frac{-4}{\mu^{2}}\left(\frac{\omega\left(\cosh \left(2 x_{0} \omega\right)-\cosh (2 L \omega)\right)}{2 \sinh (2 L \omega)}+\frac{\omega_{0}\left(\cosh \left(2 x_{0} \omega_{0}\right)+\cosh \left(2 L \omega_{0}\right)\right)}{2 \sinh \left(2 L \omega_{0}\right)}\right) .
$$

Next we evaluate the the right hand side of (44). Using (43) and (19) we obtain

$$
\begin{aligned}
\int_{-L}^{L} \alpha f^{\prime} e^{u} \phi d x & \sim \frac{1}{\mu^{2}} \int_{-L}^{L} \frac{f^{\prime}}{f} V_{x} d x \sim \frac{-1}{\mu^{2}} \int_{-L}^{L}\left(\frac{f^{\prime}}{f}\right)_{x} V d x \\
& \sim-\frac{1}{\mu}\left(\frac{f_{0}^{\prime \prime}}{f_{0}}-\frac{f_{0}^{\prime 2}}{f_{0}^{2}}\right) \int_{-\infty}^{\infty} V_{0} d y \\
& \sim-\frac{2}{\mu}\left(\frac{f_{0}^{\prime \prime}}{f_{0}}-\frac{f_{0}^{\prime 2}}{f_{0}^{2}}\right)
\end{aligned}
$$

The full equation for the eigenvalue is therefore

$$
\begin{equation*}
\frac{\omega\left(\cosh \left(2 x_{0} \omega\right)-\cosh (2 L \omega)\right)}{\sinh (2 L \omega)}+\frac{\omega_{0}\left(\cosh \left(2 x_{0} \omega_{0}\right)+\cosh \left(2 L \omega_{0}\right)\right)}{\sinh \left(2 L \omega_{0}\right)} \sim-\mu\left(\frac{f_{0}^{\prime \prime}}{f_{0}}-\frac{f_{0}^{\prime 2}}{f_{0}^{2}}\right) \tag{49}
\end{equation*}
$$

where

$$
\omega=\frac{\sqrt{1+\lambda}}{d} ; \quad \omega_{0}=\frac{1}{d}
$$

From (40) it is clear that either $d / L \ll 1$ or else $x_{0} \sim 0$. In the latter case we get

$$
\begin{equation*}
-\sqrt{1+\lambda} \tanh \left(L \frac{\sqrt{1+\lambda}}{d}\right)+\operatorname{coth}\left(\frac{L}{d}\right) \sim 0 \tag{50}
\end{equation*}
$$

Now note that the left hand side is positive when $\lambda=0$, and goes to $-\infty$ as $\lambda \rightarrow \infty$. Therefore (50) has a positive solution $\lambda>0$. This shows the instability for the case 1 of Principal Result 2.2. For the former case, we we must have $\frac{L}{d} \ll 1 ; \quad \omega \sim \omega_{0}$ so that $\lambda \ll 1$. We then expand in $\lambda$ to obtain (17). This concludes the derivation.

## 3 Two-dimensions

The analysis in two dimensions is along the lines of the one dimensional case. However there are signficant differences and complications due to the logarithmic singularity of the fundamental solution to the laplacian in two dimensions. As a result, the scaling properties and stability range is very different from the one dimensional case.

As in one dimensions, we first construct the two dimensional steady state in the form of a hot spot, then study its stability. We first state the results for general domains; the location and stability of the spot involves the interaction of the Green's function and the electric field strength $f(x)$. At the end of the section, we study in more detail the special case of a disk domain with radially symmetric $f(x)=f(|x|)$.

Principal Result 3.1. Suppose that $d^{2} p \gg 1$, with other parameters of $O(1)$. Consider the steady state equation in two dimensions,

$$
\begin{align*}
0 & =\Delta u-\frac{1}{d^{2}} u+\alpha f(x) e^{u}, \quad x \in \Omega ; \quad \partial_{n} u=0, \quad x \in \partial \Omega  \tag{51}\\
\alpha & :=\frac{p e^{u}}{\left(d \int_{\Omega} f(x) e^{u}\right)^{2}} \tag{52}
\end{align*}
$$

Then (8) admits a hot-spot solution. It is concentrated at the location $x_{0}$ given by

$$
\begin{equation*}
8 \pi \nabla H_{0}+\frac{\nabla f\left(x_{0}\right)}{f\left(x_{0}\right)}=0 . \tag{53}
\end{equation*}
$$

where $\nabla H_{0}$ is the gradient of the regular part of the Green's function as defined by (66, 67, 70, 74). The constant $\alpha$, as defined in (52) is asymptotically given

$$
\begin{equation*}
\alpha \sim \frac{(8 \pi d)^{2}}{p} \tag{54}
\end{equation*}
$$

Inside the hot spot, the temperature profile has the shape

$$
u(x) \sim \ln \left\{\frac{8\left(1+R^{2}\right)^{-2}}{\alpha \mu^{2} f\left(x_{0}\right)}\right\}, \quad R=\left|x-x_{0}\right| / \mu ; \quad R=O(1)
$$

where $\mu \ll 1$ is the spatial extent of the hot spot, asymptotically given by

$$
\begin{equation*}
\mu \sim 8 \pi \exp \left(-2 \gamma+4 \pi H_{0}\right) d^{3} \sqrt{\frac{2 f_{0}}{p}} \tag{55}
\end{equation*}
$$

where $\gamma \approx 0.5772$ is Euler's constant. Away from the hot spot, the temperature profile has the shape

$$
\begin{equation*}
u \sim 8 \pi G\left(x, x_{0}\right), \quad\left|x-x_{0}\right| \gg O(\mu) \tag{56}
\end{equation*}
$$

where $G\left(x, x_{0}\right)$ is the Green's function defined in (66).
We remark that a formula similar to (53) was obtained for a Liouville equation in [15] using a related technique. Next we summarize the stability results.

Principal Result 3.2. Let $\sigma_{1}, \sigma_{2}$ be the two eigenvalues of the matrix $8 \pi M+F$, where $M$ and $F$ are defined in (98). Then the stability problem (83) admits two small eigenvalues given by

$$
\lambda \sim \frac{d^{2}}{2 \ln \mu^{-1}} \sigma_{i}, i=1,2
$$

All other eigenvalues are strictly negative.
Alternatively, let

$$
g\left(x_{0}\right)=4 \pi H\left(x_{0}, x_{0}\right)+\ln f\left(x_{0}\right)
$$

where $H, f$ is as in Principal Result 3.1. Then the location of the hot spot solution satisfies $\nabla g\left(x_{0}\right)=0$. Moreover the hot spot is stable if $x_{0}$ is a non-degenerate maximum of $g\left(x_{0}\right)$, i.e. if the hessian of $g$ at $x_{0}$ is definite negative. It is unstable if $x_{0}$ is either a non-degenerate saddle point or a non-degenerate minimum of $g$.

Derivation of Principal Result 3.1. As in one dimension, the derivation consists of two steps. We first derive the hot spot profile, then determine its location.

