Hot spots in crime model



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UCLA Model of hot-spots in crime

- Originally proposed by Short, D'Orsogna, Pasour, Tita, Brantingham, Bertozzi, and Chayes, 2008 [The UCLA model]
- Crime is ubiquious but not uniformly distributed
 - Some neigbourhoods are worse than others, leading to crime "hot spots"
 - Crime hotspots can persist for long time.



Fig. 1. Dynamic changes in residential burglary hotspots for two consecutive three-month periods beginning June 2001 in Long Beach, CA. These density maps were created using ArcGIS.

Figure taken from Short et.al., A statistical model of criminal behaviour, 2008.

- Crime is temporaly correlated:
 - Criminals often return to the spot of previous crime
 - If a home was broken into in the past, the likelyhood of subsequent breakin increases
 - Example: graffitti "tagging"

Modelling criminal's movement

- In the original model, biased Brownian motion was used to model criminal's movement
- Our goal is to extend this model to incorporate more realistic motion
- Typical human motion consists short periods of fast movement [car trips] interspersed with long periods of slow motion [pacing, thinking about theorems, sleeping...]
- Such motion is often modelled using Levi Flights: At each time, the speed is chosen according to a **power-law distribution**; direction chosen at random: $|y(t + \delta t) y(t)| = \delta t X$ where X is a power-law distribution whose distribution function is

$$f(d) = C \left| d \right|^{-\mu}$$

- μ is the power law exponent
 - In 1D, $1 < \mu \le 3$; in 2D, $1 < \mu \le 4$.
 - $\mu = 3$ corresponds to Brownian motion in one dimension.



• González, Hidalgo, Barabási, *Understanding individual human mobility patterns, Nature 2008,* use cellphone data to suggest that human motion follows "truncated" Levi flight distribution with $\mu \approx 2.75$.

Discrete (cellular automata) model

• Two variables

 $A_k(t) \equiv \text{attractiveness at node } k, \text{ time } t;$ $N_k(t) \equiv \text{criminal density at node } k$

• Modelling attractiveness: Attractiveness has static and dynamic component:

$$A_k(t) \equiv A^0 + B_k(t).$$

$$B_{k}(t + \delta t) = \underbrace{\left[(1 - \hat{\eta}) B_{k}(t) + \frac{\hat{\eta}}{2} (B_{k-1} + B_{k+1}) \right]}_{\text{"broken window effect"}} \underbrace{(1 - w\delta t)}_{\text{decay rate}} + \underbrace{\delta t A_{k} N_{k} \theta}_{\text{decay rate}}.$$

- $0<\hat{\eta}<1$ is the strength of broken window effect
- \boldsymbol{w} is the decay rate

 Modelling criminal movement: Define the *relative weight* of a criminal moving from node *i* to node *k*, where *i* ≠ *k*, as

$$w_{i \to k} = \frac{A_k}{l^{\mu} |i - k|^{\mu}}.$$
 (1)

- l is the grid spacing, μ the Levi flight power law exponent
- The weight is *biased* by attractiveness field
- The *transition probability* of a criminal moving from point *i* to point *k*, where $i \neq k$, is

$$q_{i \to k} = \frac{w_{i \to k}}{\sum_{j \in \mathbb{Z}, j \neq i} w_{i \to j}}.$$
(2)

Update rule for criminal density:

$$N_k(t+\delta t) = \sum_{i\in\mathbb{Z}, i\neq k} N_i \cdot (1-A_i\delta t) \cdot q_{i\to k} + \Gamma \delta t.$$
(3)

- $A_i \delta t \equiv$ probability that criminal robs
- $(1 A_i \delta t) \equiv$ probability that no robbery occurs
- $N_i \cdot (1 A_i \delta t) \equiv$ expected number of criminals at node i that don't rob
- $N_i \cdot (1 A_i \delta t) \cdot q_{i \to k} \equiv$ expected number of criminals that move from mode i to mode k.
- $\Gamma \delta t \equiv {\rm constant}$ "feed rate" of the criminals

Take a limit $l, \delta t \ll 1$:

