# Stripe patterns for GM model in thin domains



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#### **Motivation**



Cnjunctival placodes within the embryonic eye of birds [Duench, Franz-Odendaal 2012; Drake-Jourdeuil-Franz-Odendaal 2024, Franz-Odendaal 2008]. These placodes are transient structures that induce underlying bones within the sclera of the eye. Comparative morphological studies by Franz-Odendaal and coworkers show that there is a specific conserved and universal sequence to the appearance of the placodes; experimental evidence to-date points to a Turing mechanism of pattern formation.

#### Thin domains:

GM model:

$$a_t = \varepsilon^2 \Delta a - a + a^p / h^q, \tag{1}$$

$$0 = d^2 \Delta h - h + \frac{1}{\varepsilon} a^m / h^s \tag{2}$$

Standard "quasi-1D" reduction:

$$\Delta \to \partial_{xx} + \frac{A'(x)}{A(x)} \partial_x.$$
 (3)

GM model becomes:

$$a_t = \varepsilon^2 \left( a_{xx} + \alpha(x)a_x \right) - a + a^p / h^q, \tag{4}$$

$$0 = d^2 \left( h_{xx} + \alpha(x)h_x \right) - h + \frac{1}{\varepsilon} a^m / h^s$$
(5)

where  $\alpha = A'/A$ , A is the cross-sectional area, x denotes the arclength coordinate along the boundary of the channel,  $\varepsilon$  is small.

#### **Example:**

Consider area between two circles. Outer circle is unit disk; inner circle off-center such that minimum and maximum distance from the outer boundary is  $d_{\min}$  and  $d_{\max}$ , respectively, with  $d_{\min} \leq d_{\max} \leq O(\varepsilon) \ll 1$ . Then

$$\alpha(x) \sim \frac{1}{2} \frac{-(\kappa^2 - 1)\sin x}{1 + \kappa^2 + (\kappa^2 - 1)\cos x}; \quad \kappa = d_{\max}/d_{\min}$$
(6)

For concreteness we will take  $\kappa = 3, \ p = 2, \ m = 2, s = 0$ . Examples of equilibria:



p=2, m=2, s=0, with q as shown

#### **Reduced system**

In the limit  $\varepsilon \ll d$ , a quasi-equilibrium solution to (4) consisting of N stripes has the form

$$a(x,t) \sim \sum V_j^{q/(p-1)} w\left(\frac{x - x_j(\varepsilon^2 t)}{\varepsilon}\right),\tag{7}$$

$$H(x,t) \sim b_m \sum_j V_j^{\gamma} G\left(x, x_j\right) \tag{8}$$

where w(y) is a standard ground state solution,

$$w_{yy} - w + w^p = 0; \quad w'(0) = 0; \quad w(y) \to 0 \text{ as } y \to \pm \infty,$$
 (9)

$$b_m = \int_{-\infty}^{\infty} w^m(y) dy,$$
(10)

 $G(\boldsymbol{x},\boldsymbol{\xi})$  is the Green's function satisfying

$$d^2 \left( G_{xx} + \alpha(x) G_x \right) - G = -\delta(x - \xi), \tag{11}$$

and  $x_j(t\varepsilon^2)$  is the time-dependent location of *j*-th stripe which is coupled to weights  $V_j$  and solves the following differential-algebraic system:

$$x'_{k} = -\alpha(x_{k}) - 2b_{m} \frac{q}{p-1} \frac{1}{V_{k}} \sum_{j} V_{j}^{\gamma} G_{x}(x_{k}, x_{j})$$
(12)

$$V_k = b_m \sum_j V_j^{\gamma} G(x_k, x_j); \tag{13}$$

$$\gamma = \frac{qm}{p-1} - s; \tag{14}$$

where  $G_x(x_k, x_k) = \frac{1}{2} \left( G_x(x_k^+, x_k) + G_x(x_k^-, x_k) \right).$ 

#### Green's function WKB theory in the limit $d \ll 1$

$$d^{2}(G_{xx} + a(x)G_{x}) - G = -\delta(x - \xi); \quad d \ll 1.$$

We use the standard WKB ansatz:

$$G \sim Y(x)e^{\frac{\phi(x)}{d}}$$

to obtain

$$\phi'^2 = 1; \ \frac{1}{Y} \left( Y^2 \phi' \right)' + Y \phi' \beta = 0.$$

Since we require decay at infinity, we take  $\phi' = - \operatorname{sign} (x - \xi)$  and equation for Y yields

$$Y = C \exp\left(-\frac{1}{2}\int_{\xi}^{x} \alpha(s) \, ds\right).$$

Applying the jump condition  $d^2G_x|_{\xi^-}^{\xi^+} = -1$ ; then yields

$$G(x,\xi) \sim \frac{1}{2d} \exp\left(-\frac{1}{2} \int_{\xi}^{x} \alpha(s) \, ds\right) \exp\left(-\frac{|x-\xi|}{d}\right)$$