Step 1, hot spot profile. We expand near the inner region of the spike as

$$
\begin{align*}
x & =x_{0}+\mu y  \tag{57}\\
f(x) & =f_{0}+\mu y f_{0}^{\prime}+\cdots \quad \text { where } f_{0} \equiv f\left(x_{0}\right), \quad f_{0}^{\prime} \equiv \nabla f\left(x_{0}\right) ;  \tag{58}\\
u(x) & =U(y)=U_{0}(y)+\mu U_{1}(y)+\cdots \tag{59}
\end{align*}
$$

where $\mu \ll 1$ is a scale parameter to be determined later. For convenience we also let

$$
\begin{equation*}
U(y)=\ln \left\{\frac{V(y)}{\alpha \mu^{2} f\left(x_{0}+\mu y\right)}\right\} \tag{60}
\end{equation*}
$$

and expand

$$
\begin{equation*}
V=V_{0}+\mu V_{1}+\cdots \tag{61}
\end{equation*}
$$

The equation for $V_{0}$ is then

$$
\begin{equation*}
\Delta_{y} V_{0}-\frac{\left|\nabla_{y} V_{0}\right|^{2}}{V_{0}}+V_{0}^{2}=0 \tag{62}
\end{equation*}
$$

A radial solution is given by

$$
\begin{equation*}
V_{0}(y)=\frac{8}{\left(1+R^{2}\right)^{2}}, \quad R=|y| \tag{63}
\end{equation*}
$$

Note that (62) admits a scaling invariance $V_{0}=a^{-2} \hat{V}_{0} ; \quad y=a \hat{y}$. However we can set $a=1$ by an appropriate relabelling of $\mu$.

Next we consider the outer region. Assuming $\alpha \ll 1$ we estimate

$$
\begin{equation*}
\Delta u-\frac{1}{d^{2}} u=-C_{0} \delta\left(x-x_{0}\right) \tag{64}
\end{equation*}
$$

where $\delta$ is a delta function and the constant $C_{0}$ is given by

$$
\begin{equation*}
C_{0}=\int_{-L}^{L} \alpha f(x) e^{u} d x \sim 2 \pi \int_{-\infty}^{\infty} V_{0}(R) R d R \sim 8 \pi \tag{65}
\end{equation*}
$$

Now consider the modified Helmholtz G-function that satisfies

$$
\begin{equation*}
\Delta G-\frac{1}{d^{2}} G=-\delta\left(x-x_{0}\right), \quad x \in \Omega ; \quad \partial_{n} G=0, \quad x \in \partial \Omega \tag{66}
\end{equation*}
$$

Note that $G$ has a logarithmic singularity as $x \rightarrow x_{0}$. To match the inner and outer solution, decompose $G$ as

$$
\begin{equation*}
G=J\left(x, x_{0}\right)+H\left(x, x_{0}\right), \quad r=\left|x-x_{0}\right| \tag{67}
\end{equation*}
$$

where $J$ is the Green's function on the entire space satisfying

$$
\begin{equation*}
\Delta J-\frac{1}{d^{2}} J=-\delta\left(x-x_{0}\right), \quad x, x_{0} \in \mathbb{R}^{2} ; \quad J \rightarrow 0 \text { as }|x| \rightarrow \infty \tag{68}
\end{equation*}
$$

and $H=G-J$ satisfies

$$
\begin{equation*}
\Delta H-\frac{1}{d^{2}} H=0, \quad x \in \Omega ; \quad \partial_{n} H=-\partial_{n} J, \quad x \in \partial \Omega \tag{69}
\end{equation*}
$$

Explicitly, we have

$$
\begin{equation*}
J\left(x, x_{0}\right)=\frac{1}{2 \pi} K_{0}\left(\frac{r}{d}\right), \quad r=\left|x-x_{0}\right| \tag{70}
\end{equation*}
$$

where $K_{0}$ is the Bessel $K$ function of order zero. In the outer region we then obtain that the solution to (64) for $u$ is

$$
\begin{equation*}
u \sim 8 \pi G\left(x, x_{0}\right), \quad\left|x-x_{0}\right| \gg O(\mu) \tag{71}
\end{equation*}
$$

To match (71) to the inner solution (60), we expand

$$
\begin{align*}
J & \sim \frac{1}{2 \pi} \ln \frac{1}{r}+\frac{1}{2 \pi}(\ln (2 d)-\gamma)+O\left(r^{2} \ln r\right)  \tag{72}\\
H & \sim H_{0}+\left(x-x_{0}\right) \cdot \nabla H_{0} \tag{73}
\end{align*}
$$

where

$$
\begin{equation*}
H_{0}=H\left(x_{0}, x_{0}\right) ; \nabla H_{0}=\left.\nabla H\left(x, x_{0}\right)\right|_{x=x_{0}} \tag{74}
\end{equation*}
$$

Writing the outer (71) solution in terms of the inner variables we have

$$
\begin{gather*}
x-x_{0}=\mu y ; \quad R=|y| \\
u \sim 4 \ln \frac{1}{\mu}+4 \ln \frac{1}{R}+4(\ln (2 d)-\gamma)+8 \pi H_{0}+\mu 8 \pi y \cdot \nabla H_{0} \ldots ; \quad \mu \ll \mu R \ll 1 . \tag{75}
\end{gather*}
$$

Taking the limit $R \rightarrow \infty$ of the inner variables we obtain

$$
\begin{align*}
V_{0} & \sim \frac{8}{R^{4}}  \tag{76}\\
u & \sim 4 \ln \frac{1}{R}+2 \ln \frac{1}{\mu}+\ln \left(\frac{8}{\alpha f_{0}}\right) \tag{77}
\end{align*}
$$

Equating (75) and (77) we get, to leading order,

$$
\begin{gather*}
4 \ln \frac{1}{\mu}+4(\ln (2 d)-\gamma)+8 \pi H_{0} \sim 2 \ln \frac{1}{\mu}+\ln \left(\frac{8}{\alpha f_{0}}\right) \\
\mu \sim \exp \left(-2 \gamma+4 \pi H_{0}\right) d^{2} \sqrt{2 \alpha f_{0}} \tag{78}
\end{gather*}
$$

To determine the spatial extent of the spike in terms of $p$ we substitute (65) into (52) to obtain

$$
\begin{equation*}
\alpha \sim \frac{(8 \pi d)^{2}}{p} \tag{79}
\end{equation*}
$$

Substituting (79) into (78) yields (55).
Step 2, hot spot location. To determine the location of the hot spot, we consider the $O(\mu)$ correction terms to the steady state. From (61) and (59) we have

$$
\begin{align*}
& 0=\Delta U_{0}+V_{0}  \tag{80}\\
& 0=\Delta U_{1}+V_{0} U_{1}+V_{0} y \cdot \frac{\nabla f_{0}}{f_{0}} \tag{81}
\end{align*}
$$

In addition we have

$$
\Delta U_{0 y_{j}}+V_{0 y_{j}}=0 ; \quad V_{0 y_{j}}=V_{0} U_{0 y_{j}}
$$

where $*_{y_{j}}$ denotes the derivative with respect to $y_{j}, j=1,2$. Let $B$ be a ball of a large radius $R \rightarrow \infty$. Multiply (81) by $U_{0 j}$ and integrate over $B$. Integrating by parts we obtain

$$
0=\int_{\partial B}\left(U_{0 y_{j}} \partial_{n} U_{1}-\partial_{n} U_{0 y_{j}} U_{1}\right) d S(y)+\int_{B} U_{0 y_{j}} V_{0} y \cdot \frac{\nabla f_{0}}{f_{0}} d y, \quad j=1,2
$$