• Main trick is to write $A_i \sim A(x)$ where x = li; then

$$\sum_{j \in \mathbb{Z}, j \neq i} w_{i \to j} = \sum_{j \in \mathbb{Z}, j \neq i} \frac{A_j}{l^{\mu} |i - j|^{\mu}} = \sum_{j \in \mathbb{Z}, j \neq i} \frac{A_j - A_i}{l^{\mu} |i - j|^{\mu}} + \sum_{j \in \mathbb{Z}, j \neq i} \frac{A_i}{l^{\mu} |i - j|^{\mu}}$$

$$\sim \frac{1}{l} \int_{-\infty}^{\infty} \frac{A(y) - A(x)}{|x - y|^{\mu}} dy + l^{-\mu} 2\zeta(\mu) A(x)$$
(4)

• We recognize the integral as *fractional Laplacian*,

$$\Delta^s f(x) = 2^{2s} \frac{\Gamma\left(s + 1/2\right)}{\pi^{1/2} |\Gamma(-s)|} \int_{-\infty}^{\infty} \frac{f(x) - f(y)}{|x - y|^{2s + 1}} dy, \quad 0 < s \le 1.$$

- Key properties:
 - The normalization constant is chosen so that the Fourier transform is:

$$\mathcal{F}_{x\mapsto q}\left\{\Delta^{s}f(x)\right\} = -|q|^{2s}\mathcal{F}_{x\mapsto q}\left\{f(x)\right\}.$$
(5)

- s = 1 corresponds to the usual Laplacian: $\Delta^s f(x) = f_{xx}$ if s = 1.

Continuum model

The continuum limit of CA model becomes

$$\frac{\partial A}{\partial t} = \eta A_{xx} - A + \alpha + A\rho.$$
(6)

$$\frac{\partial \rho}{\partial t} = D \left[A \Delta^s \left(\frac{\rho}{A} \right) - \frac{\rho}{A} \Delta^s \left(A \right) \right] - A \rho + \beta \tag{7}$$

where

$$s = \frac{\mu - 1}{2} \in (0, 1]; \quad \eta = \frac{l^2 \hat{\eta}}{2\delta t w}; \quad D = \frac{l^{2s}}{\delta t} \frac{\pi^{1/2} 2^{-2s} |\Gamma(-s)|}{z \Gamma(2s+1) w}; \quad \alpha = A_0/w; \quad \beta = \Gamma \theta/w^2.$$

• Separation of scales: if $l, \delta t \ll 1$ then

$$D\eta^{-s} \gg 1; \quad 0 < s \le 1.$$
 (8)

• The special case s = 1 ($\mu = 3$) corresponds to regular diffusion $\Delta^1 f(x) = f_{xx}$.

- We recover the UCLA model because:

$$A\left(\frac{\rho}{A}\right)_{xx} - \frac{\rho}{A}A_{xx} = \left(\rho_x - 2\frac{\rho}{A}A_x\right)_x$$

- Note that $D \to \infty$ as $s \to 1^-$ since $|\Gamma\left(-s\right)| \sim 1/(1-s).$

Simulation of continuum model

- Use a spectral method in space combined with method of lines in time.
- That is, we first discretize in space $x \in [0, L]$. To approximate $\Delta^s u$, we make use of Fourier transform:

$$\Delta^{s} u = \mathcal{F}^{-1} \left(-|q|^{2s} \mathcal{F}_{x \mapsto q} \{u\} \right).$$
(9)

- This becomes FFT on a bounded interval
- Matlab code to estimate the discretization of ∆^su(x), x ∈ [0,1]:
 n = numel(u);
 q = 2*pi*[0:n/2-1, -n/2:-1]';
 LaplaceS_u = ifft(-q.^(2*s).*fft(u));
- This implicitly imposes periodic boundary conditions on the solution.

Comparison: discrete vs. continuum

Example: Take $\mu = 2.5$, n = 60, l = 1/60, $\hat{\eta} = 0.1$, $\delta t = 0.01$, $A_0 = 1$, $\Gamma = 3$.

Then the continuum model gives $s = 0.75, \eta = 0.001388, D = 0.1828, \alpha = 1, \beta = 3.$



Discrete model is represented by dots; continuum model by solid curves. Blue is A, red is ρ . Two hot-spots form.