In particular we have:

$$G(\xi,\xi) \sim \frac{1}{2d}$$
(15)  
$$\frac{G_x(\xi^+,\xi) + G_x(\xi^-,\xi)}{2} \sim -\frac{\alpha(\xi)}{4d};$$
(16)

### Single spike

$$x_0' = -\alpha(x_0) - 2\frac{q}{p-1} \frac{G_x(x_0, x_0)}{G(x_0, x_0)}.$$
(17)

• Large *d* limit ("shadow system"):

$$x'_0 \sim -\alpha(x_0), \quad d \gg 1.$$
 (18)

- Equilibrium location  $x_0$  then correspond to zeros of  $\alpha(x) = A'(x)/A(x)$ , with *stable equilibrium corresponding to the minimum* of cross-sectional area A(x).
- Small d : Using WKB for Green's function we obtain

$$x'_0 \sim \left(-1 + \frac{q}{p-1}\right) \alpha(x_0), \quad d \ll 1.$$
(19)

- Equilibria still at zero of  $\alpha(x) = A'(x)/A(x)$ , but their stability can *switch* depending on the sign of q + 1 p: if p > q + 1, stable equilibria correspond to the minimum of A, and unstable to the maximum of A; this is reversed when p < q + 1.
- **Borderline case**: q = p 1. This includes the "standard choice" p = 2, q = 1. Then  $x' \sim 0$  up to  $O(\varepsilon^2)$ . Higher-order expansion would be needed to capture the motion.



Figure 1: Stable equilibrium solutions of the full 2D system (??) consisting of a single spike inside an annular region of uneven thickness. The outer boundary is a unit circle. The inner boundary is a circle which is at a minimum distance of 0.05 and a maximum distance of 0.15 from the outer boundary. Full 2D time-dependent problem was solved using an initial condition consisting of a single spike at  $x = \pi/2$ . Snapshots show the solution after it converged to a (stable) equilibrium. Parameters d and q are as shown, while other parameters are  $\varepsilon = 0.1$ , p, m, s = 2, 2, 0. Note that the spike is expected to be stable at the thinnest part of the domain when d is large, regardless of q. When d is small, the spike is stable at the thinnest part if q , but is stable at the thickest part

#### **Two spikes**

• Two symmetric stripes:  $x_1 = r$ ,  $x_2 = -r$  :

$$r' \sim -\alpha(r) - 2\frac{q}{p-1}\frac{G_x(r,r) + G_x(r,-r)}{G(r,r) + G(r,-r)}.$$

Assume that  $\varepsilon \ll r \ll 1,$  WKB yields

$$r' \sim \frac{\frac{2q}{p-1}\frac{1}{d}\exp\left(-\frac{2r}{d}\right)}{1+\exp\left(-\frac{2r}{d}\right)} + \alpha\left(r\right)\left(-1+\frac{q}{p-1}\right).$$
(20)

**Boundary case:** if q = p - 1, then  $r \to \infty$  regardless of  $\alpha$ ; no "cluster"

Otherwise, Expand near  $r \sim 0$ , we get

$$r' \sim \frac{\frac{2q}{p-1}\frac{1}{d}\exp\left(-\frac{2r}{d}\right)}{1+\exp\left(-\frac{2r}{d}\right)} + r\alpha'(0)\left(-1+\frac{q}{p-1}\right).$$
(21)

More generally,

Suppose that  $\alpha(x)$  has a root at  $x = x_0$  and suppose that  $\alpha'(x_0)(q-p-1) < 0$ . Then there is a two-spike steady state with spike positions at  $x \sim x_0 \pm r$ , where  $r = O(d \log d^{-1})$  asymptotes to the small solution of

$$e^{2r/d} \sim \frac{1}{r} \frac{1}{d} \frac{2q}{\alpha'(x_0) (p-1-q)}.$$
 (22)

No such solution exists if q=p-1 or  $\alpha'(x_0)\left(q-p-1\right)>0$ 



Figure 2: Two spikes inside an annular region of uneven thickness. The outer boundary is a unit circle. The inner boundary is the circle through points -1 + 0.05, 1 - 0.15 (i.e.  $\kappa = 3$  in (??)). The first column shows the equilibrium state for the full 2D system (??). Second column shows the corresponding equilibrium in the 1D system (4), approximating the solution along the boundary of the domain. (a-c) Parameter values are

# **Many stripes**

- We derive the effective spike density using methods from [Kolokolnkov, Xie, 2020]
- Idea: in the limit *d* small, the Green's function interaction is exponentially weak. So each spike only feels a local neigbourhood of spikes.
- Sort spike positions in increasing order,  $x_1 < x_2 < \ldots < x_N$ . Assume typical interspike distance of O(d). Define u(x) such that  $x_{j+1} x_j \approx u(x_j)d$ . Expand in Taylor series. End-result: for equilibrium cluster,

$$u_x = \alpha(x) \frac{\left(\left(\frac{p-1}{q} - 1\right)\frac{\sinh u}{u} + 1\right)\sinh(u)}{\cosh(u) - \frac{\gamma+1}{\gamma-1}}, \quad \gamma = \frac{qm}{p-1} - s.$$
(23)

This is a separable ODE and determines the effective inter-spike distance ud in the limit of large N.