First consider first the case $j=1$. To evaluate the boundary terms, note that the behaviour of $U$ for large $|y|$ is obtained by taking the limit of the outer expansion for small $x$. From (75) we obtain

$$
\begin{aligned}
U_{0} & \sim-4 \ln R+O(1) ; \quad U_{1} \sim 8 \pi R(\cos \theta, \sin \theta) \cdot \nabla H_{0} ; \quad R \rightarrow \infty \\
U_{0 y_{1}} & \sim-\frac{4}{R} \cos \theta ; \quad \partial_{n} U_{0 y_{1}} \sim \frac{4}{R^{2}} \cos \theta \\
\partial_{n} U_{1} & \sim 8 \pi(\cos \theta, \sin \theta) \cdot \nabla H_{0}
\end{aligned}
$$

$$
\begin{aligned}
\int_{\partial B}\left(U_{0 y_{1}} \partial_{n} U_{1}-\partial_{n} U_{0 y_{1}} U_{1}\right) d S(y) & \sim 2 \int_{0}^{2 \pi}-4 \cos \theta 8 \pi(\cos \theta, \sin \theta) \cdot \nabla H_{0} d \theta \\
& \sim-64 \pi^{2} e_{1} \cdot \nabla H_{0}
\end{aligned}
$$

Finally we have

$$
\int_{B} U_{0 y_{1}} V_{0} y \cdot \frac{\nabla f_{0}}{f_{0}} d y \sim \int_{\mathbb{R}^{2}} V_{0 y_{1}} y \cdot \frac{\nabla f_{0}}{f_{0}} d y \sim-8 \pi \frac{e_{1} \cdot \nabla f_{0}}{f_{0}}
$$

Performing the same computation with $j=2$ we finally obtain

$$
\begin{equation*}
8 \pi \nabla H_{0}+\frac{\nabla f_{0}}{f_{0}}=0 \tag{82}
\end{equation*}
$$

Stability in 2D As in one dimension, we linearize

$$
u(x, t)=u(x)+e^{\lambda t} \phi(x)
$$

to obtain

$$
\begin{equation*}
\frac{\lambda}{d^{2}} \phi=\Delta \phi-\frac{1}{d^{2}} \phi+\alpha f(x) e^{u} \phi-2 \alpha^{3 / 2} p^{-1 / 2} d^{-1} f(x) e^{u} \int_{\Omega} f(x) e^{u} \phi d x \tag{83}
\end{equation*}
$$

First we consider the small eigenvalue corresponding to the translation invariance of the inner problem. In the inner region, the eigenfunction has the form

$$
\begin{align*}
\phi & =c_{1} \frac{V_{x_{1}}}{V}+c_{2} \frac{V_{x_{2}}}{V}  \tag{84}\\
& \sim c_{1} u_{x_{1}}+c_{2} u_{x_{2}} \tag{85}
\end{align*}
$$

The constants $\left(c_{1}, c_{2}\right)$ indicate the direction of the instability. They will be determined at the same time as the eigenvalue. As in one dimension, the nonlocal term in (83) is of lower order due to the odd parity of the integrand:

$$
\int_{\Omega} f e^{u} \phi d x \sim \int_{\mathbb{R}^{2}} \frac{V}{\alpha \mu^{2}}\left(\frac{c_{1} V_{x_{1}}+c_{2} V_{x_{2}}}{V}\right) d x=0
$$

There are now two solvability conditions to consider, corresponding to two undetermined constants $c_{1}, c_{2}$. Multiply (83) by $u_{x_{j}}, j=1,2$ and integrate by parts. We obtain

$$
\frac{\lambda}{d^{2}} \int_{\Omega} \phi u_{x_{j}} d x \sim \int_{\partial \Omega}\left(u_{x_{j}} \partial_{n} \phi-\phi \partial_{n} u_{x_{j}}\right) d S(x)+\int_{\Omega} \phi\left(\Delta u_{x_{j}}-\frac{1}{d^{2}} u_{x_{j}}+\alpha f(x) e^{u} u_{x_{j}}\right) d x
$$

Note that

$$
\Delta u_{x_{j}}-\frac{1}{d^{2}} u_{x_{j}}+\alpha f(x) e^{u} u_{x_{j}}=-\alpha f_{x_{j}} e^{u}
$$

so that

$$
\begin{equation*}
\frac{\lambda}{d^{2}} \int_{\Omega} \phi u_{x} d x \sim-\int_{\partial \Omega} \phi \partial_{n} u_{x_{j}} d S(x)-\int_{\Omega} \phi \alpha f_{x_{j}} e^{u} d x \tag{86}
\end{equation*}
$$

Now away from the center of the spike we have

$$
\begin{equation*}
\Delta \phi \sim \frac{1+\lambda}{d^{2}} \phi ; \quad \Delta u_{x_{j}} \sim \frac{1}{d^{2}} u_{x_{j}}, \quad x \neq x_{0} \tag{87}
\end{equation*}
$$

Now consider a domain $D=\Omega \backslash B_{\delta}\left(x_{0}\right)$ where $B_{\delta}\left(x_{0}\right)$ is a ball of small radius $\delta$ centered around $x_{0}$; with $\mu \ll \delta \ll 1$. We obtain:

$$
\begin{align*}
& 0=\int_{D}\left(\Delta \phi-\frac{1+\lambda}{d^{2}} \phi\right) u_{x_{j}} d x=\int_{\partial \Omega \backslash B_{\delta}\left(x_{0}\right)}\left(u_{x_{j}} \partial_{n} \phi-\phi \partial_{n} u_{x_{j}}\right) d S(x)-\int_{\Omega \backslash B_{\delta}\left(x_{0}\right)} \frac{\lambda}{d^{2}} \phi u_{x_{j}} d x  \tag{88}\\
& \int_{\partial \Omega} \phi \partial_{n} u_{x_{j}} d S(x)+\int_{\Omega} \frac{\lambda}{d^{2}} \phi u_{x_{j}} d x \sim \int_{B_{\delta}\left(x_{0}\right)} \frac{\lambda}{d^{2}} \phi u_{x_{j}} d x-\int_{\partial B_{\delta}\left(x_{0}\right)}\left(u_{x_{j}} \partial_{n} \phi-\phi \partial_{n} u_{x_{j}}\right) d S(x) \tag{89}
\end{align*}
$$

Substituting (89) into (86) we obtain

$$
\begin{equation*}
\int_{\partial B_{\delta}\left(x_{0}\right)}\left(u_{x_{j}} \partial_{n} \phi-\phi \partial_{n} u_{x_{j}}\right) d S(x)-\int_{B_{\delta}\left(x_{0}\right)} \frac{\lambda}{d^{2}} \phi u_{x_{j}} d x \sim \int_{\Omega} \phi \alpha f_{x_{j}} e^{u} d x \tag{90}
\end{equation*}
$$