Turing instability analysis

$$\frac{\partial A}{\partial t} = \eta A_{xx} - A + \alpha + A\rho, \qquad \frac{\partial \rho}{\partial t} = D \left[A \Delta^s \left(\frac{\rho}{A} \right) - \frac{\rho}{A} \Delta^s \left(A \right) \right] - A\rho + \beta$$

Steady state:

$$\bar{A} = \alpha + \beta; \quad \bar{\rho} = \frac{\beta}{\alpha + \beta}$$

Linearization:

$$\begin{split} A(x,t) &= \overline{A} + \phi e^{\lambda t} e^{ikx}, \qquad \qquad \mbox{(10a)} \\ \rho(x,t) &= \overline{\rho} + \psi e^{\lambda t} e^{ikx}. \qquad \qquad \mbox{(10b)} \end{split}$$

Using the Fourier transform property, we have:

$$\Delta^s e^{ikx} = -|k|^{2s} e^{ikx}$$

so the eigenvalue problem becomes

$$\begin{bmatrix} -\eta |k|^2 - 1 + \bar{\rho} & \bar{A} \\ \frac{2\bar{\rho}}{\bar{A}}D|k|^{2s} - \bar{\rho} & -D|k|^{2s} - \bar{A} \end{bmatrix} \begin{bmatrix} \phi \\ \psi \end{bmatrix} = \lambda \begin{bmatrix} \phi \\ \psi \end{bmatrix}.$$
 (11)

The dispersion relationsh is then given by

$$\lambda^2 - \tau \lambda + \delta = 0$$

where

$$\tau = -D|k|^{2s} - \eta|k|^2 - \bar{A} - 1 + \bar{\rho}; \qquad \delta = D|k|^{2s} \left(\eta |k|^2 + 1 - 3\bar{\rho}\right) + \eta |k|^2 \bar{A} + \bar{A}.$$

Note that $\tau < 0$ so the steady state is stable iff $\delta > 0$ for all k. Equilibrium is stable if $\bar{\rho} < 1/3$. If $\bar{\rho} > 1/3$ then equilibrium is unstable iff

$$\bar{A} < D\eta^s x^s \left(-1 + \frac{3\bar{\rho}}{x+1} \right) \tag{12}$$

where x is the unique positive root of

$$x^{2} + x\left(2 + 3\bar{\rho}(1-s)/s\right) + 1 - 3\bar{\rho} = 0.$$

Comparison with numerics



The effect of changing s on dispersion relationship



Dominant instability [biggest λ]

• Recall that in terms of original gridsize l and time step δt , we have:

$$s = \frac{\mu - 1}{2} \in (0, 1]; \quad \eta = \frac{l^2 \hat{\eta}}{2\delta t w}; \quad D = \frac{l^{2s}}{\delta t} \frac{\pi^{1/2} 2^{-2s} |\Gamma(-s)|}{z \Gamma(2s+1) w}$$

so that $\eta^{-s} D = O((1-s)^{-1} (\delta t)^{s-1}) \gg 1, \quad 0 < s \le 1$

• For a physically relevant regime, the continuum model satisfies the key relationship

$$\eta^{-s}D \gg 1. \tag{13}$$

Change the variables $k = x^{1/2} \eta^{-1/2}$ and let $M = D\eta^{-s} \gg 1$. Then we obtain

$$\tau = -Mx^s - x^2 + \bar{\rho} - 1 - \bar{A}; \ \delta = Mx^s(x + 1 - 3\bar{\rho}) + x\bar{A} + \bar{A}$$

The fastest growing mode corresponds to the maximum of the dispersion curve:

$$\lambda^2 - \tau \lambda + \delta = 0$$
 and $\lambda = \tau_x / \delta_x$.

• Asymptotically, this becomes

$$k_{\text{fastest}}(s) \sim \left[\frac{s\bar{\rho}(-2+3\bar{A}+6\bar{\rho})}{D\eta}\right]^{\frac{1}{2(s+1)}}, \quad D\eta^{-s} \gg 1.$$
(14)
Expected number of "bumps" $\approx \text{floor}\left(\frac{L}{2\pi}k_{\text{fastest}}\right).$ (15)

• k_{fastest} is at a maximum when s satisfies

$$\log\left(\frac{\bar{\rho}(-2+3\bar{A}+6\bar{\rho})}{D\eta}s\right) = s+1$$

Comparison with numerics

$$l = 0.01, \delta t = 0.05, \hat{\eta} = 0.02, A_0 = 1, \Gamma = 3$$



• The initial instability has sinusoidal shape

- Eventually, hot-spot forms.
 - Hot-spots are localized regions which are *not* of the sinusoidal shape!
 - In general, the total number of stable hot-spots *does not* correspond to fastest-growing Turing mode!
 - The hot-spot regime is separate from the Turing regime!