- The density distribution is given by  $\rho(x)=1/u(x),$  where u(x) satisfies (23) subject to an integral constraint

$$\int_{D} \rho(x) dx = Nd.$$
(24)

where D = (a, b) is the support of  $\rho(x)$  (i.e. u blows up x = a, b).

• Note that (23) has a singularity when  $\cosh(u) = \frac{\gamma+1}{\gamma-1}$ . Competition instability occurs u is below this threshold [K-X 2020]. Let

$$u_c := \operatorname{arccosh}\left(\frac{\gamma+1}{\gamma-1}\right), \quad \rho_c := 1/u_c.$$
 (25)

This critical threshold agrees with known results about competition instability [Iron-Ward-Wei, 2001]. In particular, the inter-spike distance must be larger than  $u_c d$ .

- We call the density  $\rho(x) = 1/u(x)$  "*admissible*" if  $\rho(x) \leq \rho_c$  for all x, where  $\rho_c$  is given by (25). We call  $\rho(x)$  *maximal admissible density*, denoted it by  $\rho_{\max}(x)$ , if  $\rho_{\max}(x) \geq \rho(x)$  for any admissible density  $\rho(x)$ .
- Typically, Turing instability results in more spikes than  $\rho_{\rm max}$  can support due to large unstable band ( $\varepsilon \ll d$ ). Therefore it is followed by coarsening process until  $\rho \sim \rho_{\rm max}$  (at the steady state)



Figure 3: (a-c): Solutions of ODE (23) for the density  $\rho(x) = 1/u(x)$  corresponding to different admissable initial conditions (for which  $\rho(x) < \rho_c$ ) with q as indicated, and with  $\alpha(x)$  as in (??) and p = 2, m = 2, s = 0. (d) Plot of  $\rho_{\max}(x)$  as a function of q, other parameters are as in (a-c). (e)  $N_{\max}d$  and cluster size  $R_{\max}$  as a function of q, see text.









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Figure 5: Simulations of (??) starting with random initial conditions, with  $\varepsilon = 0.018$ , p = q = m = 2, s = 0 and with slowly decreasing d according to  $d = 0.447 + 10^{-7}(0.153 - 0.447)t$ ,  $t = 0 \dots 10^7$ . Snapshots show direct comparison with continuum density for d as indicated as well as the corresponding steady state. Note that the spike distribution is uniform when d = 0.361 (see text); and a cluster starts to form around d = 0.221, in full agreement with the theory.



Figure 6: Simulations of (??) starting with random initial conditions, with  $\alpha(x)$  as in (??),  $\varepsilon = 0.03$ , p = q = m = 2, s = 0 and with slowly increasing d according to  $d = 0.16 + (3 - 0.0.16)10^{-6}t$ ,  $t = 0 \dots 10^{6}$ . Left: Full solution to the PDE. Right: N, number of spikes, as a function of d: comparison between the full PDE and the continuum theory (see text)

## **Discussion**

- We have described stripe evolution and their equilibrium distributions on thin channels for the GM model.
- We found clusters can concentrate either near *thinnest* or *thickest* part of the channel, depending on parameters. This is in contrast to interface-minimizing systems such as Allen-Cahn, where the dynamics push the interface to minimize its length and therefore be located at the *thinnest* part of the channel [Kohn-Sternberg,1989; Chen, 1992; Iron-Kolokolnkov-Rumsay-Wei, 2009].
- When the domain is too thick ( $\geq O(\varepsilon)$ ), stripes break up into spots [Doelman and van der Ploeg, 2002]. *Open question:* analyse motion of *spots* (rather than stripes) inside a thin channel. Study co-existing patterns as in the picture.
- Reference: Leila Mohammadi, Theodore Kolokolnikov, David Iron, and Tamara A. Franz-Odendaal, "Stripe patterns for Gierer-Meinhard model in thin domains", to appear, Physica D.



Figure 7: Coexistence of stripes and spikes. Full simulation of (??) inside a channel whose outer boundary is a unit circle and whose inner boundary is a smaller circle with  $d_1$  and  $d_2$  is the minimum and maximum thickness of the channel. Parameters are (p, a, m, s) = (2, 0.75, 2, 0) with other parameters as indicated. First row: for  $\varepsilon = 0.1$