Next we evaluate the left hand side. Recall that

$$
u \sim-4 \ln R, \quad R=|y|=|x-z| / \mu, \quad 1 \ll R \ll \frac{1}{\mu}
$$

so that in the intermediate region, the leading order behaviour is

$$
\begin{equation*}
\phi \sim c_{1} u_{x_{1}}+c_{2} u_{x_{2}} \sim \frac{-4}{r}\left(c_{1} \cos \theta+c_{2} \sin \theta\right) ; \quad \mu \ll r \ll 1 \tag{91}
\end{equation*}
$$

where $r=|x-z|$. Therefore $\phi$ solves (87) subject to singularity condition (91) as $r=\left|x-x_{0}\right| \rightarrow 0$. Now let $G^{\lambda}$ be the Green's function satisfying

$$
\begin{equation*}
\Delta G^{\lambda}-\omega^{2} G^{\lambda}=-\delta(x-z), \quad x \in \Omega ; \quad \partial_{n} G=0, \quad x \in \partial \Omega ; \quad \omega^{2}:=\frac{1+\lambda}{d^{2}} \tag{92}
\end{equation*}
$$

Note that $G^{\lambda}(x, z) \sim-\frac{1}{2 \pi} \ln r$ as $r \rightarrow 0$. It follows that $G_{z_{1}}^{\lambda} \sim \frac{1}{2 \pi} \frac{\cos \theta}{r} ; G_{z_{2}}^{\lambda} \sim \frac{1}{2 \pi} \frac{\sin \theta}{r}$. By matching with (91) we obtain the following behaviour of $\phi$ in the outer region:

$$
\phi \sim-8 \pi\left(c_{1} G_{z_{1}}^{\lambda}+c_{2} G_{z_{2}}^{\lambda}\right), \quad r=O(1)
$$

Next we decompose $G^{\lambda}$ into singular and regular part as in (67). We will need to keep terms up to $O\left(r^{2}\right)$. For reference, note that

$$
K_{0}(r) \sim-\ln r+a_{0}+\frac{r^{2}}{4}\left(-\ln r+a_{0}\right)+O\left(r^{4} \ln r\right) ; \quad r \rightarrow 0, \quad \text { with } a_{0}=\ln 2-\gamma
$$

where $K_{0}$ is the Bessel K function so that
$G^{\lambda} \sim \frac{1}{2 \pi}\left(-\ln r+a_{0}-\ln \omega-\frac{\omega^{2}}{4} r^{2} \ln r+O\left(r^{2}\right)\right)+H^{\lambda}(x, z) \quad$ as $\quad z \rightarrow x, \quad \omega=\sqrt{\frac{1+\lambda}{d^{2}}} ; \quad r=|x-z|$. where $H^{\lambda}(x, z)$ is a $C^{2}$ function given by (69) with $\frac{1}{d^{2}}$ replaced by $\omega^{2}=\frac{1+\lambda}{d^{2}}$. In the intermediate region we then obtain

$$
\phi \sim-8 \pi\binom{-\left(c_{1} \frac{\cos \theta}{2 \pi}+c_{2} \frac{\sin \theta}{2 \pi}\right) g(r, \omega)}{+c_{1} H_{z_{1}}^{\lambda}+c_{2} H_{z_{2}}^{\lambda}}, \quad \mu \ll r \ll 1
$$

where

$$
g(r, \omega)=-\frac{1}{r}+\frac{\omega^{2}}{4}\left(2 r\left(-\ln r+a_{0}-\ln \omega\right)-r\right)
$$

Similarly for $\mu \ll r \ll 1$ we have

$$
\begin{aligned}
& u_{x_{1}} \sim 8 \pi\left[\frac{\cos \theta}{2 \pi} g\left(r, \omega_{0}\right)+H_{x_{1}}\right], \quad \omega_{0}=\frac{1}{d} \\
& u_{x_{2}} \sim 8 \pi\left[\frac{\sin \theta}{2 \pi} g\left(r, \omega_{0}\right)+H_{x_{2}}\right]
\end{aligned}
$$

Next we compute

$$
\partial_{n} \phi \sim-8 \pi\binom{c_{1}\left(H_{z_{1} x_{1}}^{\lambda} \cos \theta+H_{z_{1} x_{2}}^{\lambda} \sin \theta\right)+c_{2}\left(H_{z_{2} x_{1}}^{\lambda} \cos \theta+H_{z_{2} x_{2}}^{\lambda} \sin \theta\right)}{-\left(c_{1} \frac{\cos \theta}{2 \pi}+c_{2} \frac{\sin \theta}{2 \pi}\right) g_{r}(r, \omega)}
$$

$$
\begin{aligned}
& \partial_{n} u_{x_{1}} \sim 8 \pi\left[\frac{\cos \theta}{2 \pi} g_{r}\left(r, \omega_{0}\right)+\left(H_{x_{1} x_{1}} \cos \theta+H_{x_{1} x_{2}} \sin \theta\right)\right] \\
& \partial_{n} u_{x_{2}} \sim 8 \pi\left[\frac{\sin \theta}{2 \pi} g_{r}\left(r, \omega_{0}\right)+\left(H_{x_{2} x_{1}} \cos \theta+H_{x_{2} x_{2}} \sin \theta\right)\right]
\end{aligned}
$$

Now note that

$$
\begin{aligned}
& g(r, w) \sim-\frac{1}{r}-\frac{\omega^{2}}{2} r \ln r+O(r) \\
& g_{r}(r, w)=\frac{1}{r^{2}}-\frac{\omega^{2}}{2} \ln r+O(1)
\end{aligned}
$$

It will be evident later on that $\lambda=O\left(1 / \ln \mu^{-1}\right) \ll 1$. Therefore we have $\omega^{2}-\omega_{0}^{2} \sim \frac{\lambda}{d^{2}}$;

$$
g\left(r, \omega_{0}\right) g_{r}(r, \omega)-g(r, \omega) g_{r}\left(r, \omega_{0}\right) \sim \frac{1}{r}\left[\frac{\lambda}{d^{2}} \ln r+O(\lambda)+O(r)\right], \quad \lambda, r \rightarrow 0
$$

Keeping in mind that $\lambda$ is small we then obtain,

$$
\begin{align*}
& \int_{\partial B_{\delta}\left(x_{0}\right)}\left(u_{x_{1}} \partial_{n} \phi-\phi \partial_{n} u_{x_{1}}\right) d x \sim(8 \pi)^{2}\left(c_{1}\left(H_{z_{1} x_{1}}+H_{x_{1} x_{1}}\right)+c_{2}\left(H_{z_{2} x_{1}}+H_{x_{2} x_{1}}\right)\right)+16 \pi c_{1} \frac{\lambda}{d^{2}} \ln \delta \\
& \int_{\partial B_{\delta}\left(x_{0}\right)}\left(u_{x_{2}} \partial_{n} \phi-\phi \partial_{n} u_{x 2}\right) d x \sim(8 \pi)^{2}\left(c_{1}\left(H_{z_{1} x_{2}}+H_{x_{2} x_{1}}\right)+c_{2}\left(H_{z_{2} x_{2}}+H_{x_{2} x_{2}}\right)\right)+16 \pi c_{2} \frac{\lambda}{d^{2}} \ln \delta \tag{93}
\end{align*}
$$

Next we evaluate $\int_{B_{\delta}\left(x_{0}\right)} \frac{\lambda}{d^{2}} \phi u_{x_{j}} d x$. The dominant contribution for this integral comes from the inner region. Therefore, using (63) we obtain

$$
\begin{equation*}
\frac{\lambda}{d^{2}} \int_{B_{\delta}\left(x_{0}\right)} \phi u_{x_{j}} d x \sim \frac{\lambda}{d^{2}} \int_{B_{\delta / \mu}(0)} c_{j} U_{y_{j}}^{2} d y \sim c_{j} \pi \frac{\lambda}{d^{2}} \int_{0}^{\delta / \mu}\left(\frac{-4 R}{1+R^{2}}\right)^{2} R d R \sim 16 \pi c_{j} \frac{\lambda}{d^{2}}(\ln \delta-\ln \mu)+O(1) \tag{95}
\end{equation*}
$$