FIGURE 7. Numerically computed bifurcation diagram of A(0) vs. γ . The parameter values are $\alpha = 1, \varepsilon = 0.05, x \in [0, 1]$, and D = 2. A localized hot-spot appears for large values of A(0). The asymptotics $A(0) \sim \frac{2(\gamma - \alpha)}{\varepsilon \pi}$ (see (2.19)) are shown by a dotted line. The constant steady state $A \sim \gamma$ is indicated by a solid straight line line. Turing patterns are born from the spatially uniform steady state as a result of a Turing bifurcation at $\gamma \sim 3\alpha/2 = 1.5$. The weakly nonlinear regime is indicated by a dashed parabola coming out of the bifurcation point. Inserts shows the change in the shape of the profile A(x) along the bifurcation curve.

Construction of hotspot solution

Hotspot solution satisfies:

$$0 = \eta A_{xx} - A + \alpha + A\rho; \quad 0 = D \left[A \Delta^s \left(\frac{\rho}{A} \right) - \frac{\rho}{A} \Delta^s (A) \right] - A\rho + \beta$$
(16)
and is periodic on $[-1, 1].$

• Key transformation: Let $\rho = vA^2$; then

$$0 = \eta A_{xx} - A + \alpha + A^{3}v; \quad 0 = D \left[A\Delta^{s} \left(vA \right) - vA\Delta^{s} \left(A \right) \right] - A^{3}v + \beta \quad (17)$$

• Inner problem: Change variables $x = \eta^{1/2}y$; then

$$0 = A_{yy} - A + \alpha + A^{3}v; \quad 0 = D\eta^{-s} \left[A\Delta^{s} \left(vA \right) - vA\Delta^{s} \left(A \right) \right] - A^{3}v + \beta$$

 \bullet As before, $D\eta^{-s}\gg 1$ so that in the inner region,

$$A\Delta_y^s(vA) - vA\Delta_y^s(A) \sim 0 \implies v(y) \sim \text{const.} \sim v_0$$

- Change variables ${\boldsymbol A}=\boldsymbol{v}_0^{-1/2}\boldsymbol{w}(\boldsymbol{y}),$ then

$$w_{yy} - w + w^3 = 0 \qquad \Longrightarrow \qquad w = \sqrt{2} \operatorname{sech}(y)$$

- To determine v_0 , integrate (17) and use the identity $\int f \Delta^s g - g \Delta^s f = 0$; then

$$\int A^3 v_0 \sim \int \beta$$

• The final result is

$$A(x) \sim \begin{cases} A_{\max} w(x/\sqrt{\eta}), & x = O(\varepsilon) \\ \alpha, & x \gg O(\varepsilon). \end{cases}$$
$$A_{\max} \sim \frac{2l\beta\pi^{-3/2}}{\sqrt{\eta}}$$

where l is the half-width of the spot.



Stability of hot-spots (1D, s = 1)

• Localized states: Consider a periodic pattern consisting of *localized* hotspots of radius l. It is stable iff $l > l_c$ where

$$l_c := \frac{(\eta D)^{1/4} \pi^{1/2} \alpha^{1/2}}{\beta^{3/4}}$$

- Turing instability in the limit $\varepsilon \to 0$:
 - Preferred Turing characteristic length:

$$l_{\rm turing} \sim 2\pi \left[\frac{D\eta}{\bar{\rho}(-2+3\bar{A}+6\bar{\rho})} \right]^{1/4}, \quad D\eta^{-1} \gg 1$$

• Note that both $O(l_c) = O(l_{turing}) = O((D\eta)^{1/4})!$

Example: $\alpha = 1, \ \gamma = 2, \ D = 1, \ \varepsilon = 0.03.$



Small and large eigenvalues

- Near-translational invariance leads to "small eigenvalues (perturbation from zero)" corresponding eigenfunction is $\phi \sim w'$.
- Large eigenvalues are responsible for "competition instability".
- Small eigenvalues become unstable before the large eigenvalues.
- Example: Take $l = 1, \gamma = 2, \alpha = 1, K = 2, \varepsilon = 0.07$. Then $D_{c,\text{small}} = 20.67, D_{c,\text{large}} = 41.33$.
 - if $D = 15 \implies$ two spikes are stable
 - if $D = 30 \implies$ two spikes have very slow developing instability
 - if $D = 50 \implies$ two spikes have very fast developing instability