Note that the $\ln \delta$ term in (95) cancels precisely with the $\ln \delta$ term in $(93,94)$ so that the left hand side of (90) is indeed independent of $\delta$. Next we evaluate $\int_{\Omega} \phi \alpha f_{x_{j}} e^{u} d x$. Using (60) and (84) we obtain

$$
\begin{align*}
\int_{\Omega} \phi \alpha e^{u} f_{x_{j}} d x & \sim \frac{1}{\mu^{2}} \int_{\Omega} \sum_{i=1}^{2} c_{i}(V)_{x_{i}}\left(\frac{f_{x_{j}}}{f}\right) d x \\
& \sim-\frac{1}{\mu^{2}} \int_{\Omega} \sum_{i=1}^{2} c_{i}\left(\frac{f_{x_{j}}}{f}\right)_{x_{i}} V d x  \tag{96}\\
& \sim-\left.8 \pi \sum_{i=1}^{2} c_{i}\left(\frac{f_{x_{j}}}{f}\right)_{x_{i}}\right|_{x=x_{0}}
\end{align*}
$$

Substituting $(93,94),(95)$ and (96) into (90) we obtain the following equation for $\lambda$ :

$$
\begin{equation*}
(8 \pi M+F)\binom{c_{1}}{c_{2}}=\lambda\left(\frac{2}{d^{2}} \ln \mu^{-1}\right)\binom{c_{1}}{c_{2}} \tag{97}
\end{equation*}
$$

where

$$
M=\left.\left[\begin{array}{cc}
H_{z_{1} x_{1}}+H_{x_{1} x_{1}} & H_{z_{2} x_{1}}+H_{x_{2} x_{1}}  \tag{98}\\
H_{z_{1} x_{2}}+H_{x_{2} x_{1}} & +H_{z_{2} x_{2}}+H_{x_{2} x_{2}}
\end{array}\right]\right|_{x=x_{0}} ; \quad F=\left.\left[\begin{array}{cc}
\left(\frac{f_{x_{1}}}{f}\right)_{x_{1}} & \left(\frac{f_{x_{1}}}{f}\right)_{x_{2}} \\
\left(\frac{f_{x_{2}}}{f}\right)_{x_{1}} & \left(\frac{f_{x_{2}}}{f}\right)_{x 2}
\end{array}\right]\right|_{x=x_{0}}
$$



Figure 3: Comparison of numeric and asymptotic computations of the small eigenvalue $\lambda$ for a two dimensional disk domain of radius $L$. (a) The graph of $\lambda$ vs. $a$, where $f(x)=\exp \left(-a|x|^{2} / 2\right)$ and other parameters are $\alpha=0.00125, L=1.5, d=1$. The solid curve is the asymptotic approximation given by (100). The dots are obtained by numerically solving the eignevalue problem (83) using boundary value problem solver. (b) The threshold of stability $\lambda=0$ in two dimensions with $d=1$, $f(x)=\exp \left(-a|x|^{2} / 2\right)$ and $\alpha=0.005$. The solid curve is the asymptotic threshold given by $a=$ $2 K_{0}^{\prime \prime}(L) / I_{0}^{\prime \prime}(L)-2 K_{0}^{\prime}(L) / I_{0}^{\prime}(L)$. The dotted points are obtained by numerically solving the eignevalue problem (83) for $\lambda=\lambda(a)$, then using a root finder to solve for $\lambda=0$. The hot spot is unstable for parameter values below the curve and is stable for parameter values above the curve.

In particular, assuming that matrix $4 \pi M+F$ is $O(1)$, it follows that $\lambda=O\left(d^{2} / \ln \left(\mu^{-1}\right)\right) \ll 1$ since $\mu \ll 1$. Note that there are in general two small eigenvalues, corresponding to the two eigenvalues of the matrix $4 \pi M+F$. This concludes the derivation.

Disk domain. Next specialize the results of Principal Result 3.2 to a disk of of radius $L$, with a radially symmetric electric field strength $f(x)=f(|x|)$. The goal is derive the explicit instability threshold given in (4). We assume that the hot-spot is radially symmetric and is located at the center of the disk. In this case, the expressions in (98) can be significantly simplified as follows. First note that when $z=0$, the solution $G$ to (66) can be explicitly written as

$$
\begin{gathered}
\left.G(x, z)\right|_{z=0}=\frac{1}{2 \pi}\left(K_{0}(\omega r)-\frac{K_{0}^{\prime}(\omega L)}{I_{0}^{\prime}(\omega L)} I_{0}(\omega r)\right), \quad r=|x| ; \quad \omega=\frac{1}{d} . \\
\left.H(x, z)\right|_{z=0}=-\frac{1}{2 \pi}\left(\frac{K_{0}^{\prime}(\omega L)}{I_{0}^{\prime}(\omega L)}\right) .
\end{gathered}
$$

On the other hand, let $v(x)=\left.G_{z_{1}}(x, z)\right|_{z=0}$. Now we have $2 \pi G \sim-\ln (|x-z|)$ as $x \rightarrow z$ so that
$\left.2 \pi G_{z_{1}}\right|_{z=0} \sim \frac{\cos \theta}{r}, r=|x| \rightarrow 0$. It follows that $v$ solves

$$
\begin{aligned}
\Delta v-\omega^{2} v & =0, \quad x \in B_{L}(0) \\
v & \sim \frac{\cos \theta}{2 \pi r}, \quad r=|x| \rightarrow 0 \\
\partial_{n} v & =0, \quad r=L
\end{aligned}
$$

Thus we obtain that $v(x)=(\cos \theta) J(r)$ where $J(r)$ solves the ODE

$$
\begin{equation*}
J_{r r}+\frac{1}{r} J_{r}-\frac{1}{r^{2}} J-\omega^{2} J=0 \tag{99}
\end{equation*}
$$

subject to boundary conditions

$$
J^{\prime}(L)=0 ; \quad J(r) \sim \frac{1}{2 \pi r} \text { as } r \rightarrow 0
$$

The particular solutions to (99) are given by $K_{0}^{\prime}(r \omega), \quad I_{0}^{\prime}(r \omega)$, with $K_{0}^{\prime}(r \omega) \sim \frac{-1}{\omega r}$ so that we get

$$
J(r)=-\frac{\omega}{2 \pi}\left(K_{0}^{\prime}(r \omega)-\frac{K_{0}^{\prime \prime}(\omega L)}{I_{0}^{\prime \prime}(\omega L)} I_{0}^{\prime}(r \omega)\right)
$$

Therefore we obtain

$$
\begin{aligned}
& H_{x_{1}}=-\frac{\omega}{2 \pi} \frac{K_{0}^{\prime}(\omega L)}{I_{0}^{\prime}(\omega L)}\left(I_{0}^{\prime}(\omega r)\right)(\cos \theta) \\
& H_{z_{1}}=\frac{\omega}{2 \pi} \frac{K_{0}^{\prime \prime}(\omega L)}{I_{0}^{\prime \prime}(\omega L)}\left(I_{0}^{\prime}(r \omega)\right)(\cos \theta)
\end{aligned}
$$

We compute further,

$$
\begin{aligned}
\left(H_{x_{1} x_{1}}\right)_{r=0} & =\left(\left(H_{x_{1}}\right)_{r} \cos \theta-\frac{1}{r}\left(H_{x_{1}}\right)_{\theta} \sin \theta\right)_{r=0} \\
& =-\frac{\omega}{2 \pi} \frac{K_{0}^{\prime}(\omega L)}{I_{0}^{\prime}(\omega L)}\left(\omega I_{0}^{\prime \prime}(\omega r) \cos ^{2} \theta+\frac{1}{r} I_{0}^{\prime}(\omega r) \sin ^{2} \theta\right)_{r=0} \\
& =-\frac{\omega^{2}}{4 \pi} \frac{K_{0}^{\prime}(\omega L)}{I_{0}^{\prime}(\omega L)}
\end{aligned}
$$

(where we have used the Taylor series expansion $I_{0}(t) \sim 1+t^{2} / 4, t \rightarrow 0$ ) and in the same way,

$$
\left(H_{z_{1} x_{1}}\right)_{r=0}=\frac{\omega^{2}}{4 \pi} \frac{K_{0}^{\prime \prime}(\omega L)}{I_{0}^{\prime \prime}(\omega L)}
$$

Similarly,

$$
\begin{aligned}
\left(H_{z_{1} x_{1}}\right)_{r=0} & =\left(\left(H_{z_{1}}\right)_{r} \sin \theta+\frac{1}{r}\left(H_{z_{1}}\right)_{\theta} \cos \theta\right)_{r=0} \\
& =0 \\
\left(H_{z_{1} x_{1}}\right)_{r=0} & =0
\end{aligned}
$$

so that

$$
H_{z_{1} x_{1}}+H_{x_{1} x_{1}}=\frac{\omega_{0}^{2}}{4 \pi}\left(\frac{K_{0}^{\prime \prime}\left(\omega_{0} L\right)}{I_{0}^{\prime \prime}\left(\omega_{0} L\right)}-\frac{K_{0}^{\prime}\left(\omega_{0} L\right)}{I_{0}^{\prime}\left(\omega_{0} L\right)}\right)
$$

The expressions involving $z_{2}$ in (98) are evaluated in the same way. Finally, for a radially symmetric function $f(x)=f(r)$ we obtain:

$$
\begin{aligned}
& {\left[\left(\frac{f_{x_{1}}}{f}\right)_{x_{1}}\right]_{x=0}=\left[\left(\frac{f_{x_{2}}}{f}\right)_{x_{2}}\right]_{x=0}=\left(\frac{f^{\prime}(r)}{f(r)}\right)_{r=0}^{\prime}=\frac{f^{\prime \prime}(0)}{f(0)}} \\
& {\left[\left(\frac{f_{x_{2}}}{f}\right)_{x_{1}}\right]_{x=0}=\left[\left(\frac{f_{x_{2}}}{f}\right)_{x_{1}}\right]_{x=0}=0}
\end{aligned}
$$

Thus we obtain

$$
\begin{equation*}
\lambda \sim \frac{1}{\ln \mu^{-1}}\left\{\left(\frac{K_{0}^{\prime \prime}(L / d)}{I_{0}^{\prime \prime}(L / d)}-\frac{K_{0}^{\prime}(L / d)}{I_{0}^{\prime}(L / d)}\right)+\frac{d^{2}}{2} \frac{f^{\prime \prime}(0)}{f(0)}\right\} \tag{100}
\end{equation*}
$$

Using Van-Dyke matching, we obtain the following simple uniform solution on a disk of radius $L$,

$$
\begin{equation*}
u_{\mathrm{unif}} \sim 4\left(K_{0}(r / d)-\frac{K_{0}^{\prime}(L / d)}{I_{0}^{\prime}(L / d)} I_{0}(r / d)\right)-2 \ln \left(1+(r / \mu)^{2}\right) \tag{101}
\end{equation*}
$$

where $\mu$ is given by Principal Result 3.1.

## 4 Large eigenvalues, single spot

To conclude the stability analysis of a single hot spot, we now prove the stability with respect to the large eigenvalues in one and two dimensions. The proof for one dimension has appeared elsewhere, see for example [11] or [4]. We include it here for completeness. Here, we follow [11]. In two dimensions, the situation is slightly more complicated because of the presence of a scaling invariance, which yields an extra zero eigenvalue.

We start by studying the local operator

$$
\begin{equation*}
L_{0} \Phi=\Delta \Phi+V_{0} \Phi \tag{102}
\end{equation*}
$$

where $V_{0}$ is given by (20) in one dimension or by (62) in two dimensions. We have the following characterization of the non-negative spectrum of (102):

Lemma 4.1. Consider the local eigenvalue problem on all of $\mathbb{R}^{n}$,

$$
\begin{equation*}
L_{0} \Phi=\Lambda \Phi ; \quad|\Phi(y)| \text { is bounded as }|y| \rightarrow \infty \tag{103}
\end{equation*}
$$

with $n=1$ or $n=2$. It admits a single strictly positive eigenvalue $\Lambda=\Lambda_{0}>0$ corresponding to a positive eigenfunction. In $\mathbb{R}^{1}$, (103) admits one zero eigenvalue; the corresponding eigenfunction is due to translation invariance and is given by

$$
Z_{1}=\left(\frac{\partial}{\partial y} V_{0}(y)\right) / V_{0}
$$

In $\mathbb{R}^{2}$, (103) admits three zero eigenvalues given by

$$
\begin{equation*}
Z_{1}=\cos \theta\left(\frac{\partial}{\partial R} V_{0}\right) / V_{0}, \quad Z_{2}=\sin \theta\left(\frac{\partial}{\partial R} V_{0}\right) / V_{0}, \quad Z_{3}=2+R\left(\frac{\partial}{\partial R} V_{0}\right) / V_{0} \tag{104}
\end{equation*}
$$

where $R=|y|$. The first two are due to translation invariance and the third is due to the scaling invariance. All other eigenvalues are strictly negative.

Proof. We first note that $Z_{3}$ satisfies $L_{0} \Phi=0$ in both one and two dimensions. To see this, let $U=\ln \left(V_{0}\right)$ so that $U$ satisfies

$$
\begin{equation*}
\Delta U+e^{U}=0 \tag{105}
\end{equation*}
$$

This equation has a symmetry: if we write $U(R)=w\left(e^{\beta / 2} R\right)+\beta$ then $w(z)$ also satisfies (105). Therefore differentiating (105) with respect to $\beta$ and then setting $\beta=0$, we obtain that $Z_{3}=\partial U / \partial \beta$ satisfies $L_{0} \Phi=0$. In the same way, it is also easy to see that $Z_{1}$ and $Z_{2}$ correspond to translational invariance of (105). Now in one dimension, note that $Z_{3} \sim O(R)$ for large $R$, so it is not bounded at infinity. On the other hand, in two dimensions we have $Z_{3}=O(1)$ for large $R$, so $Z_{3}$ satisfies (103) in two dimensions but not in one dimension.