Stability: large eigenvalues

• Step 1: Reduces to the nonlocal eigenvalue problem (NLEP):

$$\lambda\phi = \phi'' - \phi + 3w^2\phi - \chi\left(\int w^2\phi\right)w^3 \quad \text{where } w'' - w + w^3 = 0.$$
 (18)

with

$$\chi \sim \frac{3}{\int_{-\infty}^{\infty} w^3 dy} \left(1 + \varepsilon^2 D (1 - \cos \frac{\pi k}{K}) \frac{\alpha^2 \pi^2}{4l^4 \beta^3} \right)^{-1}$$

• Step 2: *Key identity*: $L_0w^2 = 3w^2$, where $L_0\phi := \phi'' - \phi + 3w^2\phi$. Multiply (18) by w^2 and integrate to get

$$\lambda = 3 - \chi \int w^5 = 3 - \chi \frac{3}{2} \int w^3$$

Conclusion: (18) is stable iff $\chi > \frac{2}{\int w^3} \iff D > D_{c,\text{large}}$.

• This NLEP in 1D can be fully solved!!

Stability: small eigenvalues

- Compute asymmetric spikes
- They bifurcate from symmetric branch
- The bifurcation point is precisely when $D = D_{c,small}$.
- This is "cheating"... but it gets the correct threshold!!

Stability of \boldsymbol{K} spikes

• Possible boundary conditions:

Config type	Boundary conditions for ϕ
Single interior spike on $\left[-l,l ight]$	$\phi'(0) = 0 = \phi'(1)$
even eigenvalue	$\varphi\left(0\right) = 0 = \varphi\left(l\right)$
Single interior spike on $\left[-l,l ight]$	$\phi(0) = 0 = \phi'(l)$
odd eigenvalue	
Two half-spikes at $[0, l]$	$\phi'(0) = 0 = \phi(l)$
K spikes on $[-l, (2K-1)l]$,	$\phi(l) = z\phi(-l), \qquad \phi'(l) = z\phi'(-l),$
Periodic BC	$z = \exp\left(2\pi i k/K\right), \ k = 0\dots K - 1$
K spikes on $[-l, (2K-1)l],$	$\phi(l) = z\phi(-l), \qquad \phi'(l) = z\phi'(-l),$
Neumann BC	$z = \exp\left(\pi i k / K\right), \ k = 0 \dots K - 1$

(same BC for $\psi)$

Two dimensions

Given domain of size S, let

$$K_c := 0.07037 \eta^{-3/8} D^{-1/3} \left(\ln \frac{1}{\sqrt{\eta}} \right)^{1/3} \beta \alpha^{-2/3} S.$$
⁽¹⁹⁾

Then K spikes are stable if $K < K_c$. Example: $\alpha = 1$, $\gamma = 2$, $\varepsilon = 0.08$, D = 1.



We get S = 16, $K_c \approx 10.19$. Starting with random initial conditions, the end state constits of $K = 7.5 < K_c$ hot-spots [counting boundary spots with weight 1/2 and corner spots with weight 1/4], in agreement with the theory.

Discussion

- Natural Separation of scales: $\eta^{-s}D \gg 1$
 - comes from the modelling assumptions
 - Required for hot-spot construction
 - The steady states are localized hotspots in the form of a sech, not sinusoidal bumps!
- Open question:
 - extend stability of hot-spots to Levi flights
 - More general moels of human motion?
- There is an optimal Levi flight exponent $1 < \mu < 3$ which "maximizes" the number of hot-spots. Do criminals "optimize" their strategy with respect to μ ?
- References:
 - J. Breslau, T. Chaturapruek, D. Yazdi, S. McCalla and T. Kolokolnikov, *Incorporating Levi flights into a model of crime,* in preparation
 - T. Kolokolnikov, M. Ward and J. Wei, *The Stability of Steady-State Hot-Spot Patterns for a Reaction-Diffusion Model of Urban Crime,* to appear, DCDS-B.