Next note that $Z_{1}$ has one root in one dimension. Therefore by oscillation theorem, there must be an eigenfunction that has no roots, and whose eigenvalue is positive. Moreover such an eigenfunction is unique, again by oscillation theorem. Similarly, in two dimensions, the eigenfunctions corresponding to the zero eigenvalue, $Z_{1}, Z_{2}, Z_{3}$ all have a single nodal line, which implies the existence of a unique strictly positive eigenvalue. It remains to prove that there are no other zero eigenvalues. In one dimension, this is true because the second order ODE $L_{0} \Phi=0$ has only two solutions $\left(Z_{1}\right.$ and $\left.Z_{3}\right)$ so by uniqueness of solution of an ODE, no other zero eigenfunctions can exist. In two dimensions, we decompose in polar coordinates, $\Phi(r, \theta)=\Phi(r)(A \cos m \theta+B \sin m \theta)$ where $m$ is an integer. When $m=0$ or $m=1$, there are exactly three solutions to $L_{0} \Phi=0$, given by $Z_{1}, Z_{2}, Z_{3}$, each having one nodal line. If $m>1$ then $\Phi$ has at least two nodal lines which correspond to roots of $A \cos m \theta+$ $B \sin m \theta=0$. But this implies that the corresponding eigenvalue $\lambda<0$ by the Oscillation theorem see for example [17], exercise 10 in $\S 11.6$.

Remark 1: Note that the inner eigenvalue problem (103) is somewhat nonstandard, as there is no linear decay-type term on the right hand side. As such, it has a continuous spectrum up to $\operatorname{Re}(\Lambda) \leq 0$. However the outer problem (16) or (83) does have a decay since the outer region away from the spike is of the form $\lambda \phi \sim d^{2} \Delta \phi-\phi$. Therefore any continuous spectrum must satisfy $\operatorname{Re}(\lambda) \leq-1$. As such, the presence of continuous spectrum does not affect the stability of the hot spot.

Remark 2: In one dimension, the unique positive eigenvalue of (103) is $\Lambda_{0}=1 / 4$; the corresponding eigenfunction is $\operatorname{sech}(y / 2)$. (see [11]). In two dimensions, we do not know an explicit formula but numerically we obtain $\Lambda_{0} \approx 2.545$.

Next consider the nonlocal problem

$$
\begin{equation*}
L_{0} \Phi-\gamma V_{0} \int_{\mathbb{R}^{n}} V_{0} \Phi d y=\Lambda \Phi ; \quad \Phi(y) \rightarrow 0 \text { as }|y| \rightarrow \infty \tag{106}
\end{equation*}
$$

Note that $L_{0} 1=V_{0}$ so that $\Phi=1$ is an eigenfunction of (106) corresponding to the zero eigenvalue whenever $\gamma=\gamma_{0}$ where

$$
\begin{equation*}
\gamma_{0}=\frac{1}{\int_{\mathbb{R}^{n}} V_{0} d y} \tag{107}
\end{equation*}
$$

Next we show the following
Principal Result 4.1. Consider the nonlocal eigenvalue problem (106). Suppose that $\gamma>\gamma_{0}$. Then the problem (106) has no strictly positive eigenvalues. The zero eigenspace is the same as that of a local problem (103) and is given in Lemma 4.1. On the other hand, if $\gamma<\gamma_{0}$ then there is a strictly positive eigenvalue of (106).

Proof. Given an eigenfunction $\Phi$ of (106), there are two cases to consider. Either $\int V_{0} \Phi$ is zero or not. In the former case, by Lemma $4.1, \Lambda \leq 0$. In the latter case, by scaling $\Phi$ appropriately, (106) becomes

$$
\gamma V_{0}=\left(L_{0}-\Lambda\right) \Phi ; \quad \int_{\mathbb{R}^{n}} V_{0} \Phi d y=1
$$

Define

$$
f(\Lambda)=\int_{\mathbb{R}^{n}} V_{0}\left(L_{0}-\Lambda\right)^{-1} V_{0} d y
$$

so that $\Lambda$ corresponds to the solution of $f(\Lambda)=1 / \gamma$. We now study the graph of $f(\Lambda)$. Using integration by parts we have

$$
f^{\prime}(\Lambda)=\int_{\mathbb{R}^{n}}\left(\left(L_{0}-\Lambda\right)^{-1} V_{0}\right)^{2} d y>0
$$

Also note that $f(0)=1 / \gamma$ and $f \rightarrow 0$ as as $\Lambda \rightarrow \infty$. Moreover $f(\Lambda)$ has a vertical asymptote near $\Lambda=\Lambda_{0}$, the positive eigenvalue of the local operator $L_{0}$. Since $\Lambda_{0}$ is the only strictly positive eigenvalue of $L_{0}, f(\Lambda)$ has no other singularities for $\Lambda>0$. This shows that $f(\Lambda)>\frac{1}{\gamma}$ on $\left(0, \Lambda_{0}\right)$ and $f(\Lambda)<0$ on $\left(\Lambda_{0}, \infty\right)$. So if $\gamma>\gamma_{0}$ then there are no solutions to $f(\Lambda)=\frac{1}{\gamma}$; on the other hand there is a solution $\Lambda \in\left(0, \Lambda_{0}\right)$ to $f(\Lambda)=\frac{1}{\gamma}$ if $\gamma<\gamma_{0}$.

Finally, it is easy to verify that $\int_{\mathbb{R}^{n}} V_{0} Z_{i} d y=0$ for $i=1$ (in $\mathbb{R}^{1}$ ) or $i=1,2,3$ (in $\mathbb{R}^{2}$ ). This shows that the null space of $L_{0}$ is also in the zero eigenspace of (106). On other hand if $\Phi$ an eigenfunction corresponding to a zero eigenvalue, then either $\int_{\mathbb{R}^{n}} V_{0} \Phi d y=0$ - in which case $\Phi$ is a linear combination of $Z_{i}$ - or else by choosing an appropriate rescaling we have

$$
L_{0} \Phi=V_{0}, \quad \gamma \int_{\mathbb{R}^{n}} V_{0} \Phi d y=1
$$

But then $\Phi=1$ and $\gamma=\gamma_{0}$. This completes the proof.
Principal Result 4.1 shows that the stability of the full problem (16 or 83) depends only on the stability of the small eigenvalues whose eigenfunctions in the inner region correspond to the kernel of $L_{0}$ as given in Lemma 4.1. Now in one dimension, this kernel consists of translational mode $Z_{1}$, whose instability was classified in Principal Result 2.2. In two dimensions, the kernel consists of two translation modes $Z_{1}, Z_{2}$ which were classified in Principal Result 3.2, and of a scaling eigenfunction $Z_{3}$. Now we note that $Z_{3} \sim$ const. as $R=\left|x-x_{0}\right| / \mu \rightarrow \infty$. On the other hand, in the outer region we have:

$$
d^{2} \Delta \phi-\phi \sim \lambda \phi, \quad\left|x-x_{0}\right| \gg O(\mu)
$$

with Neumann condition at the boundaries. To match with the inner region, $\phi$ must be bounded as $\left|x-x_{0}\right| \rightarrow 0$. But then we must have $\lambda \sim-1$, since $\phi \neq 0$. This shows that the eigenvalue corresponding to the scaling mode $Z_{3}$ is stable.

## 5 Non-singular solutions; two hot spots.

For some values of $p$, it is possible to construct non-singular perturbation solutions. To leading order, such solutions satisfy the differential equation (3) with $d$ set to 0 . In this case the leading order behaviour of the solution must satisfy the implicit relation

$$
\begin{equation*}
u=d^{2} \alpha f(x) e^{u} \tag{108}
\end{equation*}
$$

To determine the critical value of $p$ when such solutions exist, we consider the relation $u=\beta e^{u}$. This relation will have no solutions for $\beta>\frac{1}{e}$, one solution for $\beta=\frac{1}{e}$ and two solutions otherwise. Thus, to find the critical value of $p$, we solve for $u=\frac{f(x)}{M} e^{u-1}$, where $M=\max _{\Omega}|f(x)|$. We may then evaluate $\alpha$ as,

$$
\alpha=\frac{p}{\left(d \int_{\Omega} M e W\left(-\frac{f(x)}{M e}\right) d x\right)^{2}},
$$



Figure 4: Comparison of solution to (108) and the full numerical simulation of (3) on a unit disk. The electric field $f(x)$ is taken to be (110), $p=1.3$ and $d=0.05$. (a) Solution given by (108). (b) Full numerical simulation of (3) using FlexPDE. Initial conditions were taken to be a constant and the simulation quickly reached a steady state which is shown here.
where $W(x)$ is the principle branch of the Lambert W function. At the critical value of $p, \alpha=\frac{1}{d^{2} M e}$. We can then solve for the critical value of $p$ as

$$
\begin{equation*}
p_{c}=M e\left(\int_{\Omega} W\left(-\frac{f(x)}{M e}\right) d x\right)^{2}, \tag{109}
\end{equation*}
$$

For $p<p_{c}$, there will be two non-singular perturbation solutions. Since to leading order, the partial differential equation is reduced to an ordinary differential equation at each point $x$, it is evident that the smaller solution is stable and the larger unstable.

To illustrate the existence of such solutions, consider the two-dimensional unit disk with

$$
\begin{equation*}
f(x)=\cos (\theta)^{2} \mathrm{~J}_{1}\left(z_{1} r\right)^{2} \tag{110}
\end{equation*}
$$

where $z_{1}$ is the first root of $J_{1}(z)$ the Bessel function of the first kind of order 1 . Such an electric field results from using a $\mathrm{TM}_{111}$ wave guide with the wafer placed near the bottom of the cavity on pegs[14]. Using (110) we then compute from (109) that $p_{c} \sim 1.35$. Next we take $p=1.3$. Solving


Figure 5: A simulation of (3) with $p=0.14$. We use the $f$ and initial conditions as in (4).
(108) we then obtain 4(a). On the other hand, we used FlexPDE software [3] to simulate the full PDE (3). Using $d=0.01$ and a constant initial condition $u(x, 0)=0.1$, the solution quickly settles to a steady state which is shown in Figure $4(\mathrm{~b})$. It is seen to be in good agreement with the steady state given by (108).

If $p>p_{c}$, then the non-singular solutions will not exist. To illustrate this, we again consider $f(x)$ given by (110) but take $p=1.4>p_{c}=1.35$. We also took $d=0.01$ and the initial condition $u(x, 0)=0.1$. The resulting solution is shown on Figure 5 . Since $p$ is close to $p_{c}$, numerical simulation shows that initially, the solution resembles the non-singular solution of Figure 4. Such transient state then evolves into a solution that consists of two hot spots located near the maxima of $f(x)$. However this two hot-spot solution itself is unstable; one of the spots is quickly destroyed. Finally the resulting solution containing only one hot-spot appears to settle to a stable equilibrium.

The instability of two-spot solutions can be seen as follows. As discussed in $\S 4$ the spectrum of the local problem (103) contains an $O(1)$ positive eigenvalue $\Lambda_{0}$ with a strictly positive eigenfunction $Z_{0}$. Now consider $\phi=\frac{1}{f\left(x_{0}\right)} Z_{0}\left(\frac{\left|x-x_{0}\right|}{\epsilon}\right)-\frac{1}{f\left(x_{1}\right)} Z_{0}\left(\frac{\left|x-x_{1}\right|}{\epsilon}\right)$. Due to the symmetry of the solution and the localized nature of $Z_{0}$, the integral term of the nonlocal eigenvalue problem (106) will vanish, reducing it to the local eigenvalue problem (103). It follows that $\lambda>0$ is an eigenvalue of the two-spot configuration. This unstable eigenvalue is responsible for the competition-type instability observed in

Figure 5.

## 6 Discussion

For a homogeneous electric field $(f(x)=$ const.), it was shown in [9] that the hot spot exhibits a metastable behaviour, and slowly moves to the boundary of the domain [9]. On the other hand, for the case where the nonlinearity in (1) is $G(u)=u^{2}$, it was also shown in [9] that in the limit of small diffusivity, the one-dimensional hot-spot will concentrate at the maximum of $f(x)$. This is more complicated when the nonlinearity is exponential and the power $p$ is sufficiently large. In such a case, the position of the hot spot is determined by a combination of $f(x)$, the power $p$ and the domain geometry (see Principal Result 2.1). As Formula (6) shows, the hot-spot can lose its instability in the one-dimensional case even with $d \ll 1$, when $p$ is increased sufficiently so that

$$
p>d^{2} \exp \left(\frac{\left|f^{\prime \prime}(0)\right| d^{2}}{4 f(0)} \exp (2 L / d)\right)
$$

The two dimensional case is more difficult to analyse, due to the appearnce of the logarithmic singularity in the free-space Green's function. Unlike the one-dimensional case, the stability is independent of the power $p$, and the hot-spot will be stable provided that the diffusion $d \ll 1$ and $f(x)$ has an interior maximum. Moreover, two-dimensional hot-spot can be stable even when $d=O(1)$, provided that the relationship (4) holds. By contrast, the one dimensional hot-spot is unstable when $d=O(1)$, regardless of the shape of $f(x)$.

It is well known that scalar local reaction diffusion systems cannot give rise to stable hot-spot type solutions [2]. On the other hand, the addition of a nonlocal term has a stabilizing effect [4], [18], citeiw-metastable. Even then, two or more hot-spot solutions are found to be unstable - similar phenomenon was discussed in [8] in the context of reaction-diffusion systems. It is an open question as to whether several hot-spot solutions can be stabilized.

The instability of the small eigenvalue typically induce a motion of the hot spot. In the case when $d$ is small, the equations of motion of the spot in 1D was derived in [9]; such motion was shown to be metastable (exponentially slow in $d$ ). Presumably, an extension to two dimensions should be along similar lines. However when $d$ is of $O(1)$, the expression for small eigenvalues is implicit in 1D (see (49)). This complicates the derivation of the equations of motion of the spot.

Another open problem is to extend the modelling and analysis to the three dimensional case. For the exponential nonlinearity, the inner problem leads to the Bratu equation,

$$
U_{r r}+\frac{2}{r} U+\lambda \exp (U)=0, \quad U^{\prime}(0)=0
$$

The hot-spot solutions have the property that $U(0) \rightarrow \infty$ with $\lambda \rightarrow 2$ [10]. This makes it difficult to match the inner and outer solution properly.

Finally, it would be interesting to study the stability and dynamics of a hot spot along the boundary; this is of interest for example if $f(x)$ has no interior maximum, in which case the interior spot is unstable. Presumably, it will then move towards the boundary, and its eventual equilibrium location would depend on the balance between the magnitude of the electric field $f(x)$ and the geometry of the domain.

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